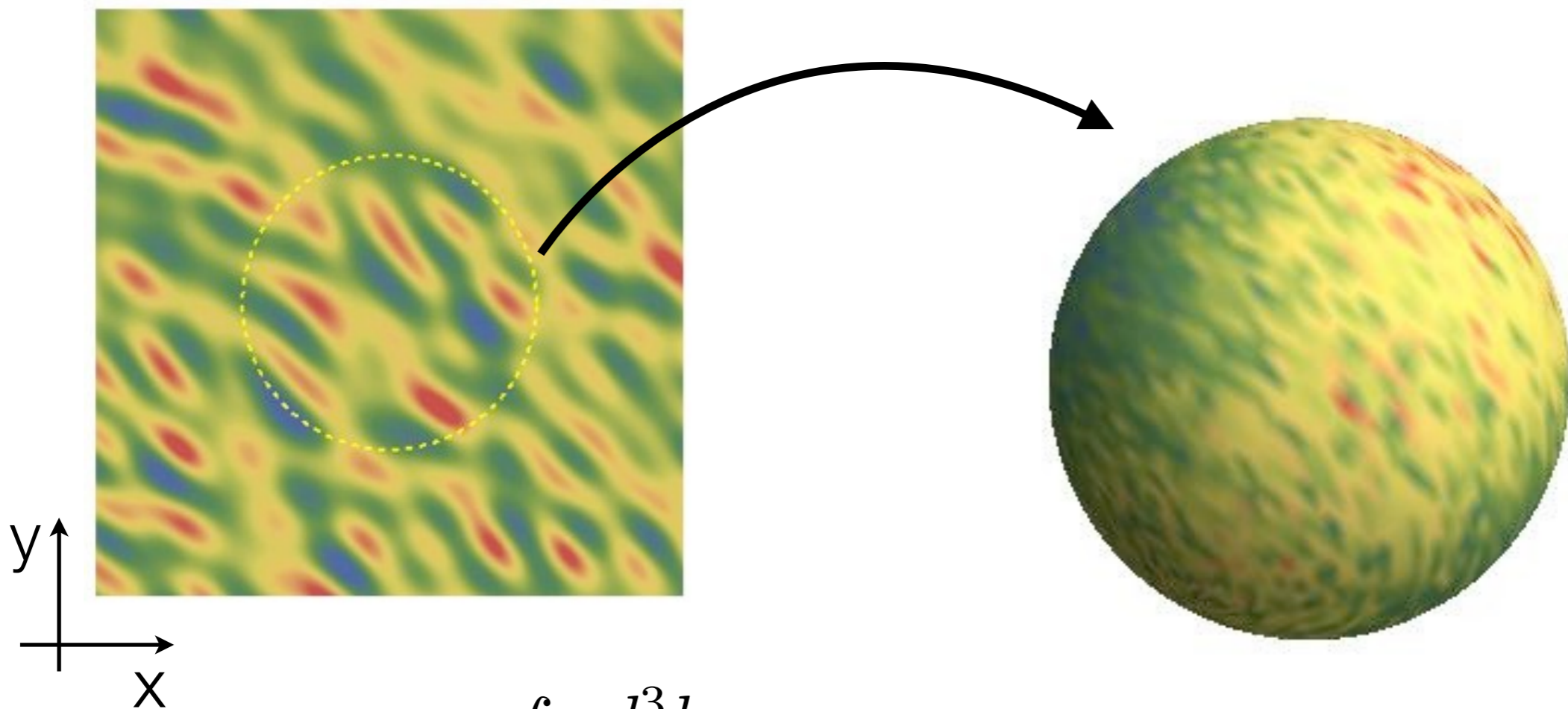


Observing the Universe(s)

Matt Johnson
Perimeter Institute/York University

The CMB

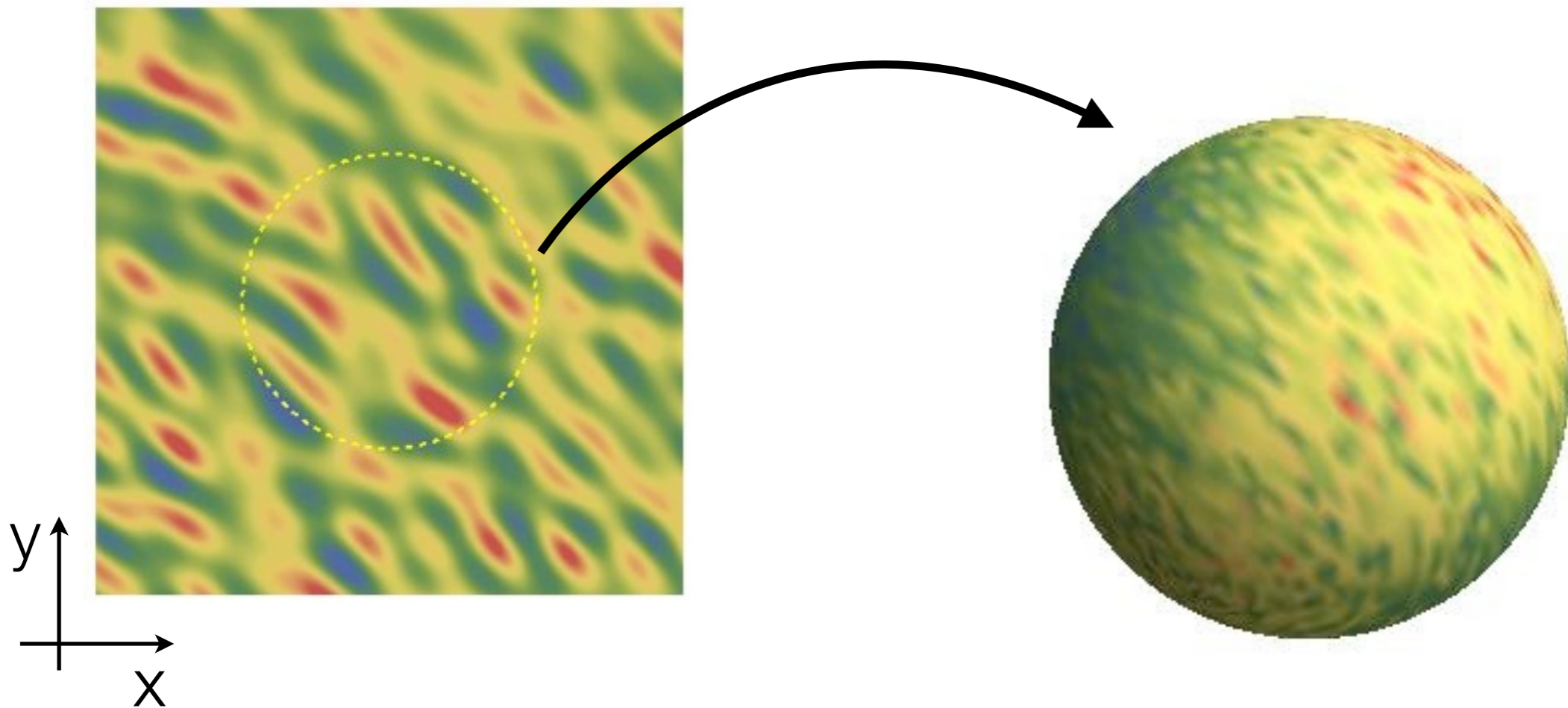
- The CMB is a 2D projection of a 3D field.



$$a_{\ell m} = \int \frac{d^3 k}{(2\pi)^3} \Delta_{\ell}(k) \Phi_{\text{init}}(k) Y_{\ell m}(\hat{k})$$

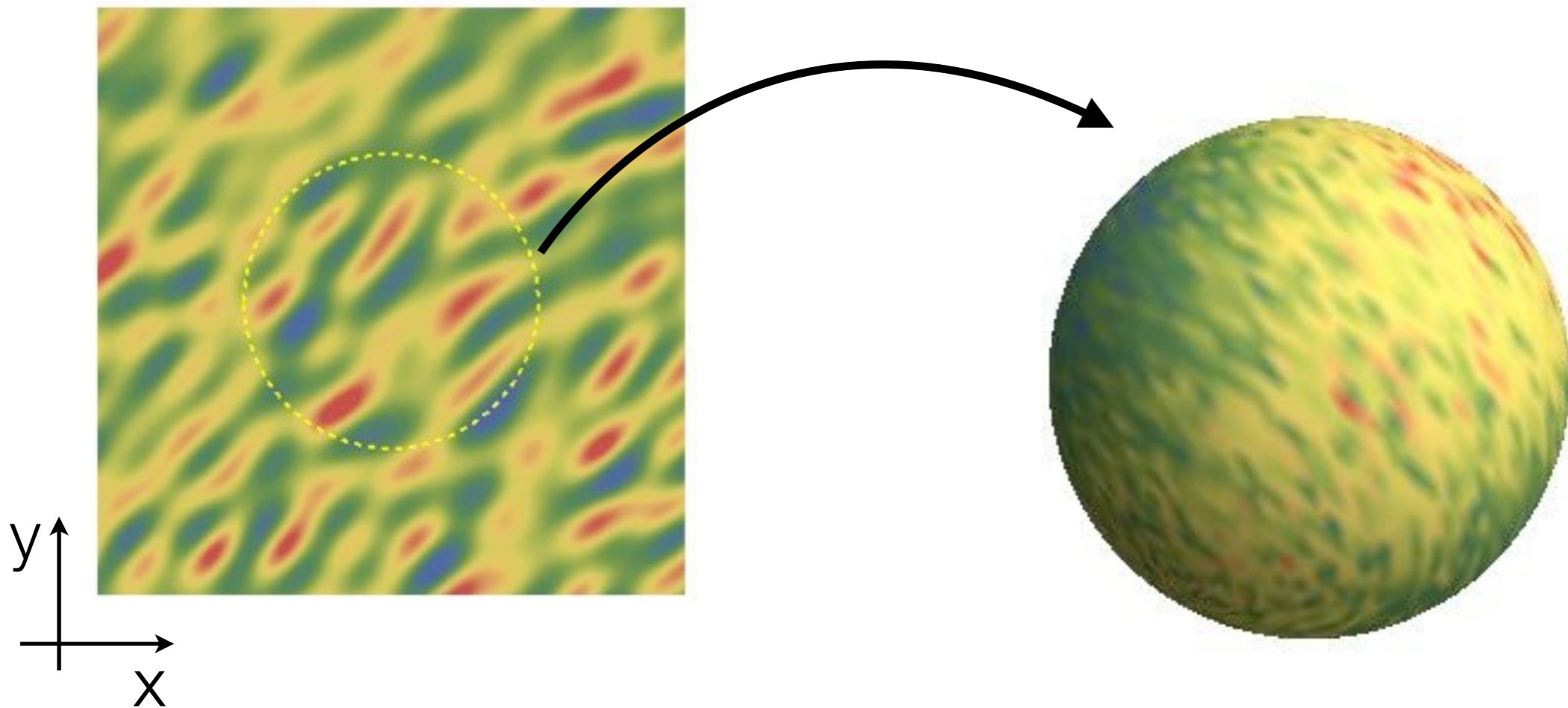
The CMB

- Different realizations of the random field can give the same CMB.



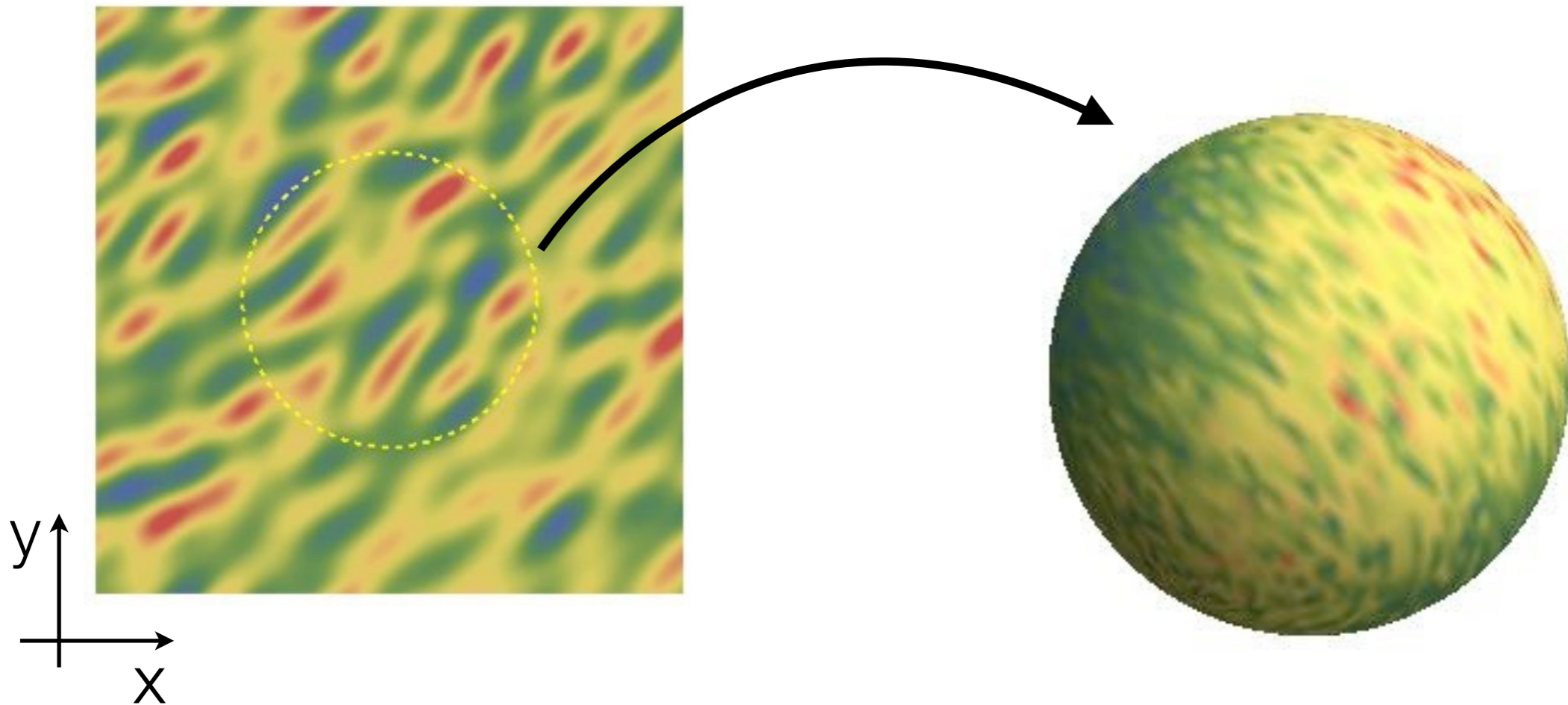
The CMB

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The CMB

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Cosmic Variance

- Measuring the power spectrum in a perfect world:



$$C_\ell = \frac{1}{2\ell + 1} \sum_{m=-\ell}^{\ell} a_{\ell m} a_{\ell m}^*$$

$$\frac{\Delta C_\ell}{C_\ell} = \sqrt{\frac{1}{2\ell + 1}}$$

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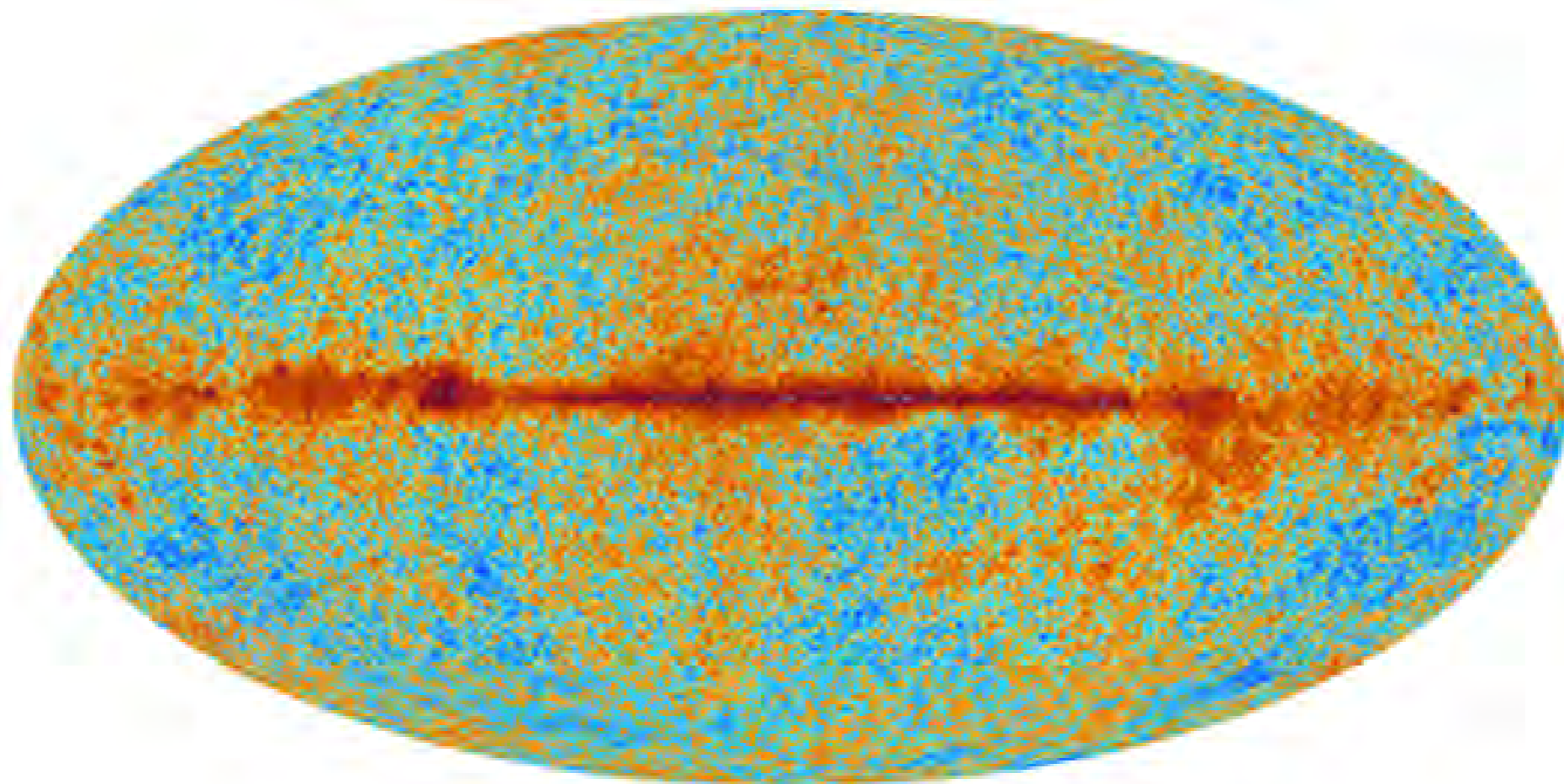
$$\frac{\Delta C_\ell}{C_\ell} = \sqrt{\frac{1}{2\ell + 1}}$$

- There are a finite number of data points *in principle*.

Cosmic Variance

Cosmic Variance

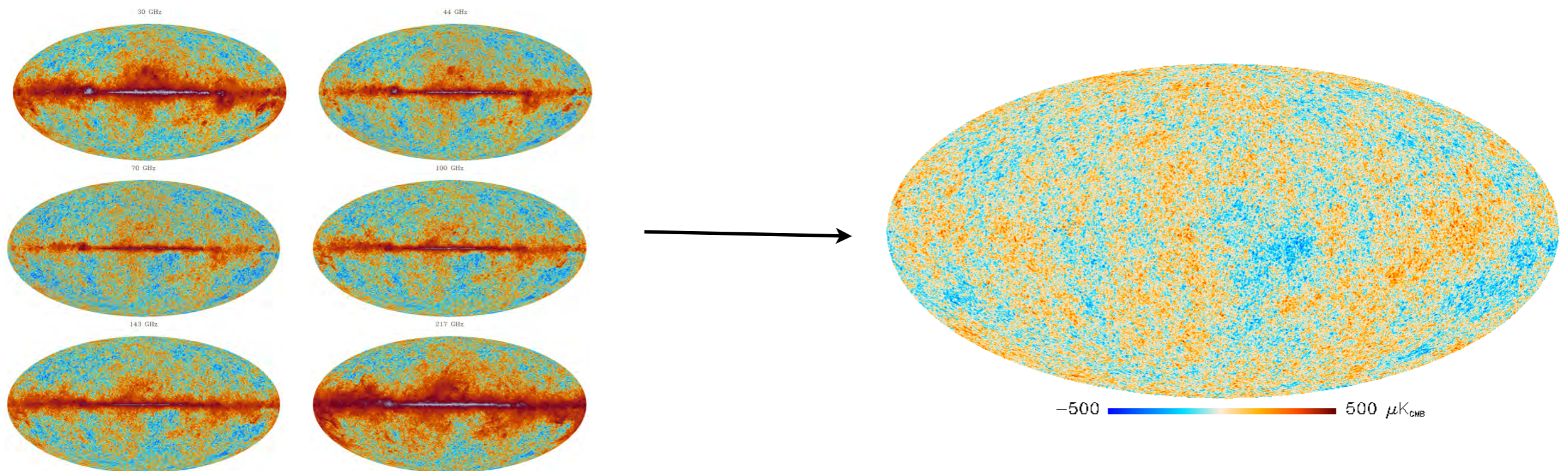
- Measuring the power spectrum in our world: foregrounds.



143 GHz

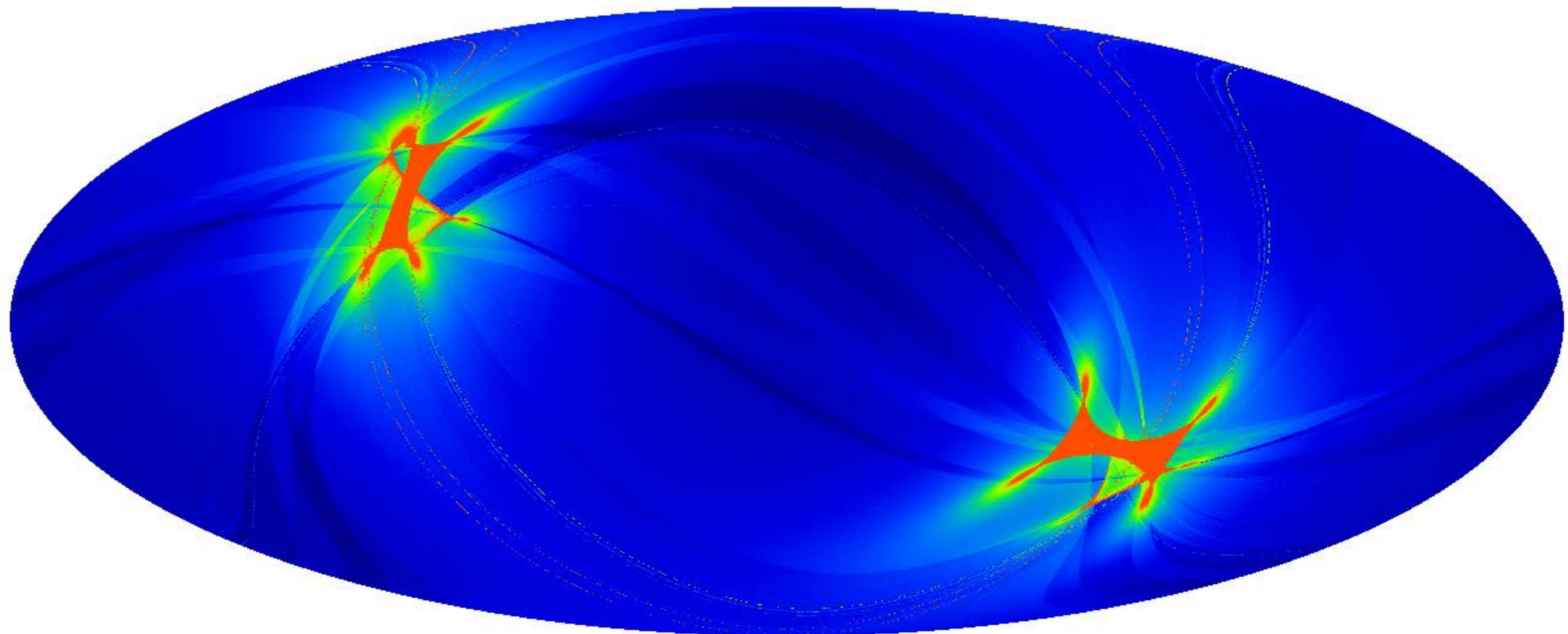
Cosmic Variance

- Measuring the power spectrum in our world: foregrounds.
- Astrophysical sources vary significantly with frequency, the CMB does not -- can use maps from different frequencies.

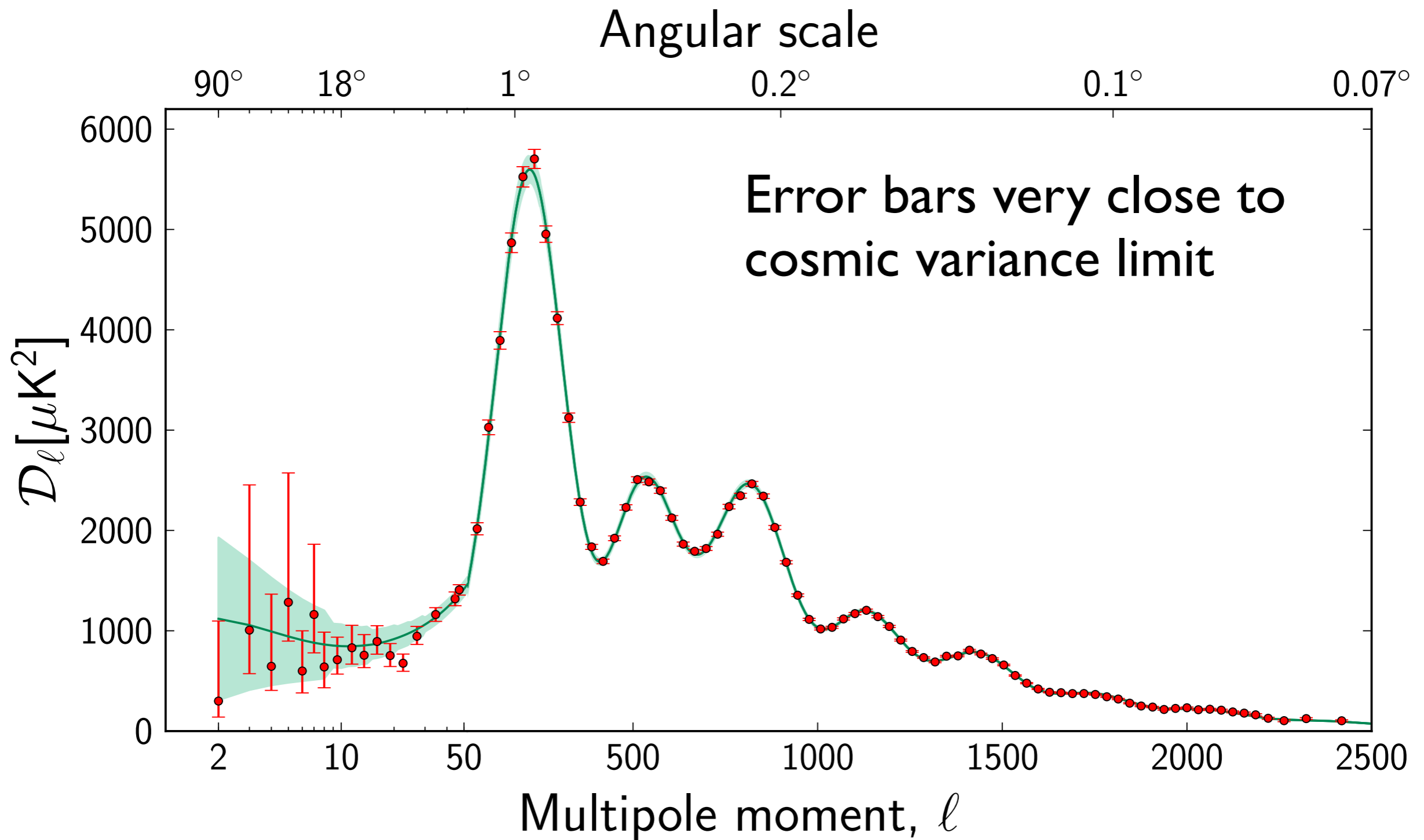


Cosmic Variance

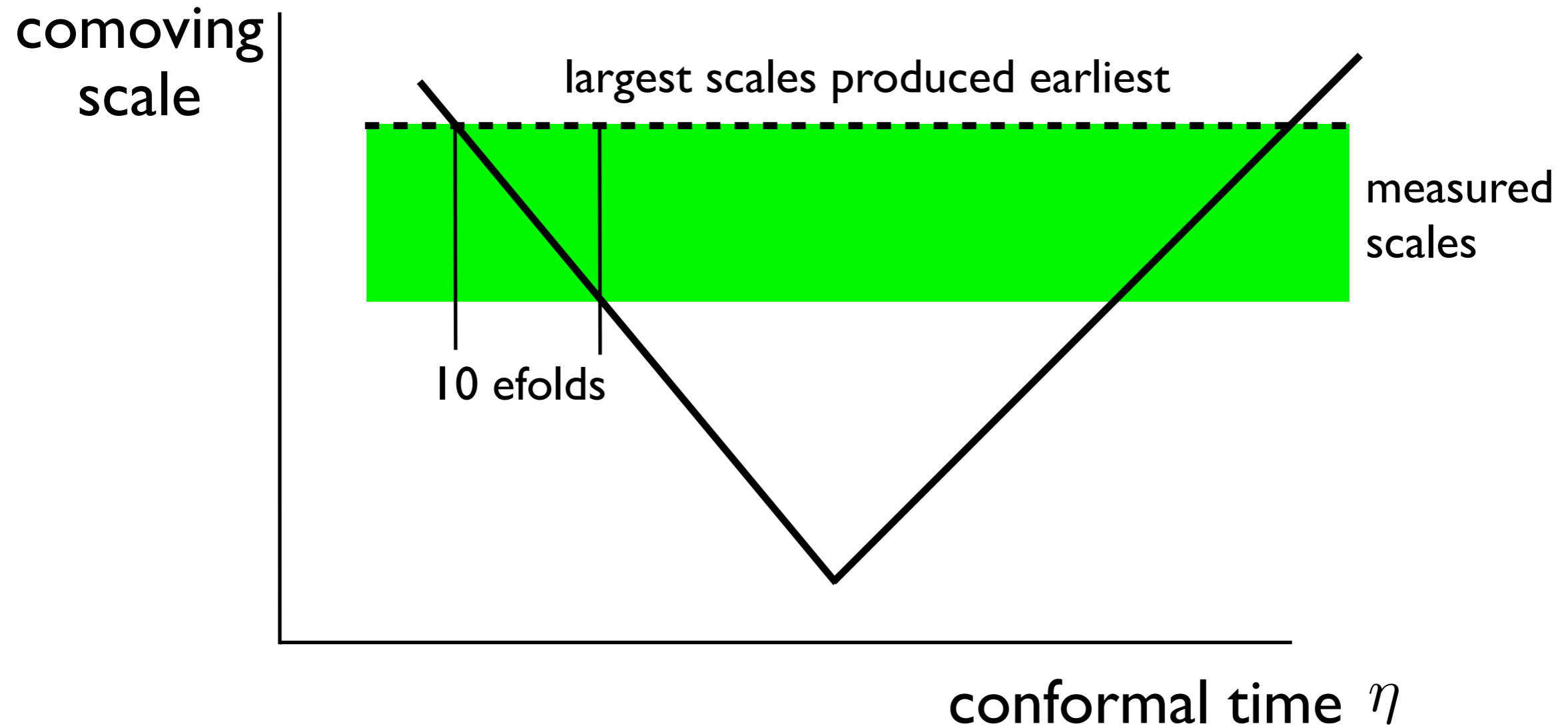
- Measuring the power spectrum in our world: spatially varying noise.
- The measured signal is not completely statistically isotropic--need to understand precisely.



Cosmic Variance



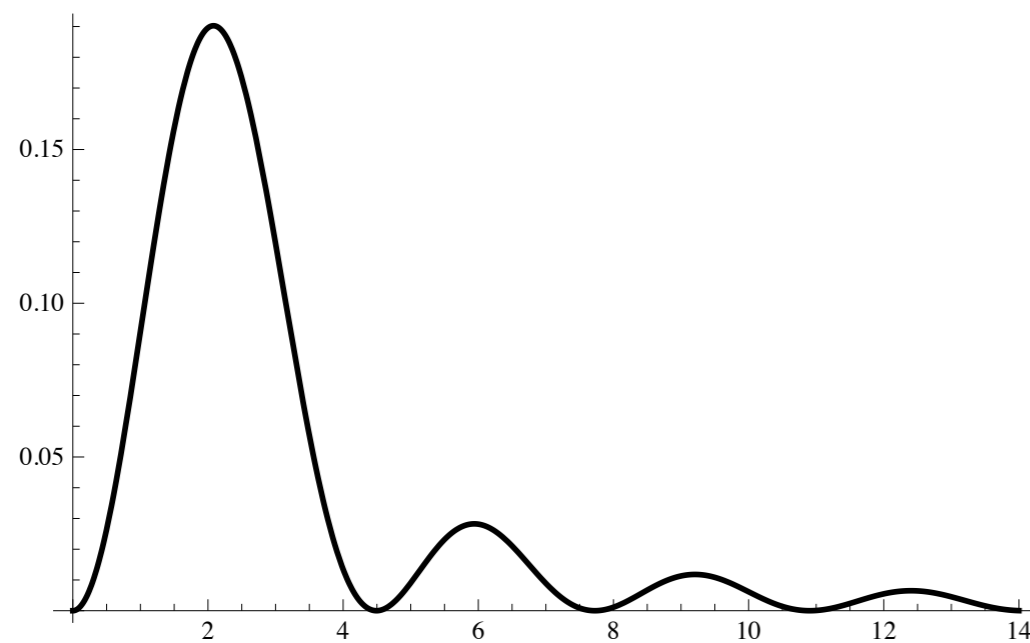
Cosmic Variance



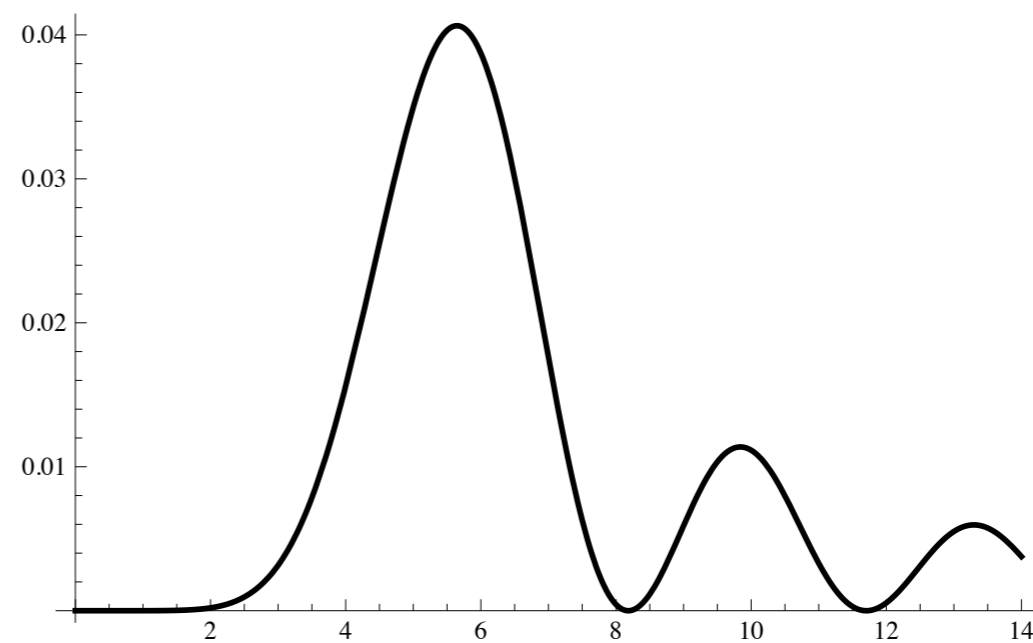
- We observe fluctuations from 10 e-folds in the CMB.

Cosmic Variance

- Each multipole gets contributions from a variety of k .
- Low multipoles get dominant contribution from largest scales.



$\Delta_{\ell=2}(k)$



$\Delta_{\ell=5}(k)$

$$a_{\ell m} = \int \frac{d^3 k}{(2\pi)^3} \Delta_{\ell}(k) \Phi_{\text{init}}(k) Y_{\ell m}(\hat{k})$$

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The most (intrinsic) uncertainty is at the largest scales and therefore near the beginning of inflation.

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Can we do better?

A Finite Amount of information

- We see only what is on our light cone.
- e.g. we don't see the actual galaxies that the fluctuations in the CMB grow into.

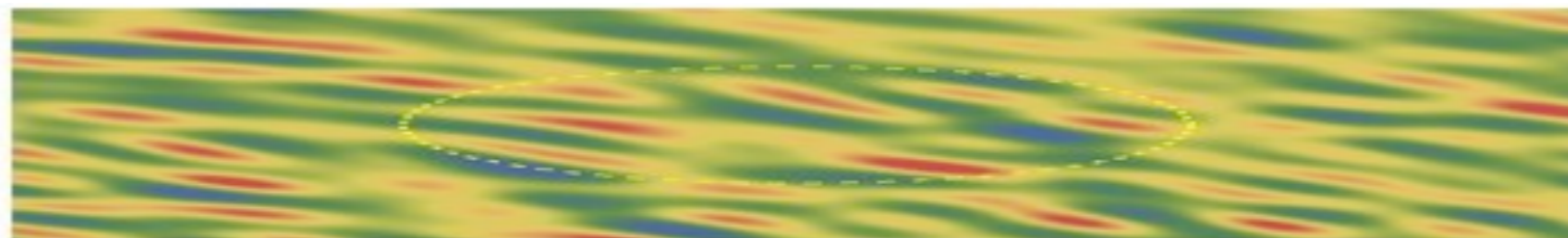
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today



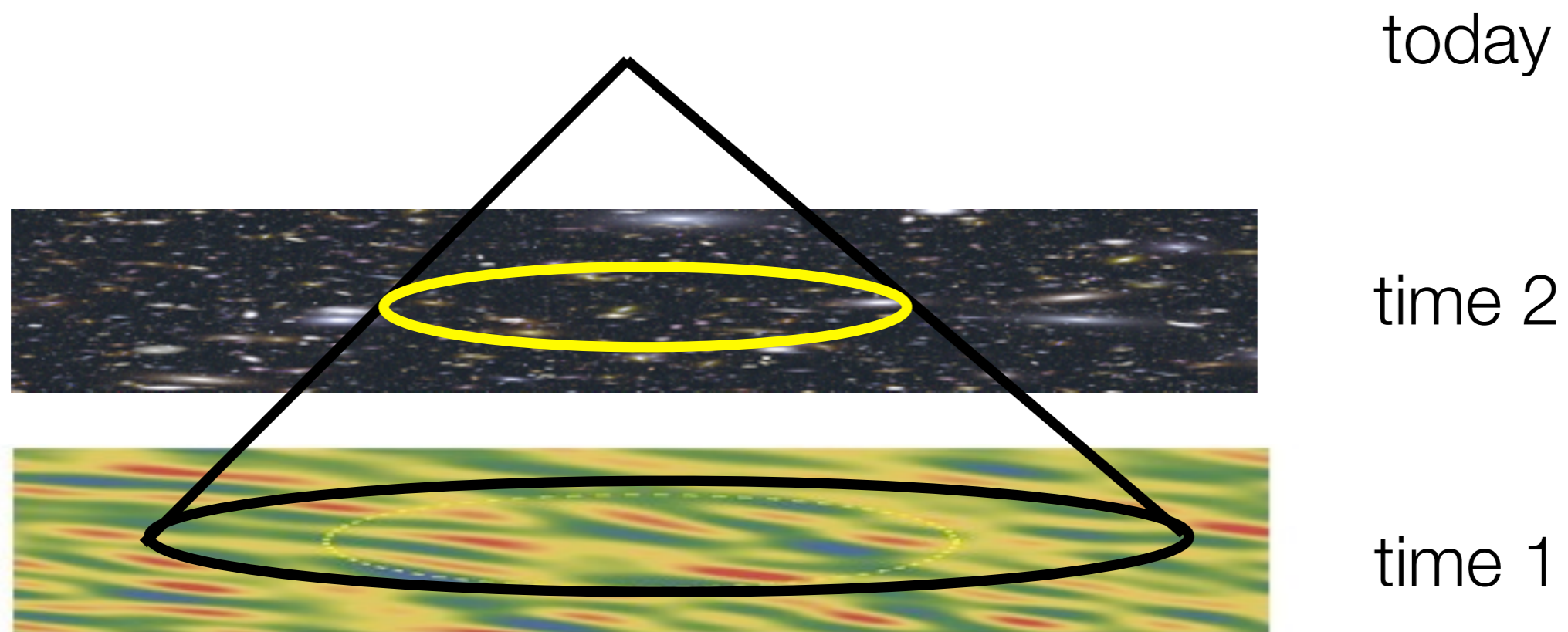
time 2



time 1

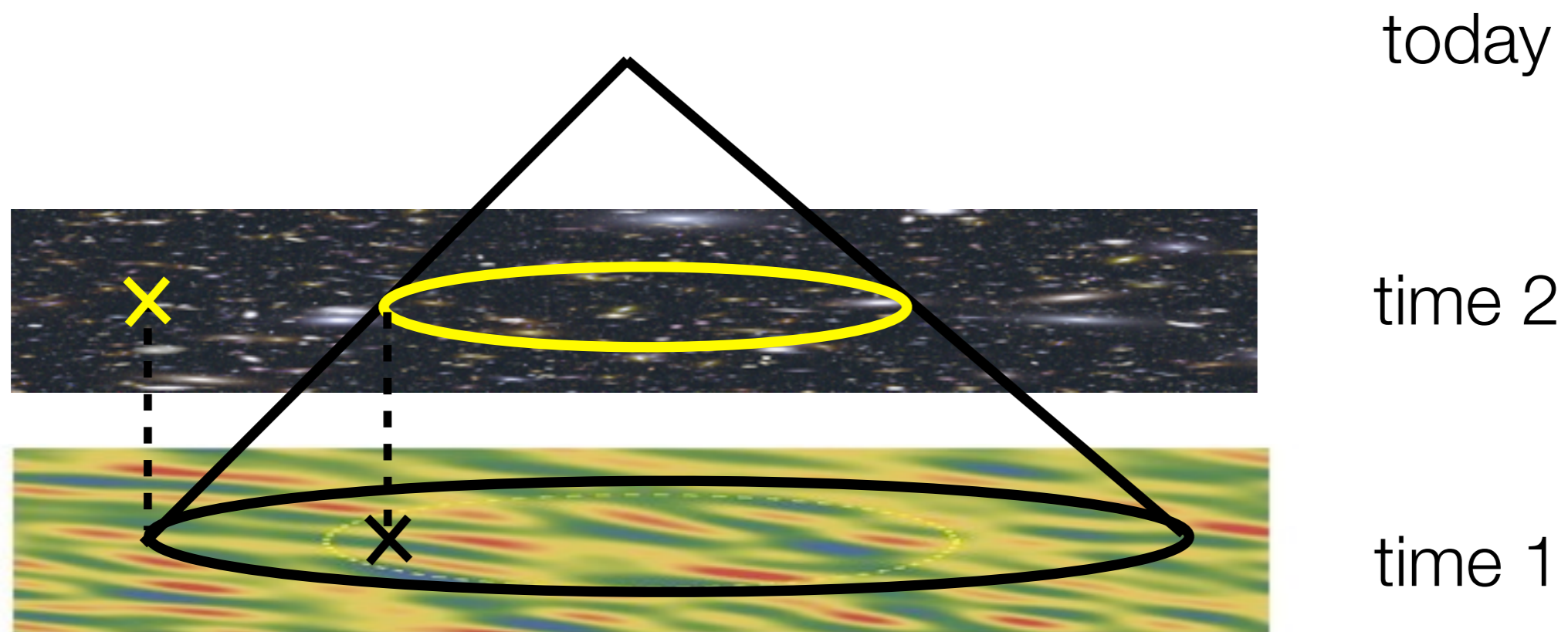
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A Finite Amount of information

- The best we get is a set of projections:



time 1

$\mathcal{P}(t_1)$



time 2

$\mathcal{P}(t_2)$



time 3

$\mathcal{P}(t_3)$

$\mathcal{P}(t = 0)$

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time 3

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$$\mathcal{P}(t = 0)$$

- With more projections, we can better test our theory of initial conditions and evolution for *probability distributions*.
- Hopefully realized in measurements of the 21 cm hydrogen line.

A Finite Amount of information

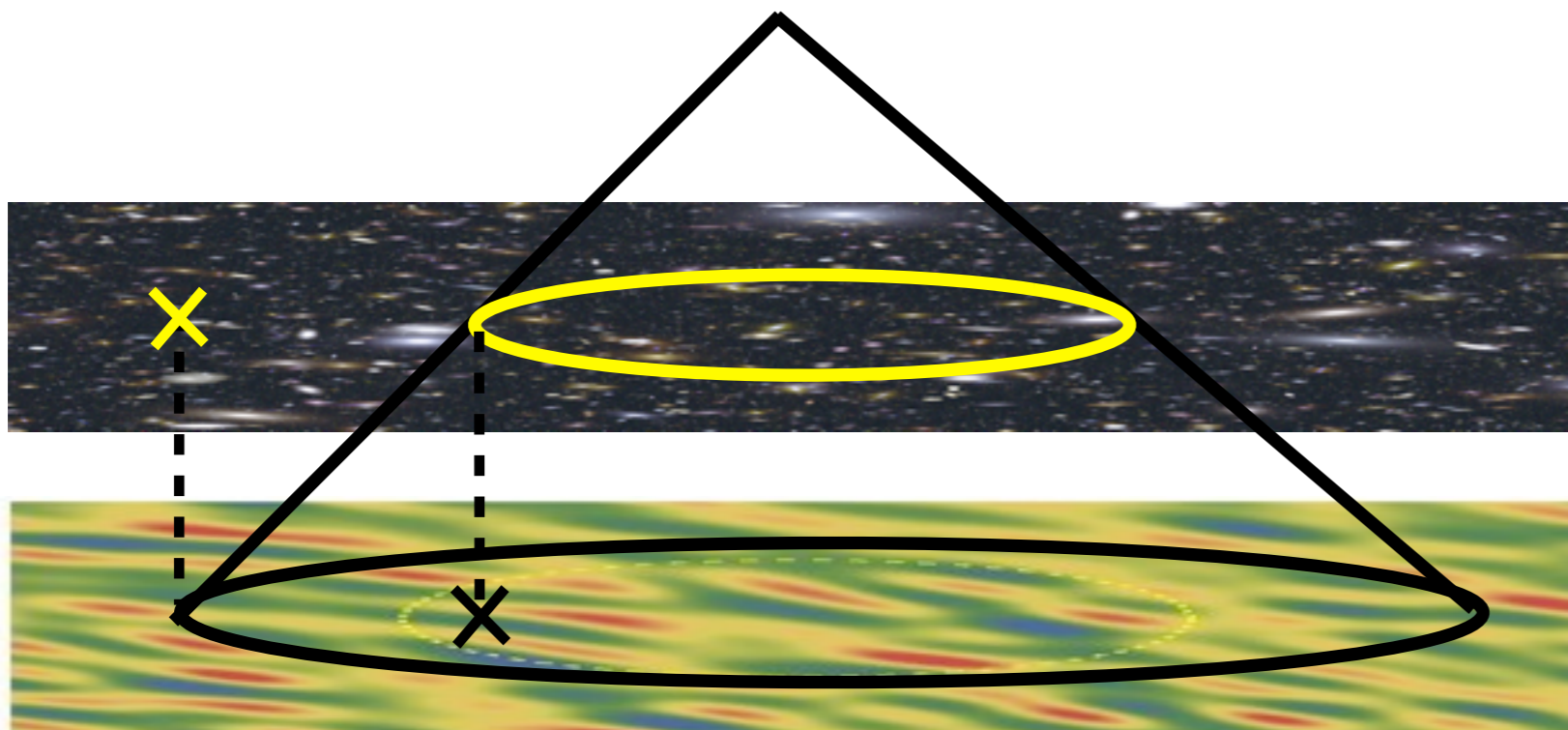
- Finite number of linear modes to measure.

$c_s^2 = 0$	radiation	matter	dark energy
	$\frac{\delta\rho}{\bar{\rho}} \propto \log(a)$	$\frac{\delta\rho}{\bar{\rho}} \propto a$	$\frac{\delta\rho}{\bar{\rho}} \propto \text{const.}$

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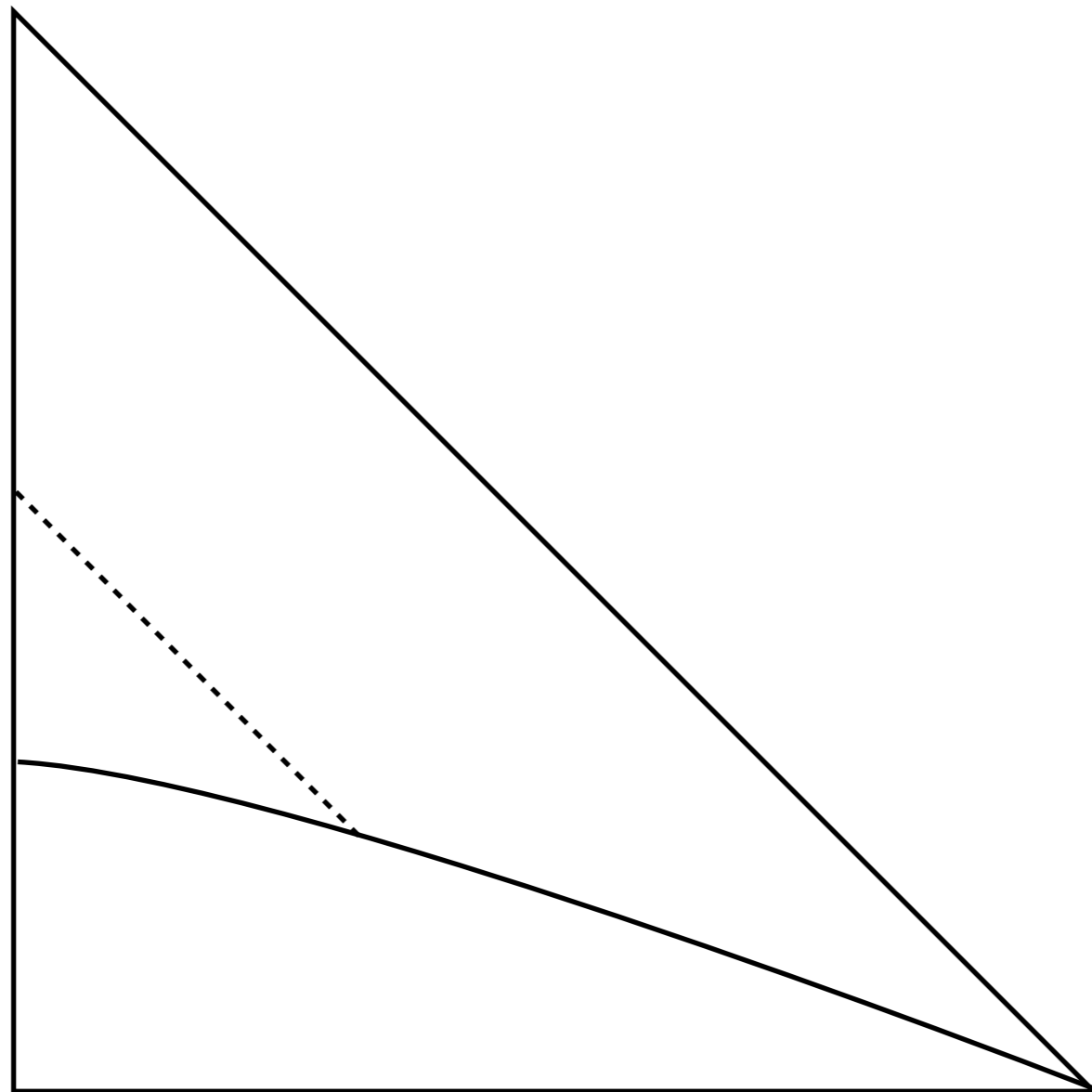


↑ narrowing window

$$k_{\text{obs}} \leq k < k_{\text{lin}}$$

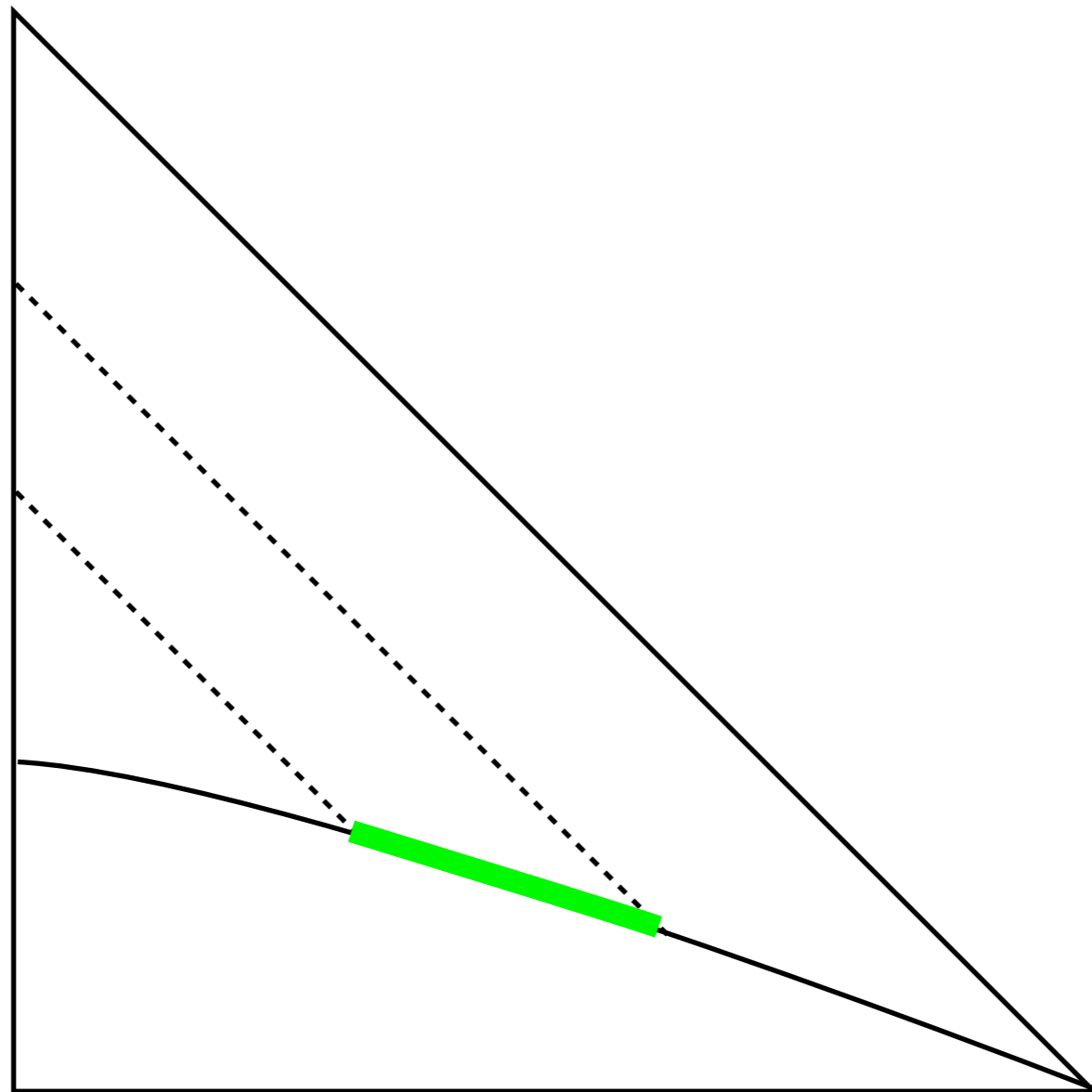
A Finite Amount of information

- Without a fundamental CC, we can see everything and travel to any galaxy we currently observe



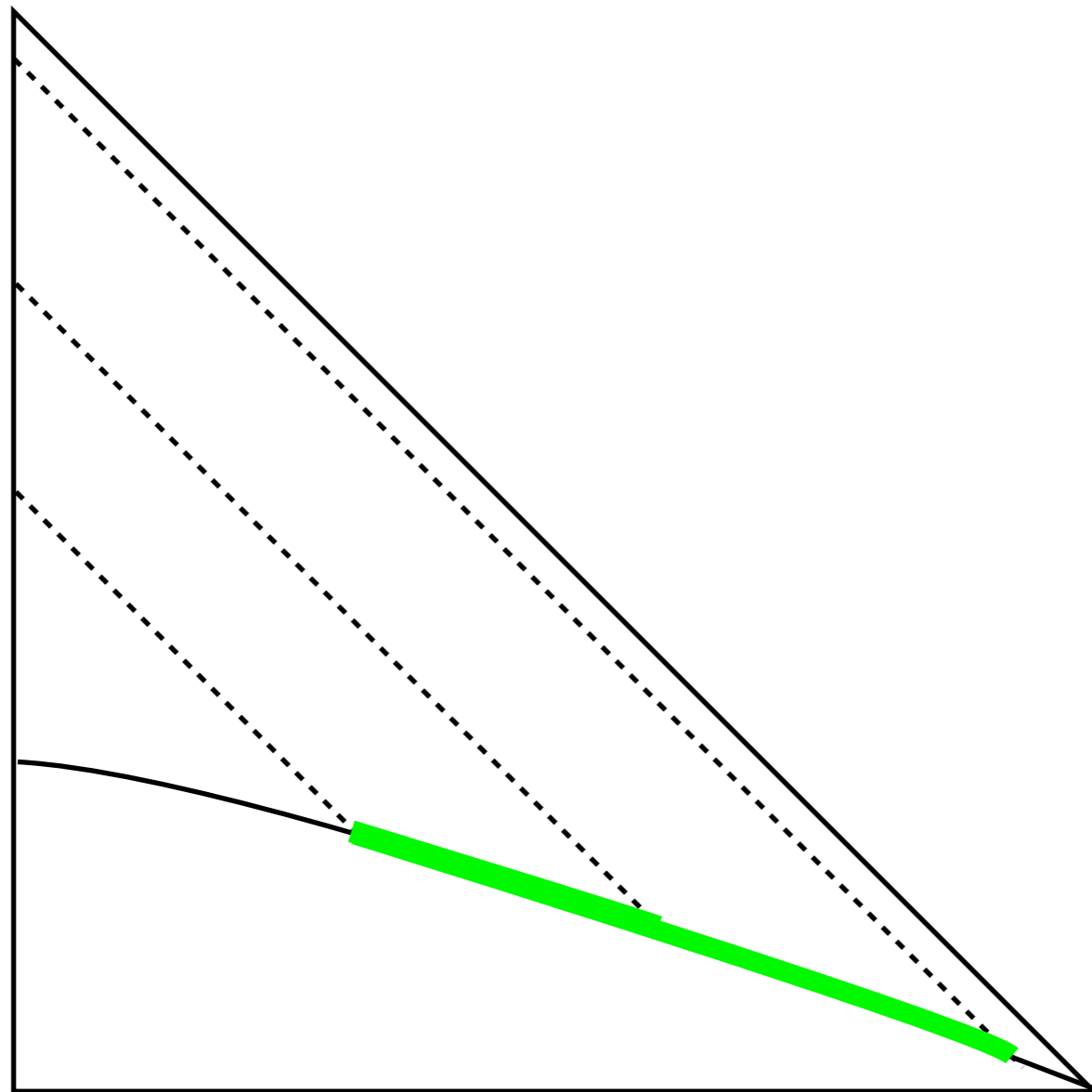
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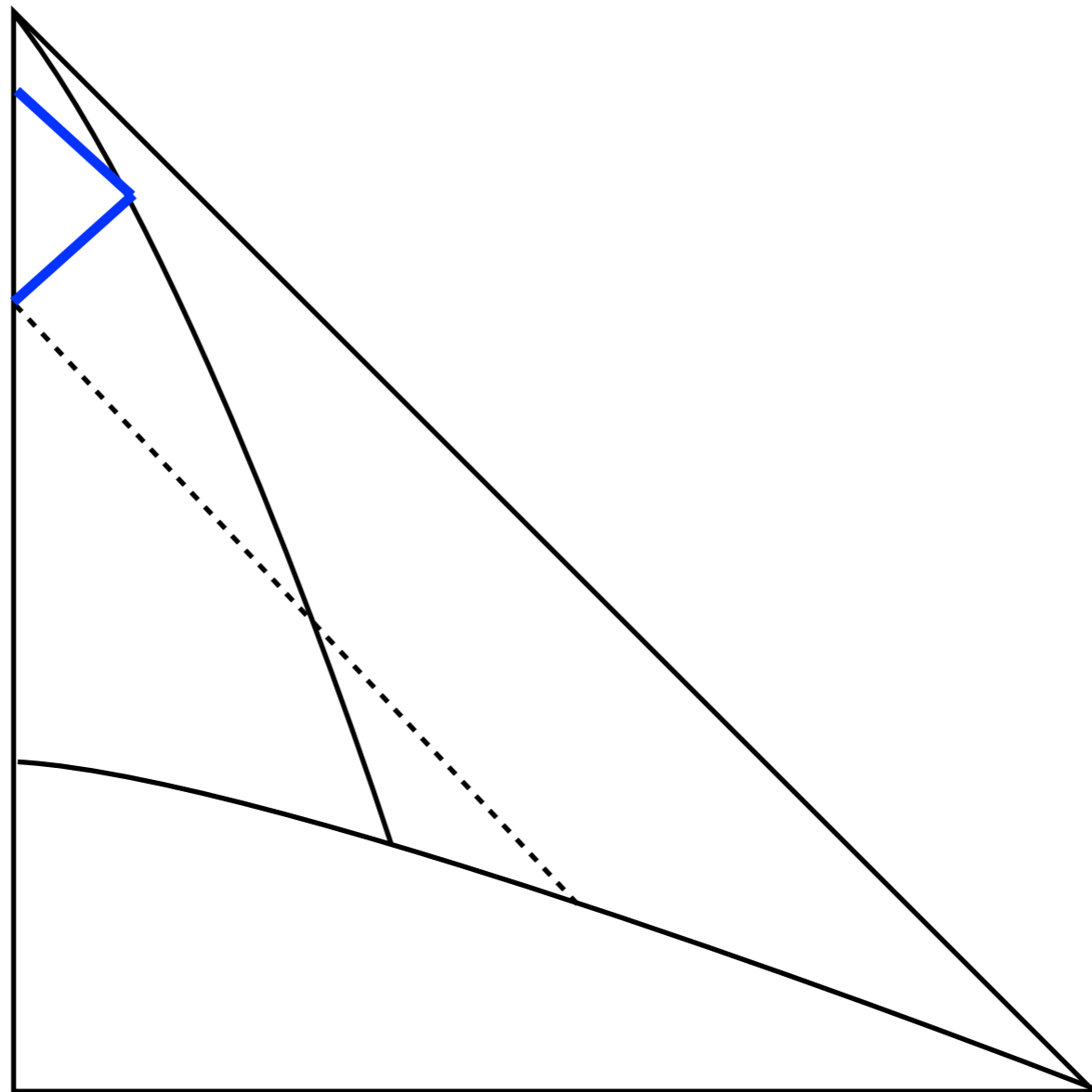
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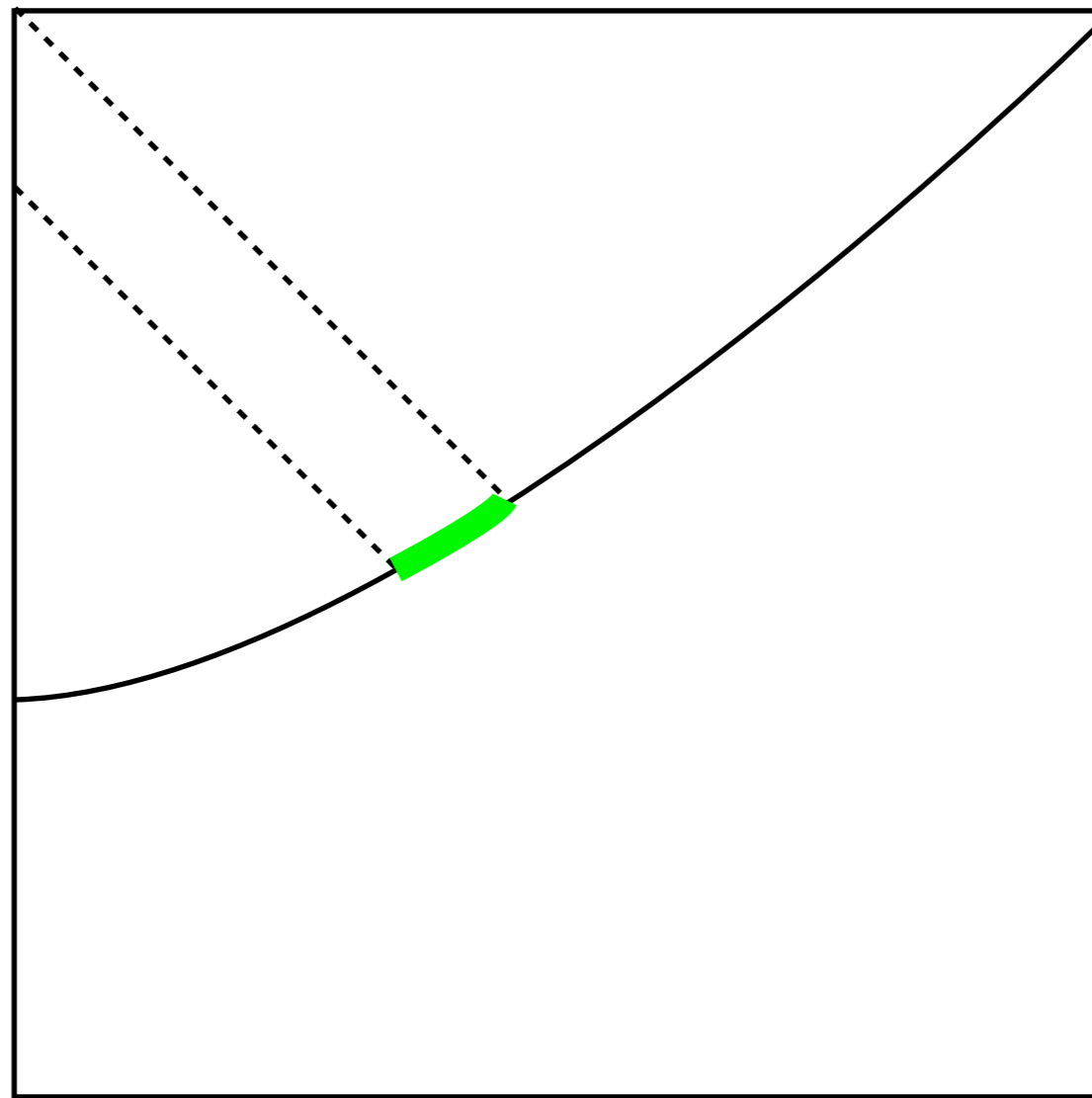
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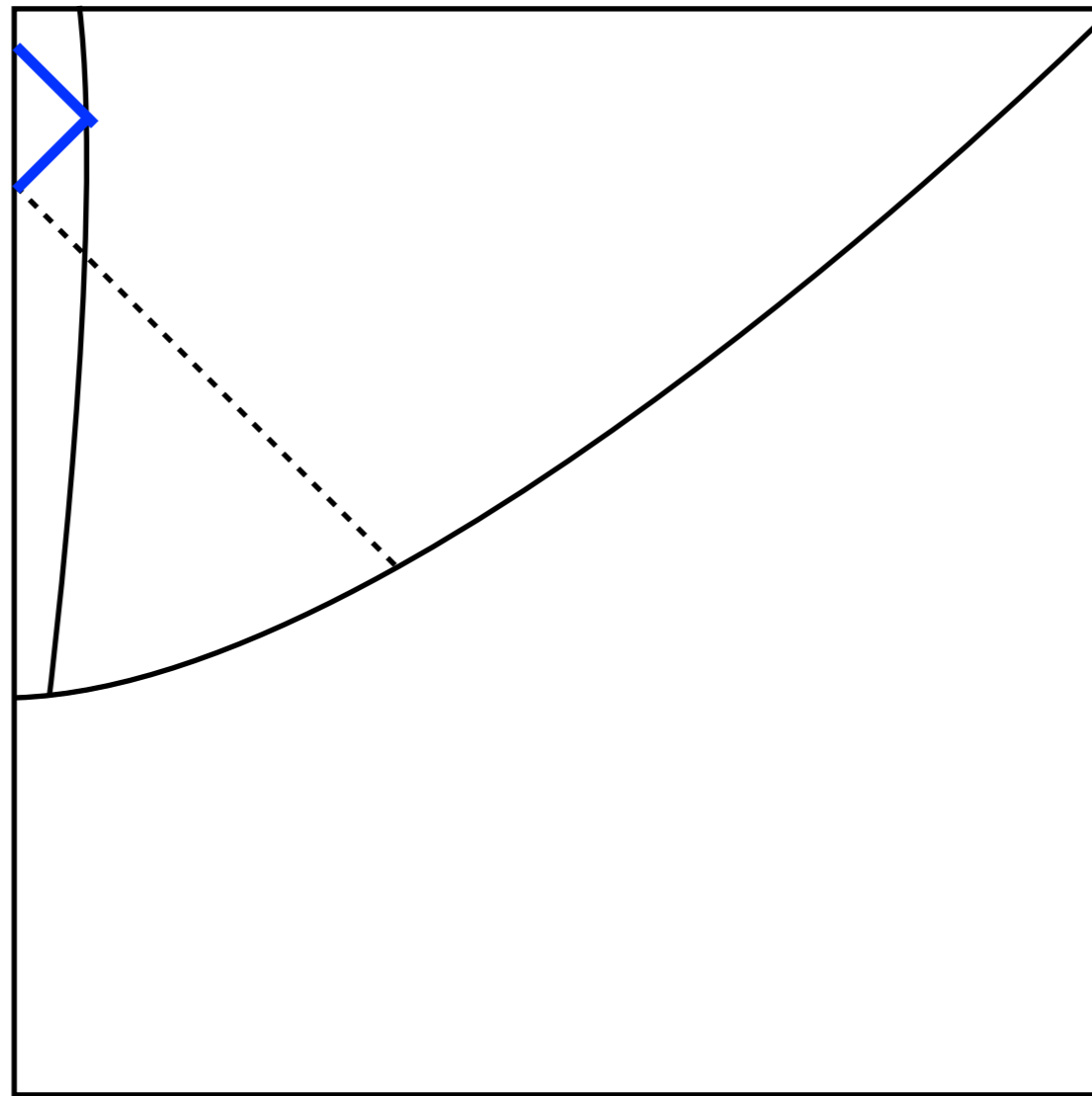
A Finite Amount of information

- With a fundamental CC, there are limits



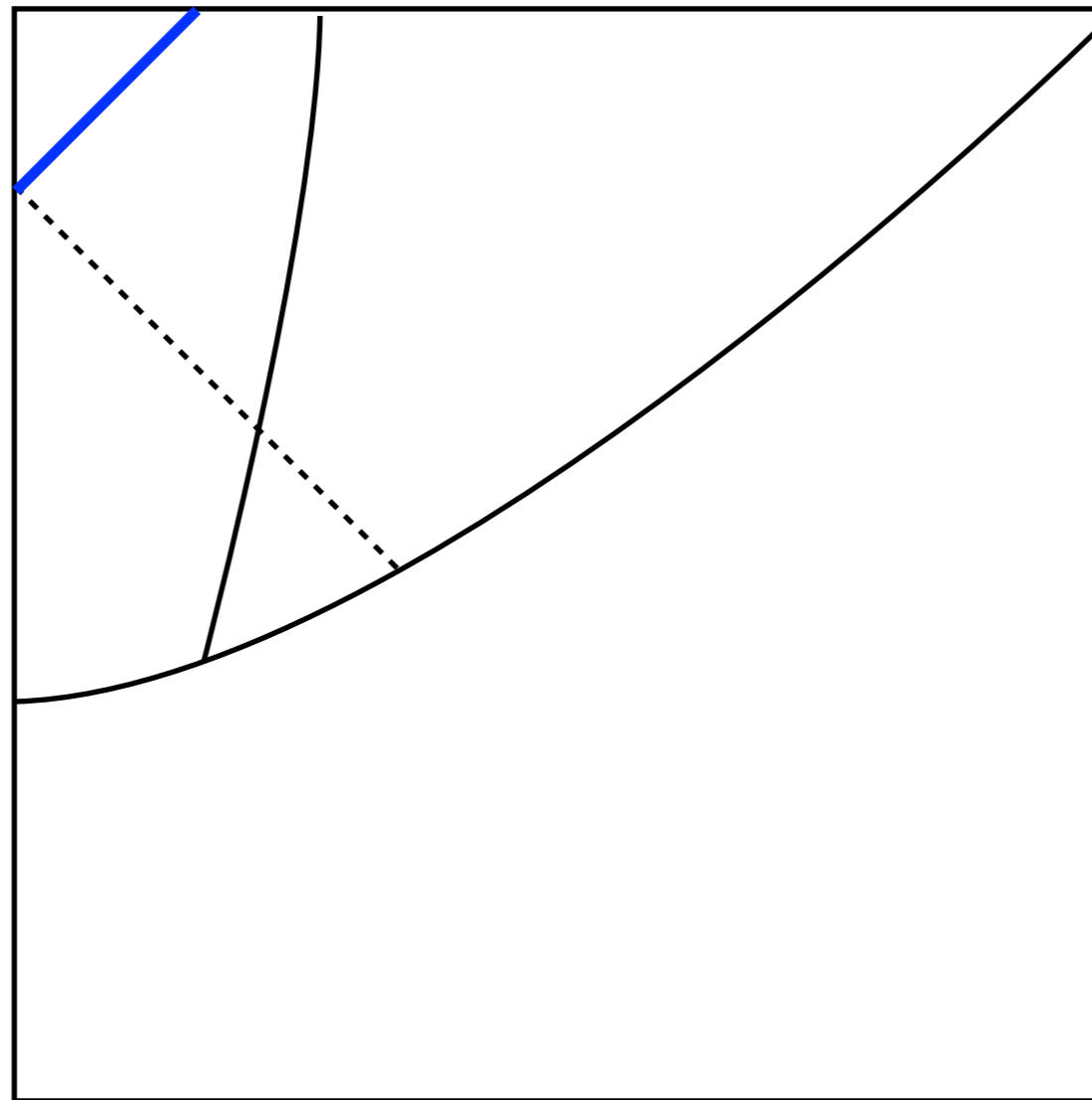
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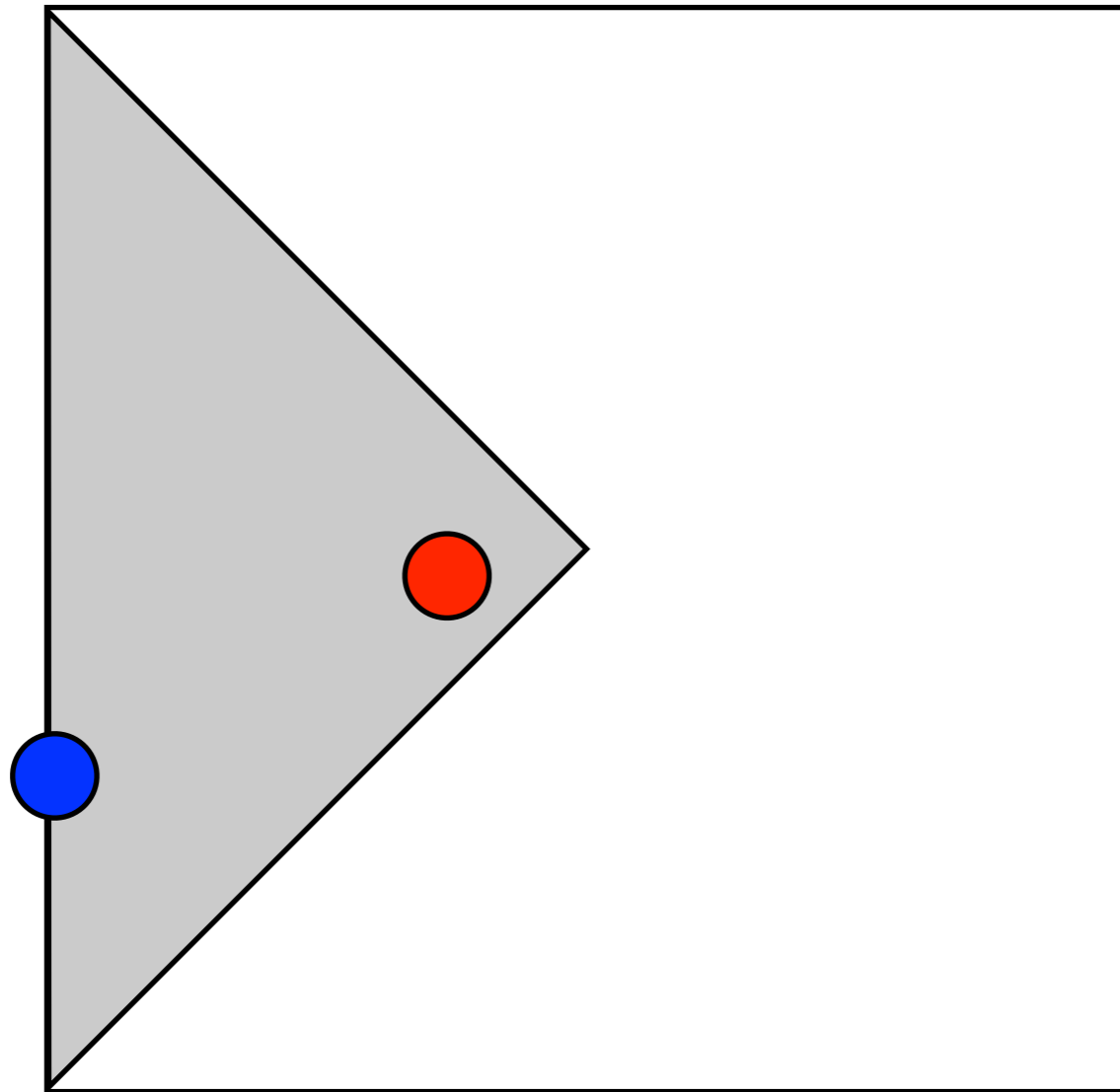
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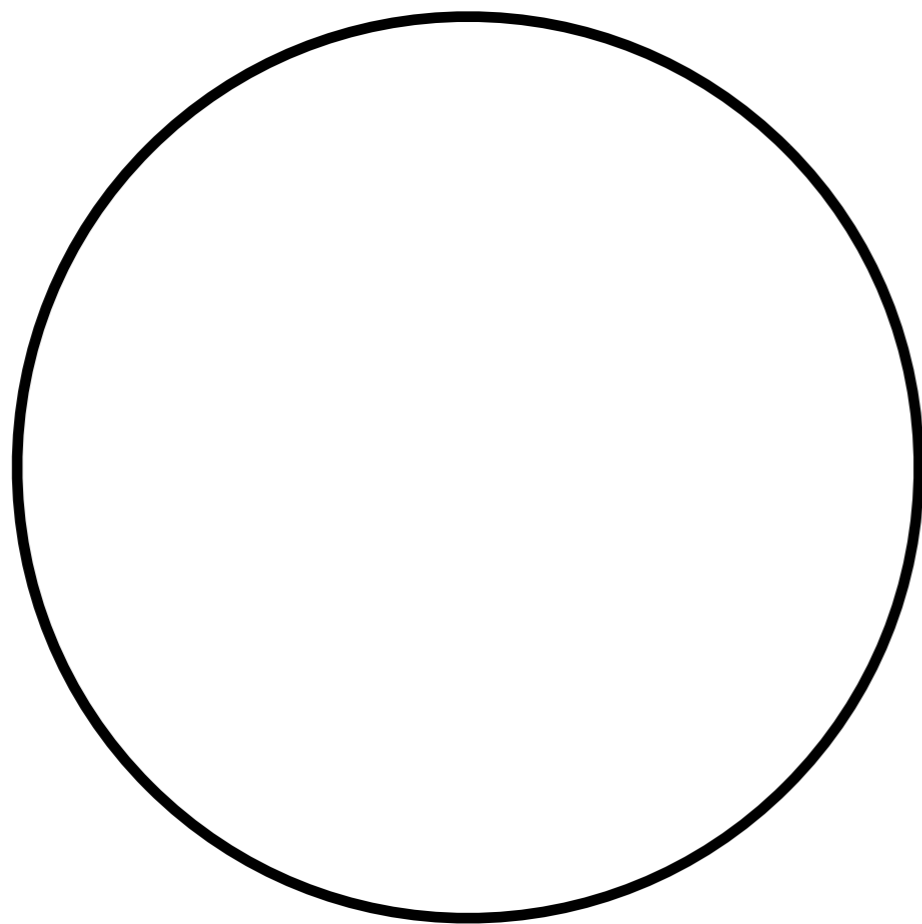
- Another consequence of a cosmological constant: maximum precision for any conceivable experiment.



can't separate things
to arbitrarily large
distances

A Finite Amount of information

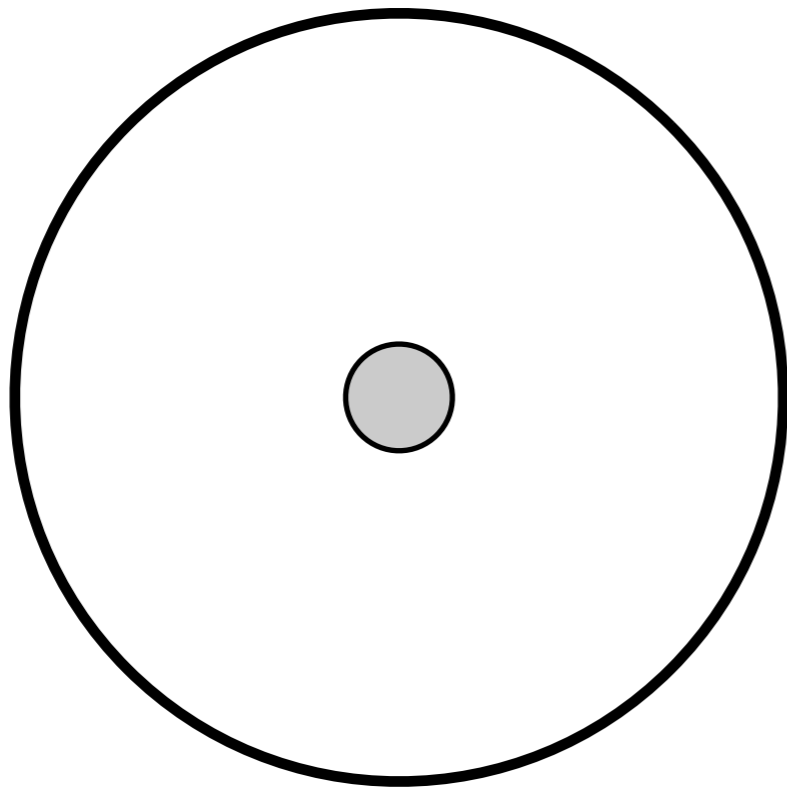
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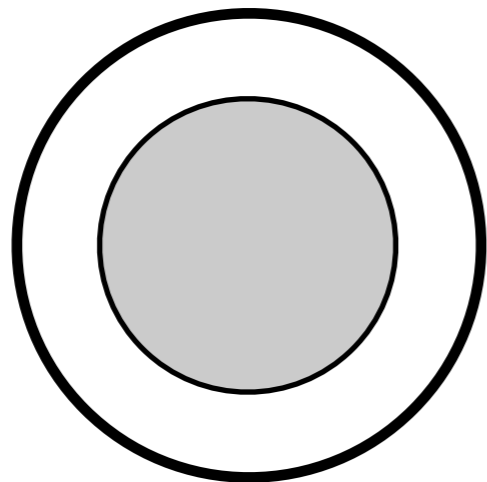


cosmological horizon shrinks
in presence of a mass

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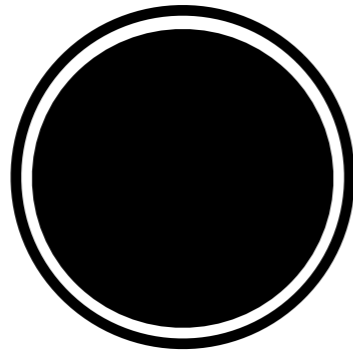


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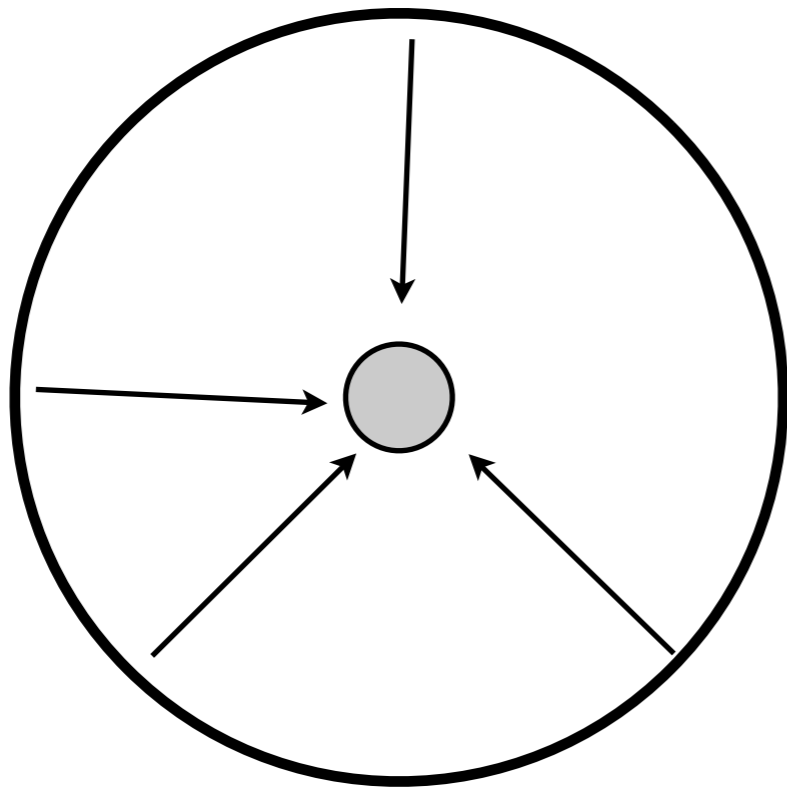


There is a biggest black hole,
and therefore a biggest
apparatus and a finite number
of states.

can't make an
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complicated apparatus

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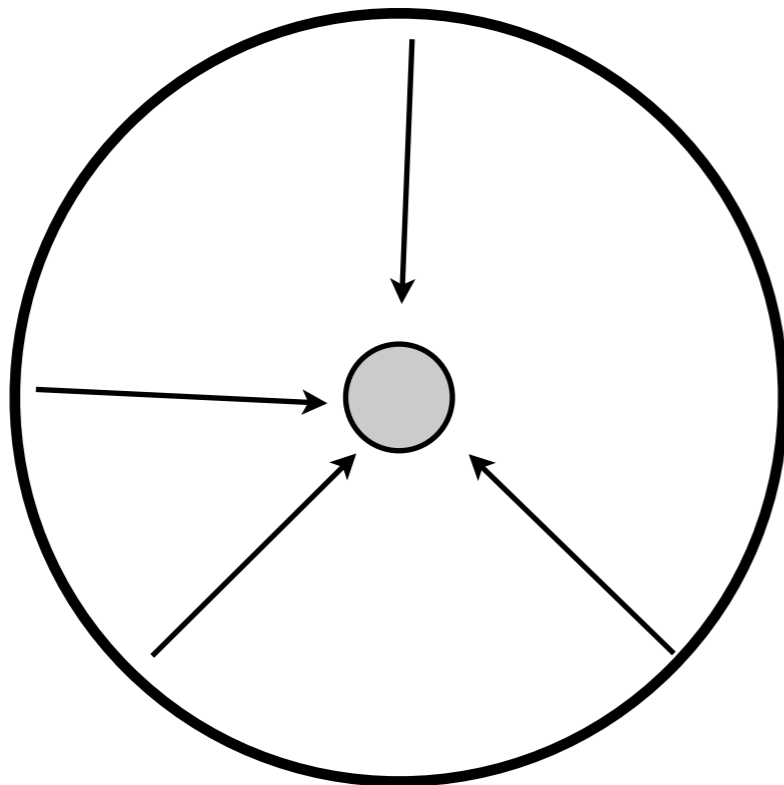
- Another consequence of a cosmological constant: maximum precision for any conceivable experiment.



Any detector is being
bombarded by Hawking
radiation

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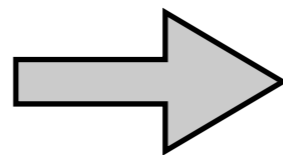
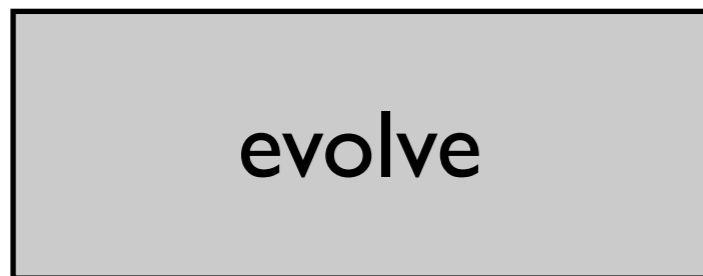
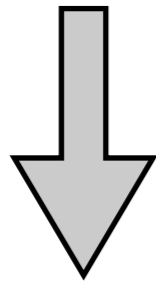


Any detector has a
finite lifetime

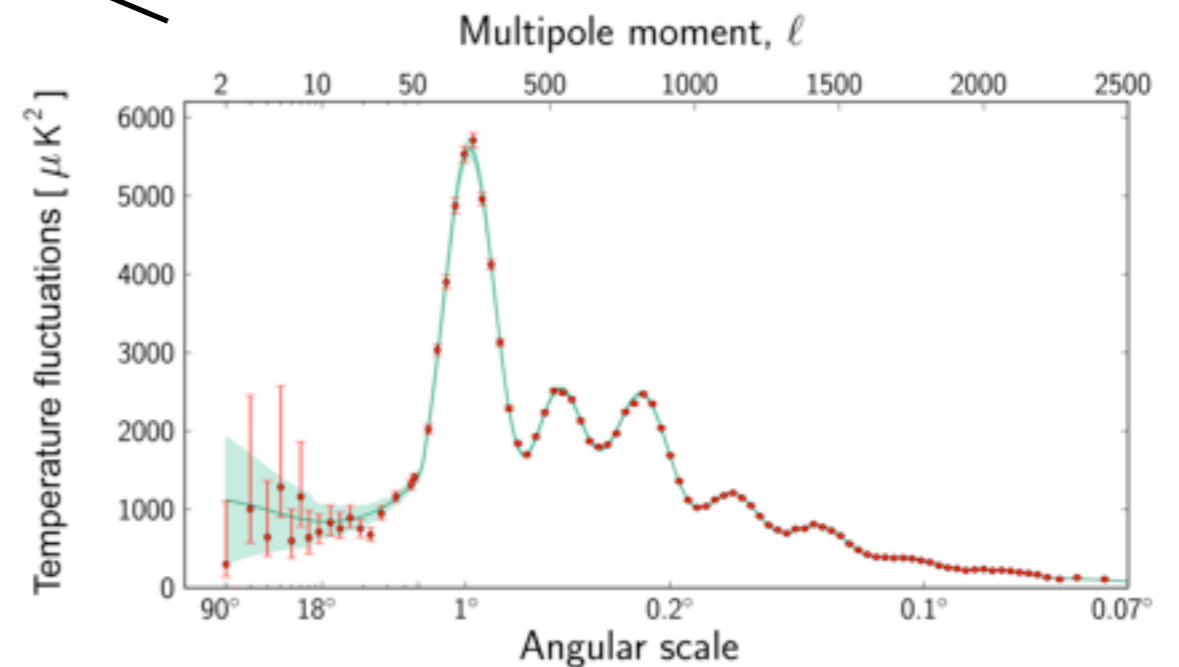
In Practice

- How do we compare data with theory?

$\Omega_c, \Omega_b, \Omega_\Lambda, A, n_s, \tau$



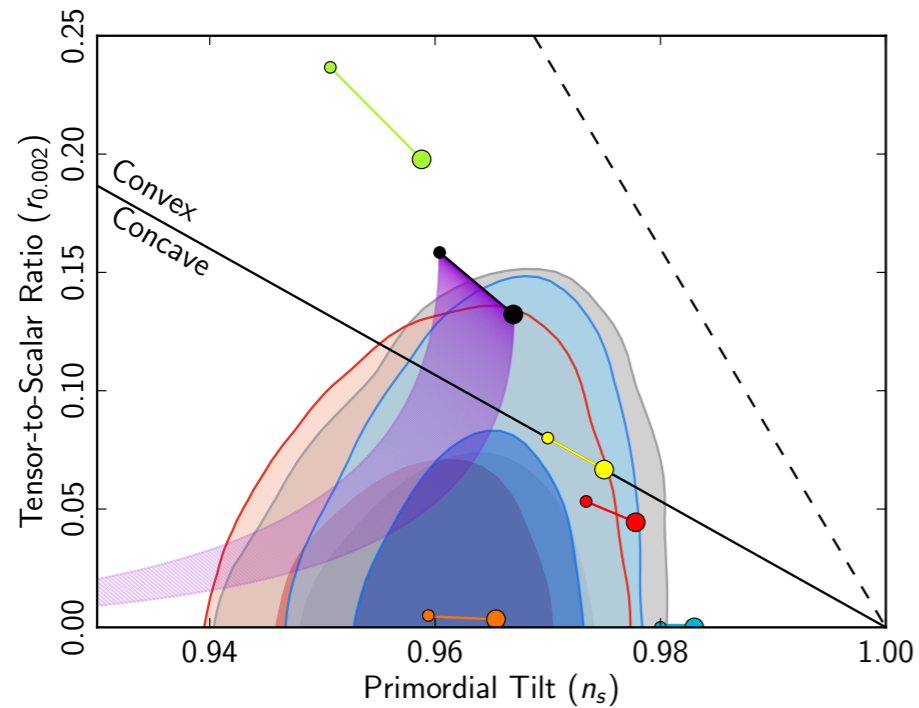
experimental
details



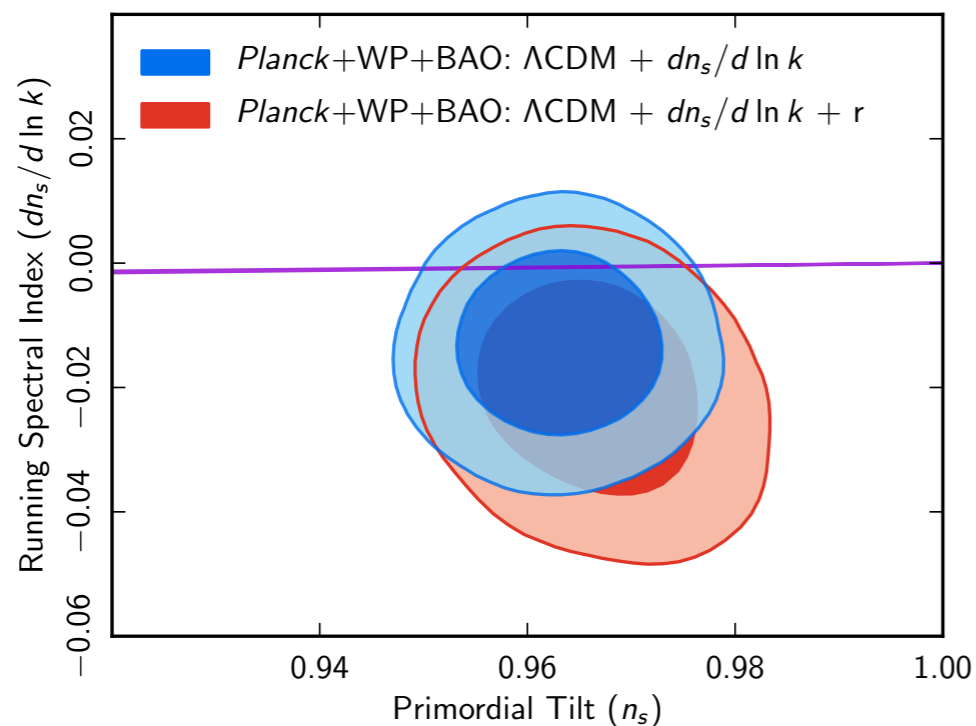
- Test the fit to data, repeat. $\text{Pr}(\text{data}|\text{model})$
- Important part: include other datasets!

In Practice

- Include more variables, and test the fit.



6 parameter model
still works best!!!



Eternal Inflation: is this our universe?



Movie: Anthony Aguirre

Really?

- An infinite number of individually infinite universes in an infinite expanding background?

Surely I can't be serious!

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non-unique vacuum
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(possible in standard model)

(common in BSM physics)

(inevitable in string theory)

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Quantum field
theory

(works fantastically)

accelerated
expansion

(observed: dark energy)

(inferred: inflation)

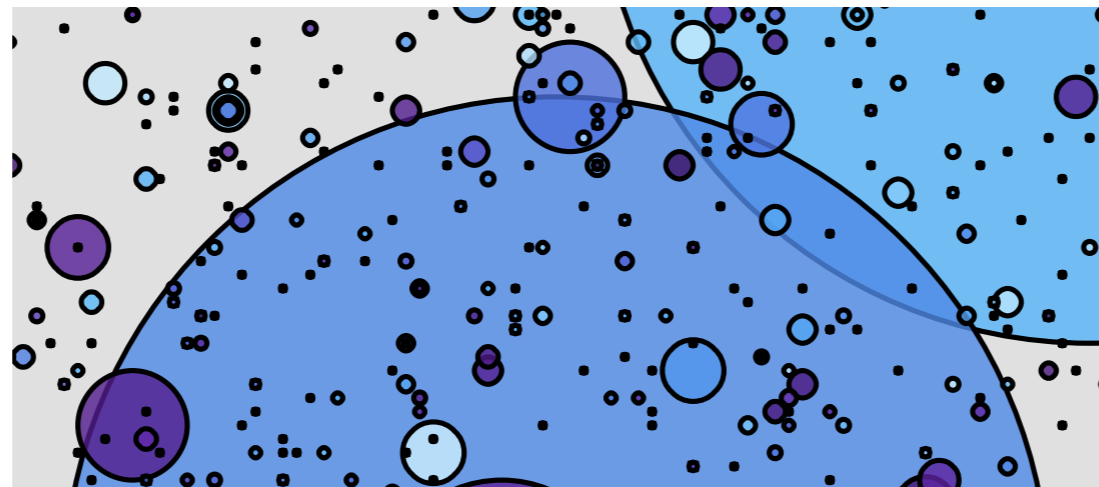
Observational Tests of Eternal Inflation

- Strong theoretical motivation, but is eternal inflation experimentally verifiable?

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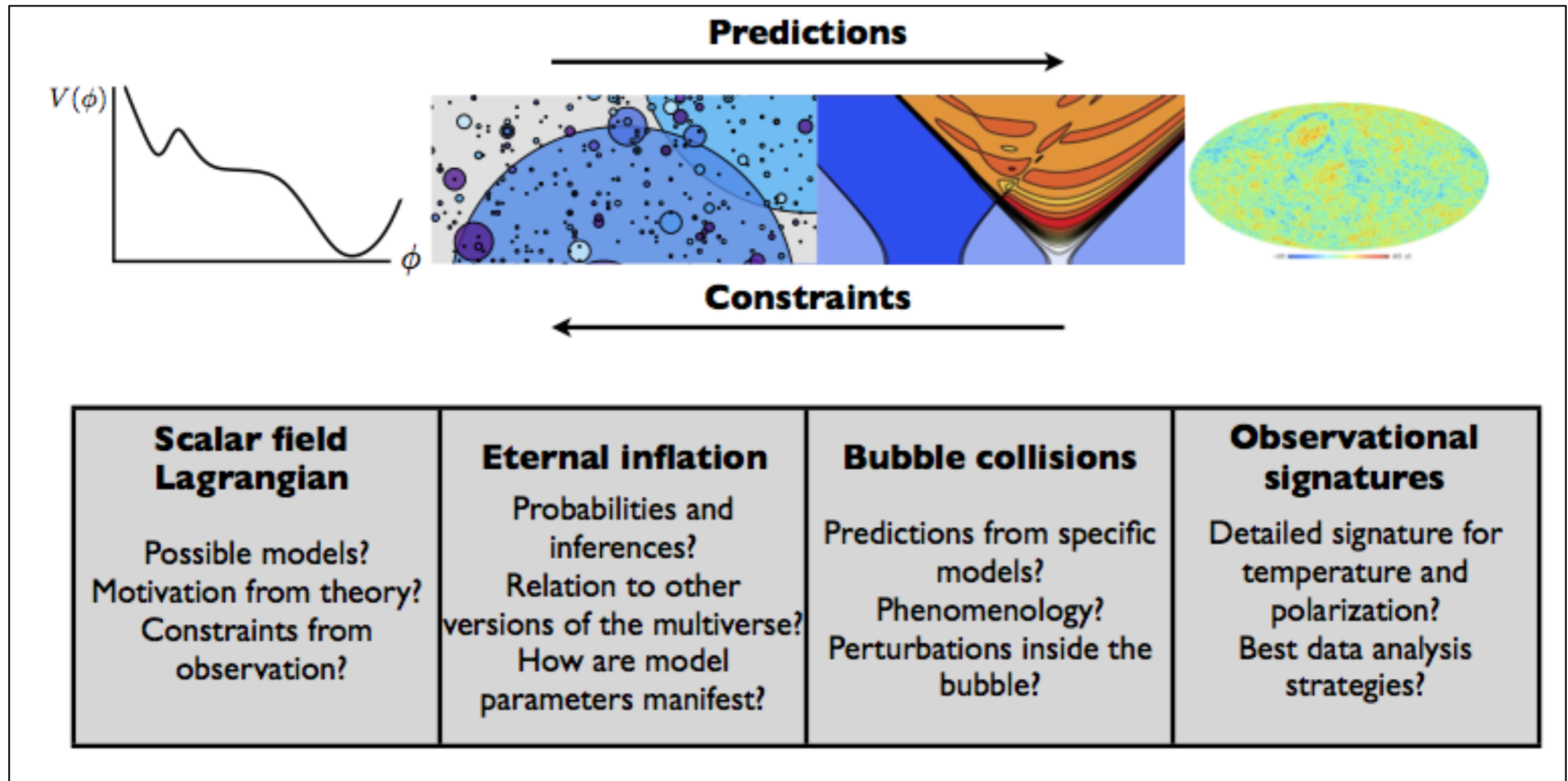
Our bubble does not evolve in isolation....



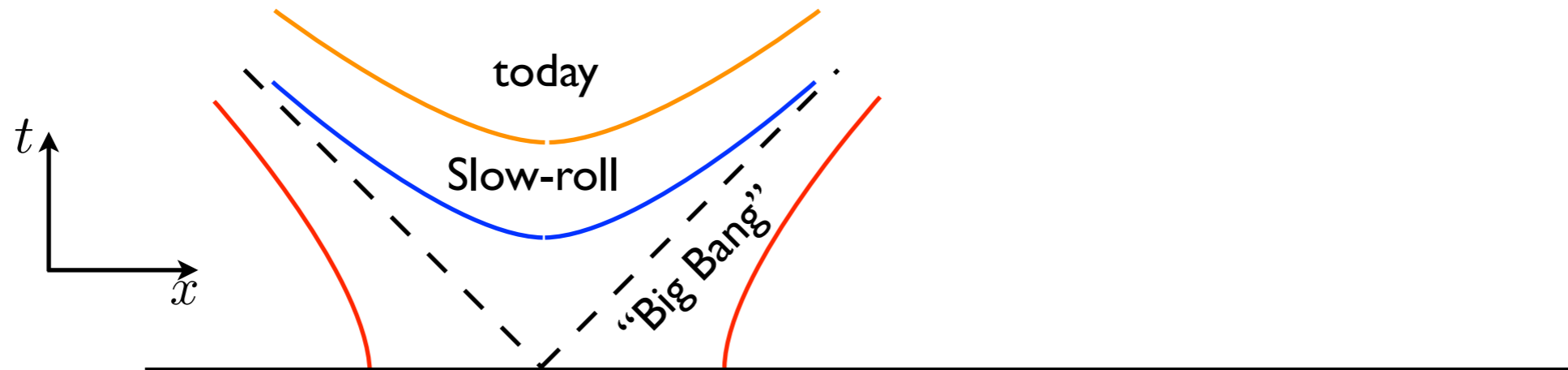
The collision of our bubble with others provides an observational test of eternal inflation.

Aguirre, [MCJ](#), Shomer

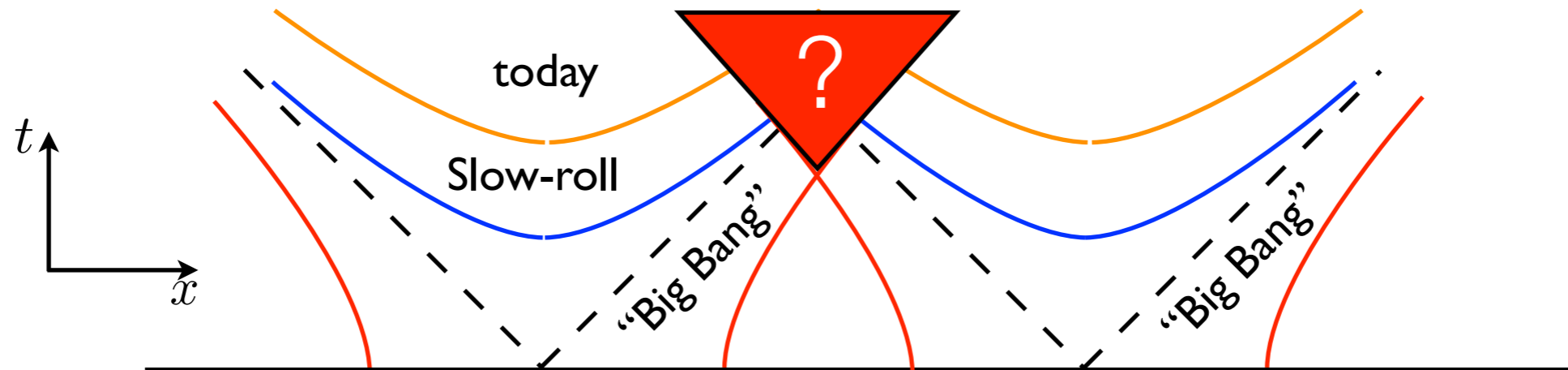
Making predictions and testing models



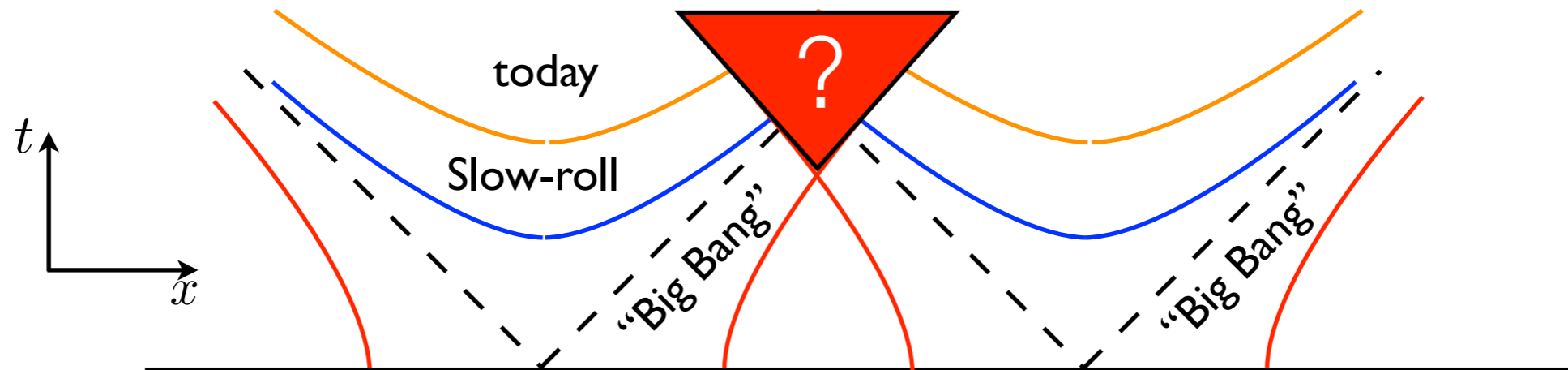
Bubble collisions



Bubble collisions

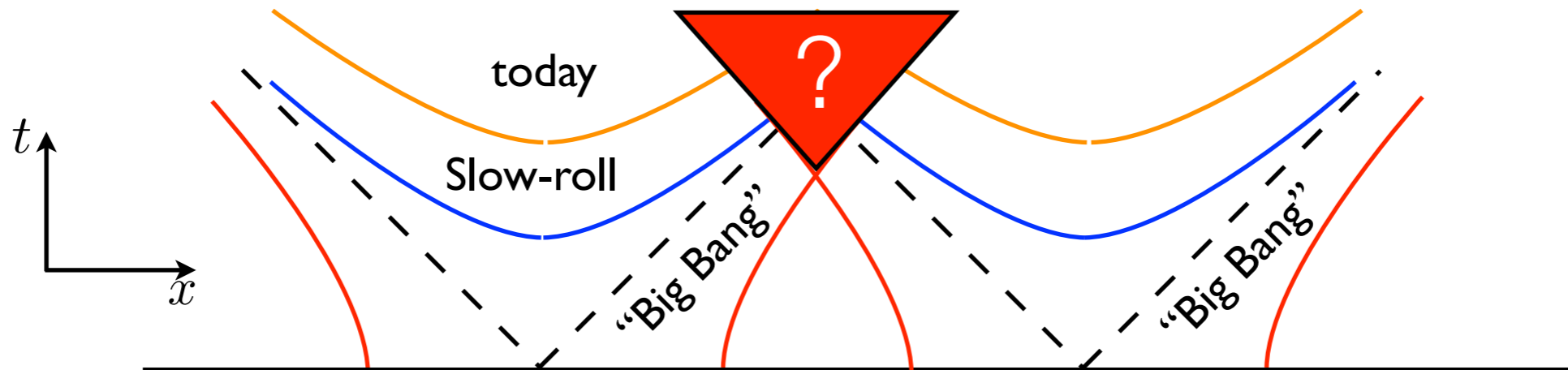


Bubble collisions



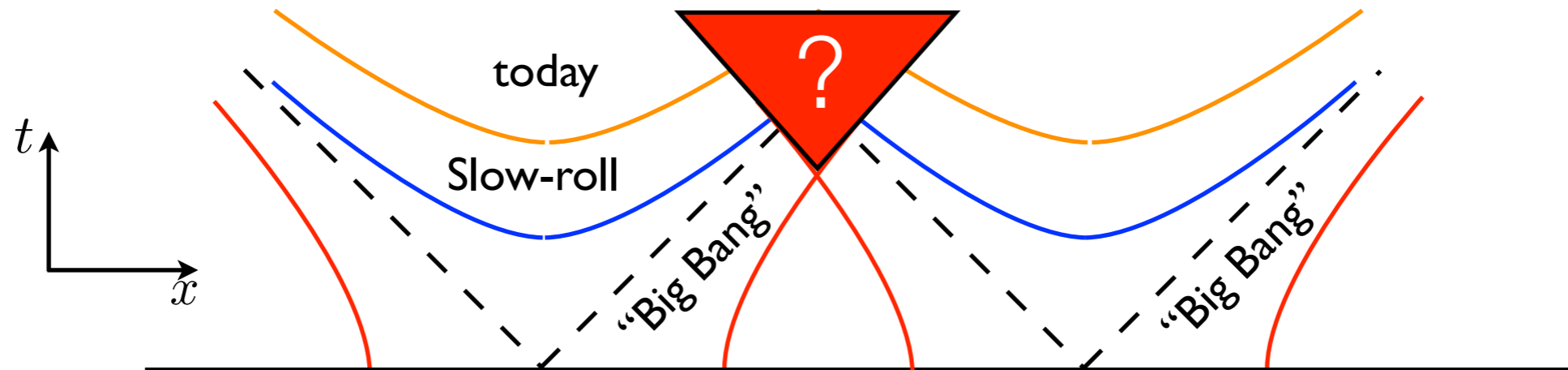
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Bubble collisions



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- To study what happens, need full GR.

Bubble collisions

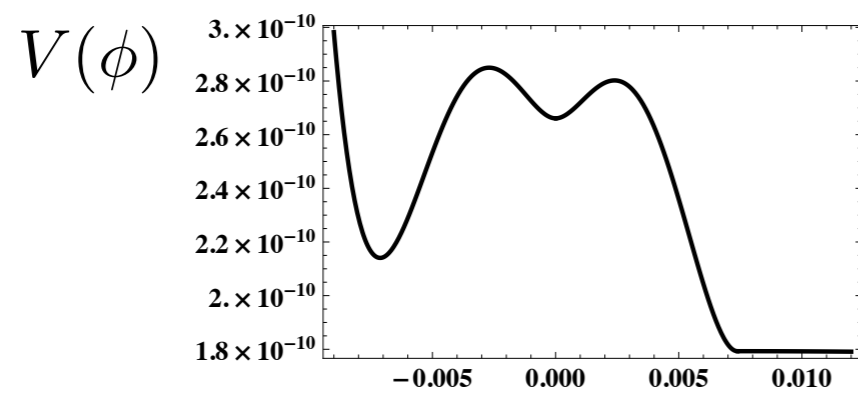


- Collisions are always in our past.
- The outcome is fixed by the potential and kinematics.
- To study what happens, need full GR.
 - We want to find the post-collision cosmology: GR.
 - Huge center of mass energy in the collision.
 - Non-linear potential, non-linear field equations.

Numerical solutions

- Numerical simulations with full GR: full dynamics.

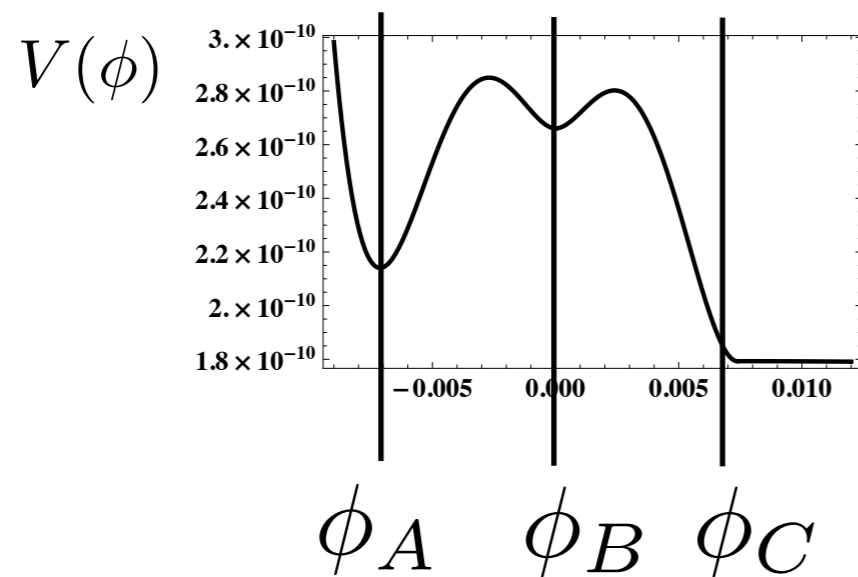
$$ds^2 = -\alpha(x, z)dz^2 + a(x, z)dx^2 + z^2 dH_2^2 \quad \phi(x, z)$$



Numerical solutions

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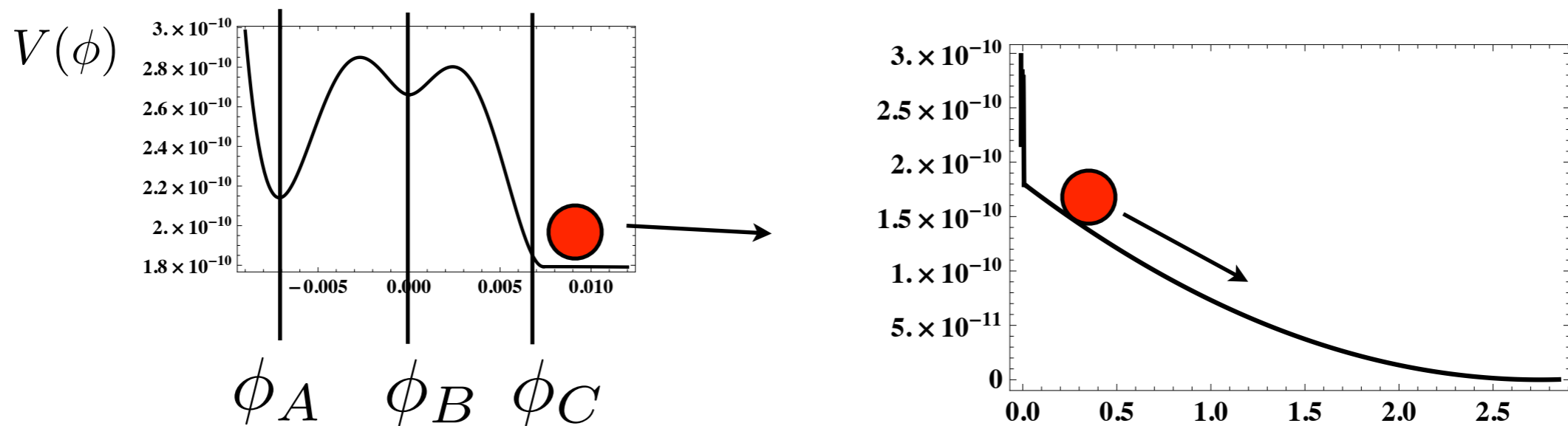


- 2 types of bubbles from false vacuum.

Numerical solutions

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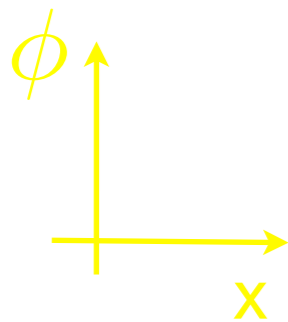
$$ds^2 = -\alpha(x, z)dz^2 + a(x, z)dx^2 + z^2 dH_2^2 \quad \phi(x, z)$$



- 2 types of bubbles from false vacuum.
- Slow roll inflation inside one, starting near ϕ_C .

Numerical solutions

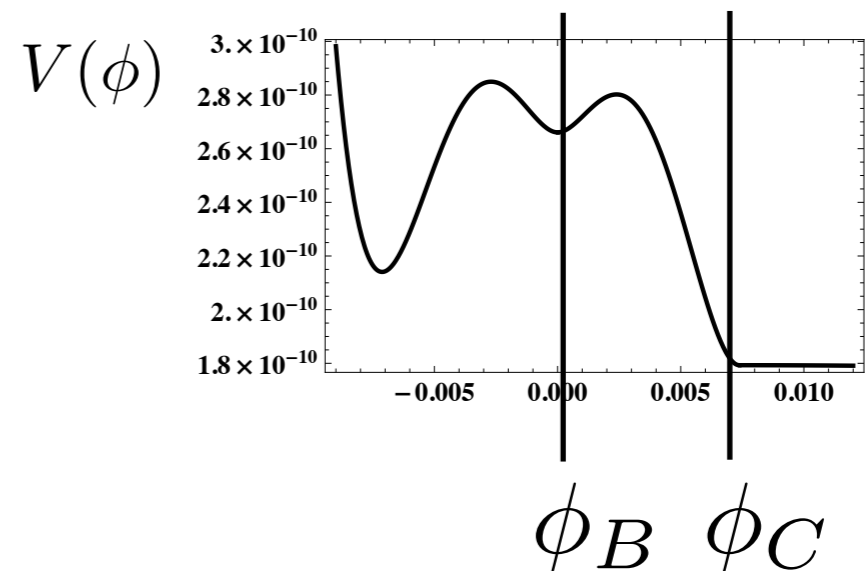
- Colliding identical bubbles.



$$2(\phi_C - \phi_B)$$

$$\phi_C$$

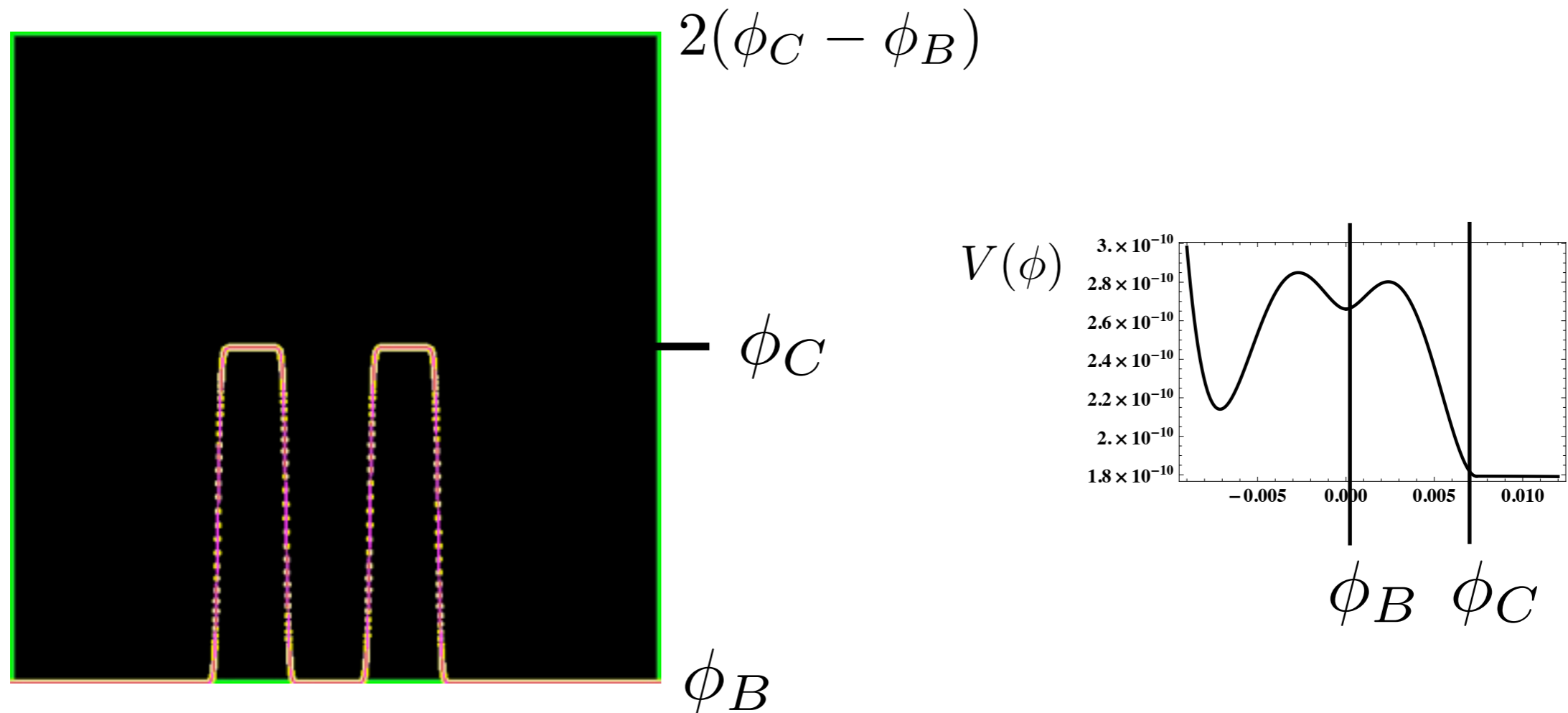
$$\phi_B$$



- After the collision, fields linearly superpose: potential key.
- Dynamics necessary!

Numerical solutions

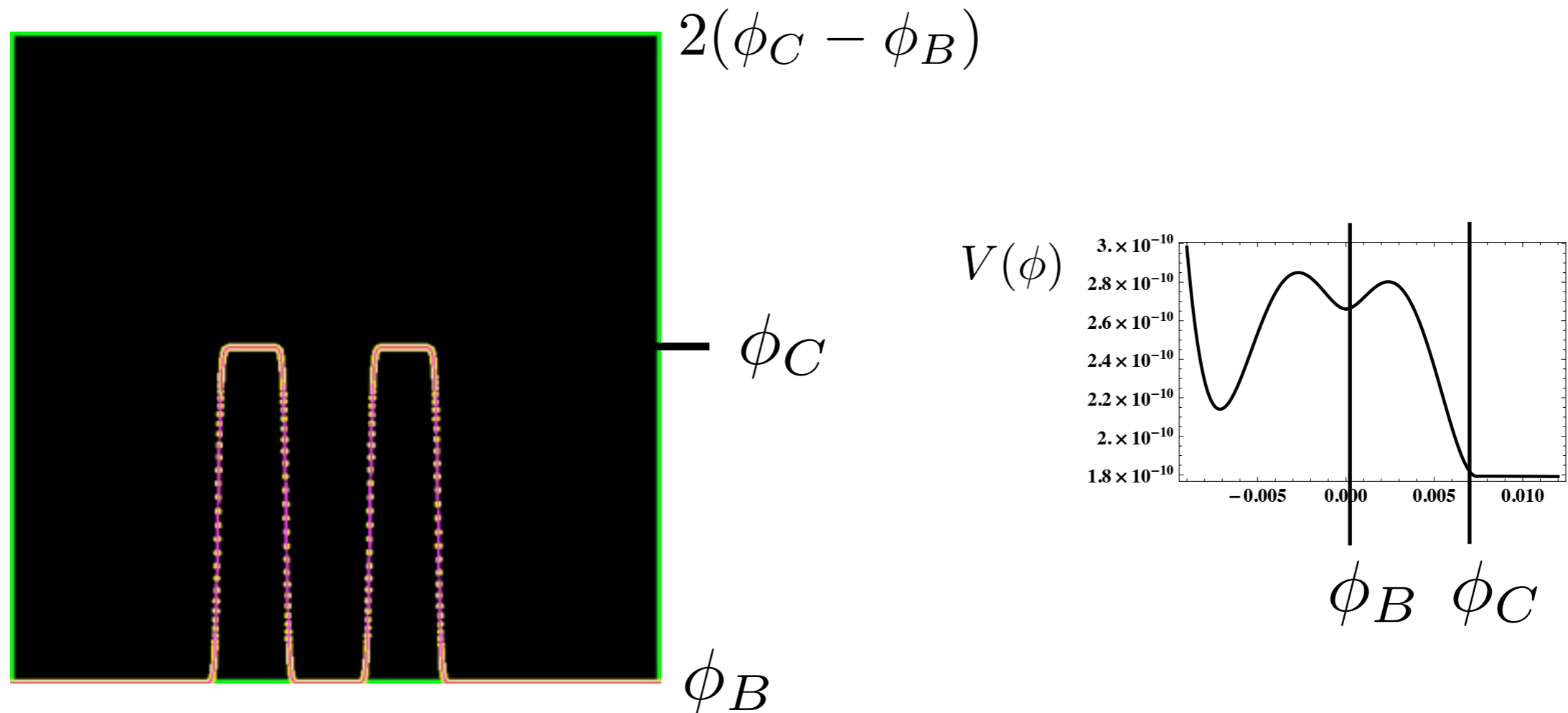
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Numerical solutions

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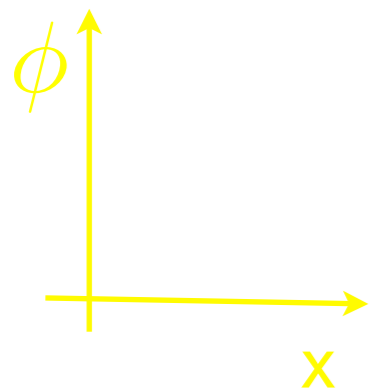
Numerical solutions

- Colliding different bubbles.

ϕ_C



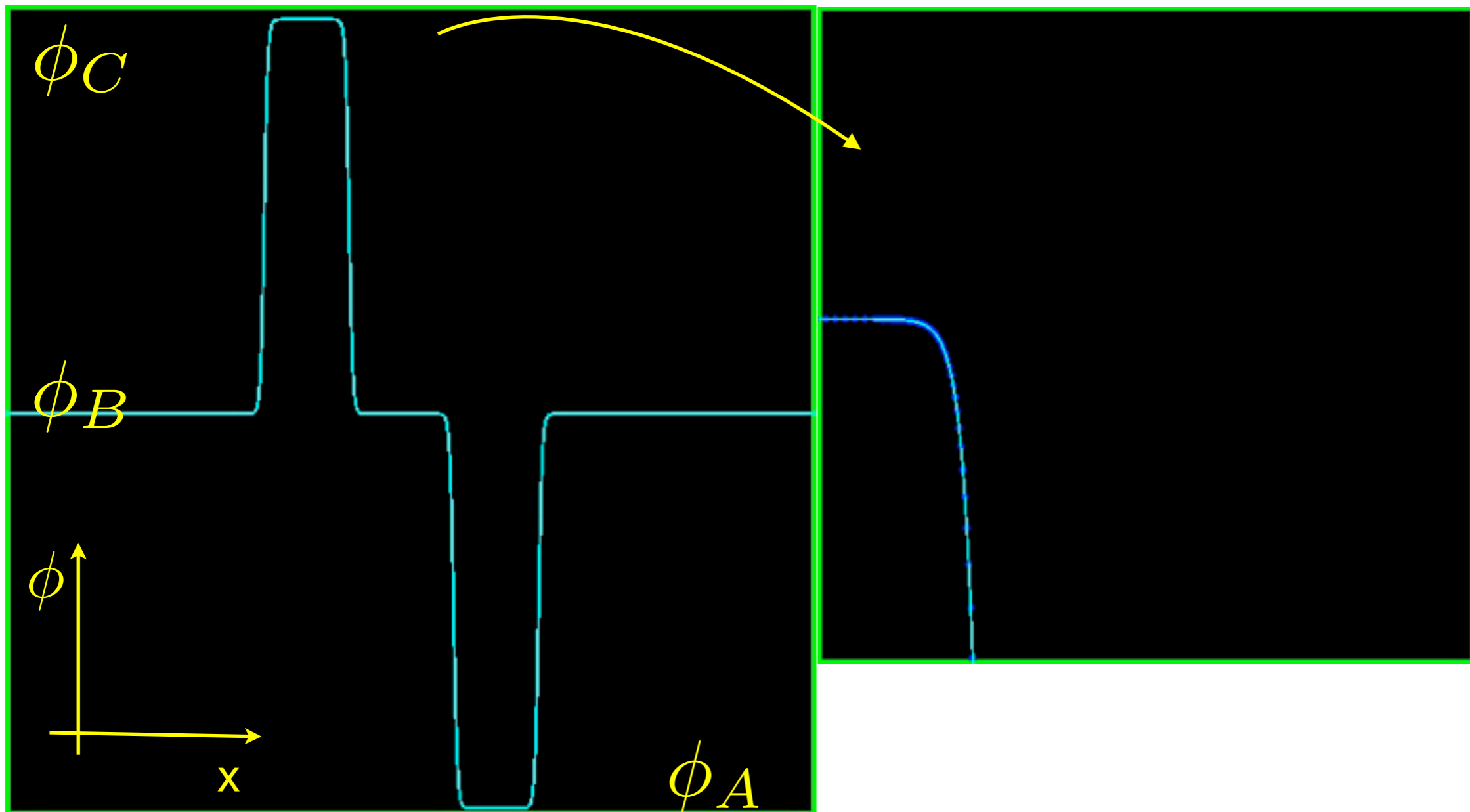
ϕ_B



ϕ_A

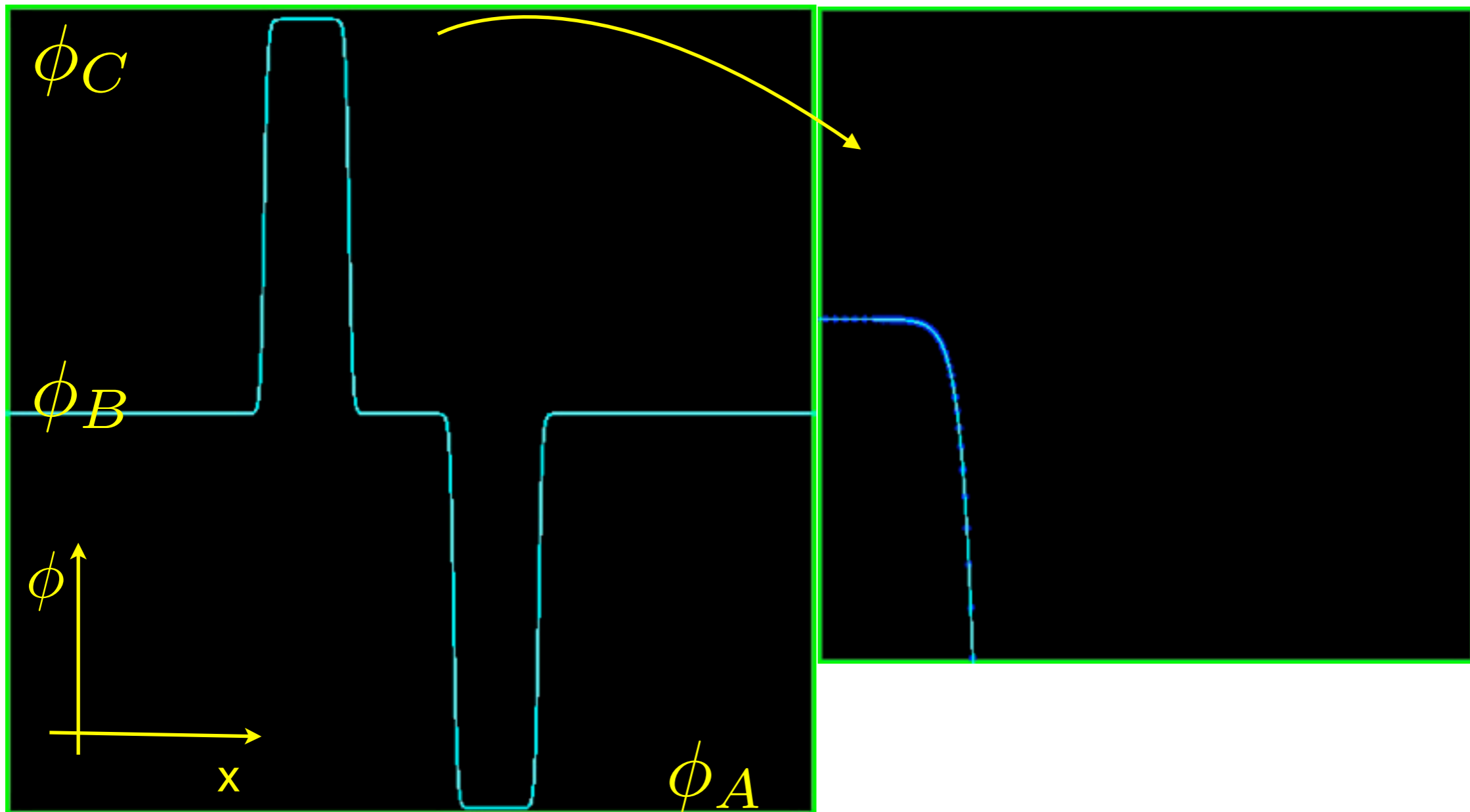
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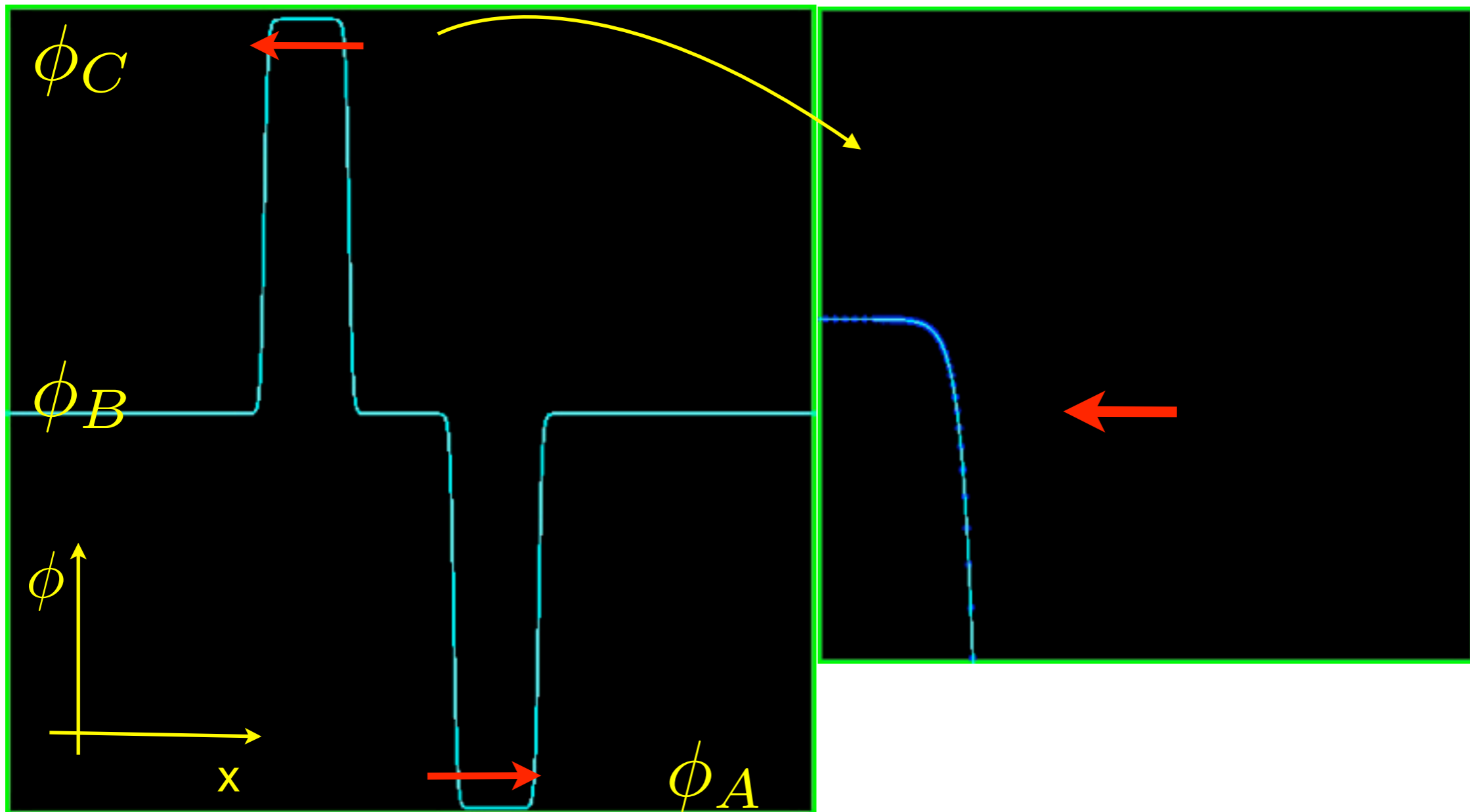
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Numerical solutions

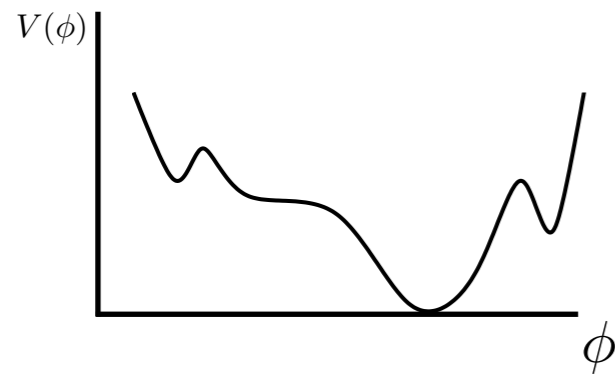
- Colliding different bubbles.



- Inflation does not end, there are new perturbations!

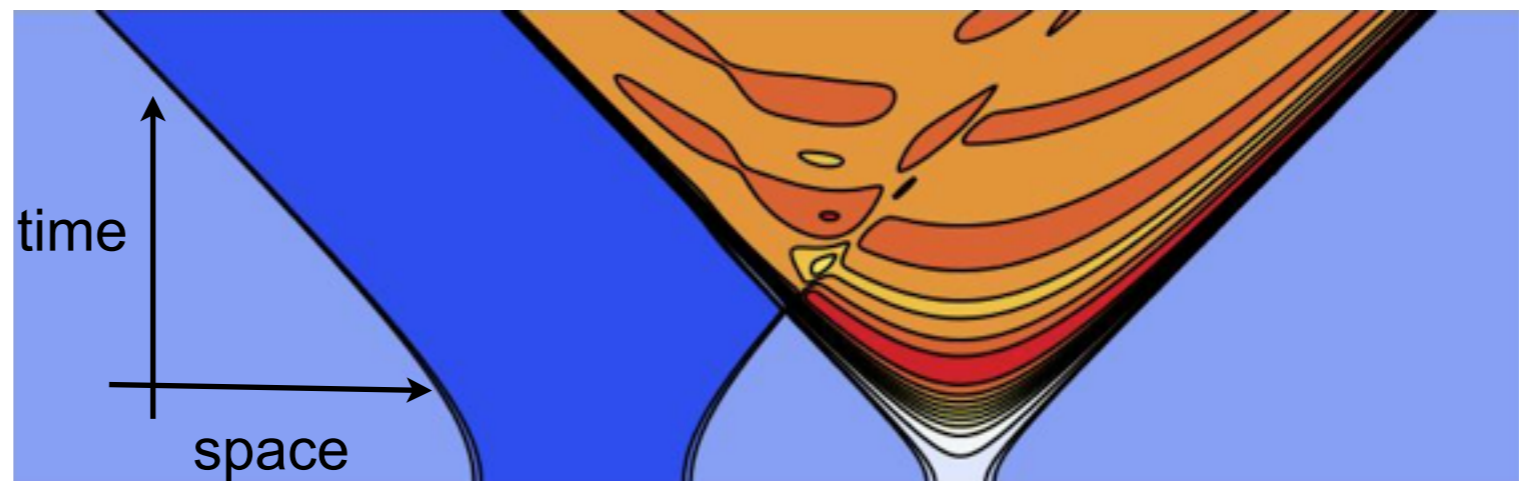
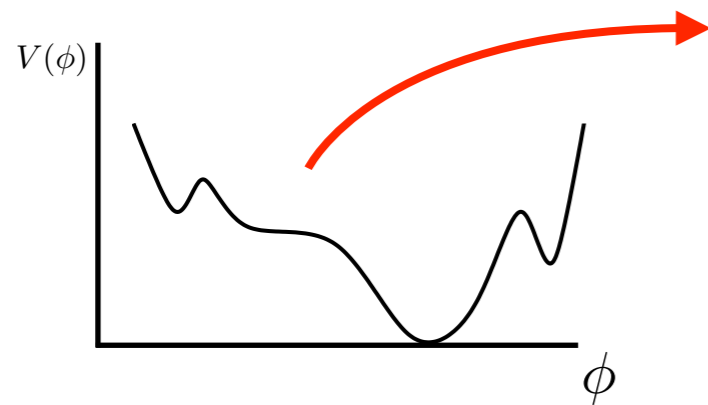
Observational Signatures

- Bubble collisions perturb the epoch of inflation inside our bubble.



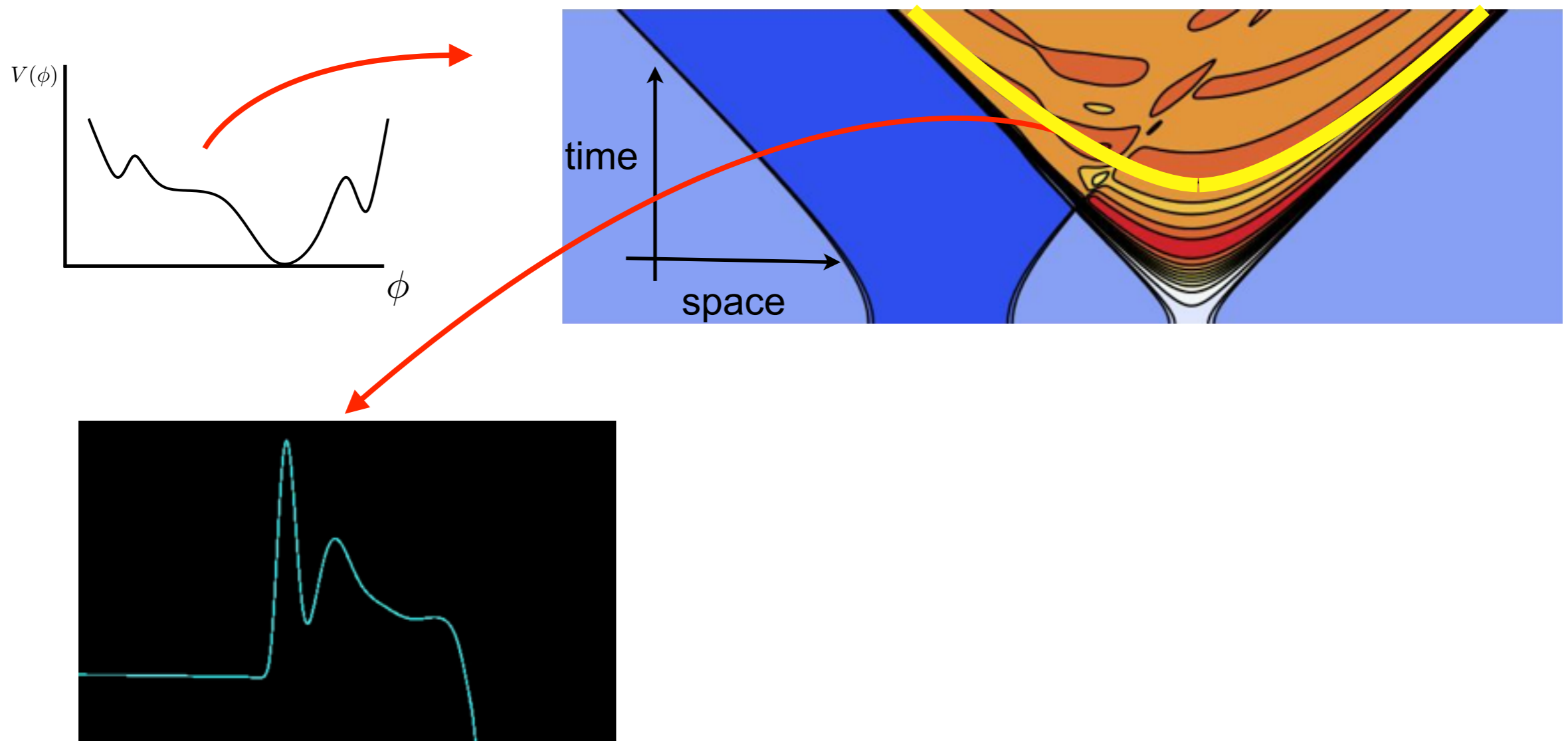
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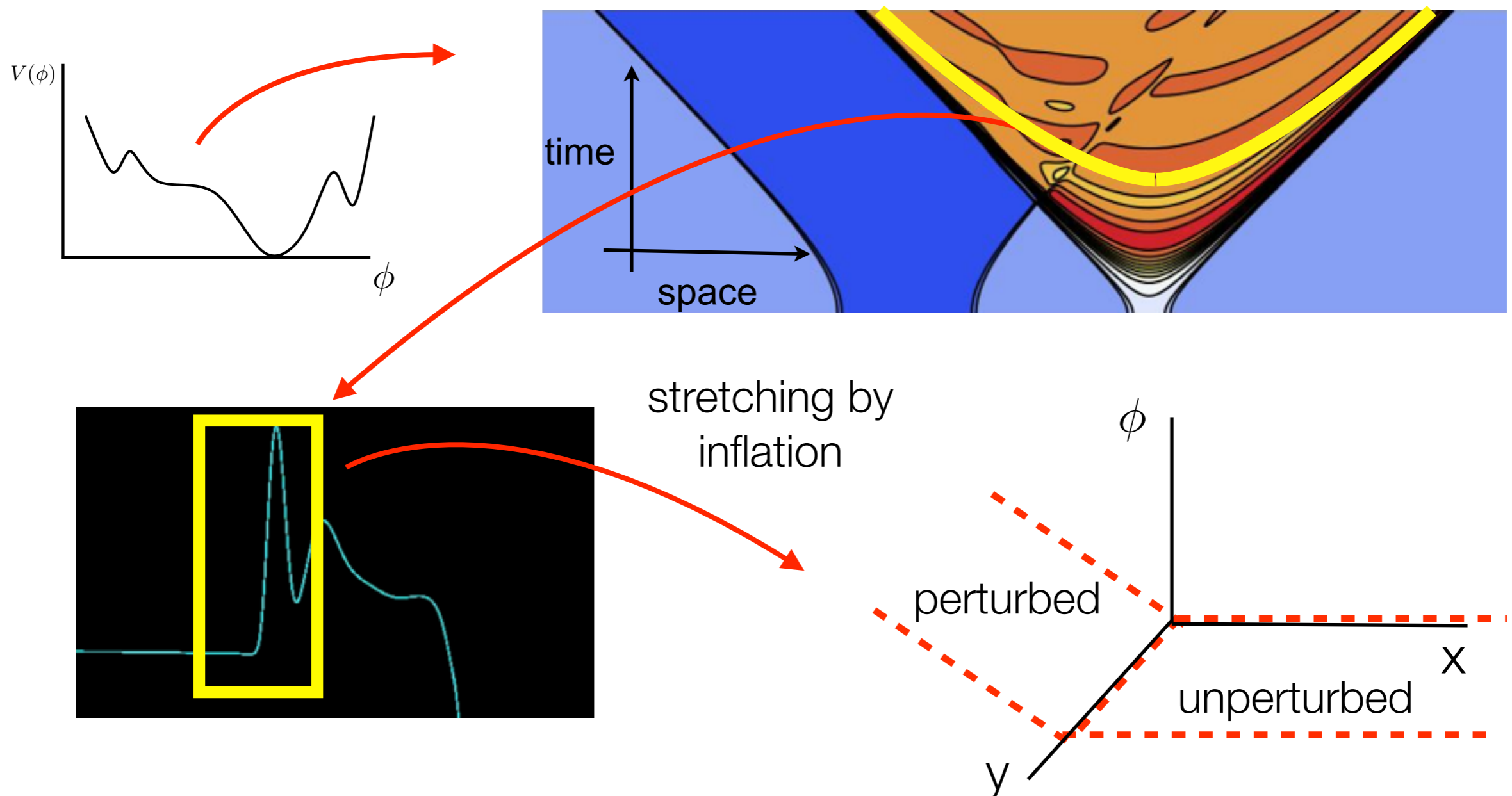
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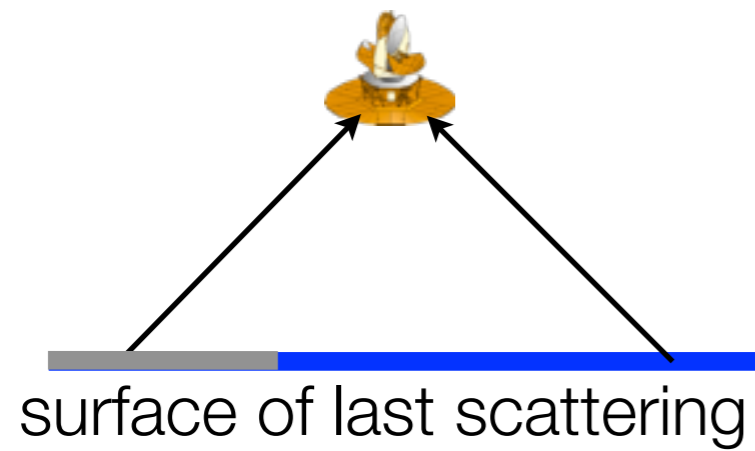


Observational Signatures

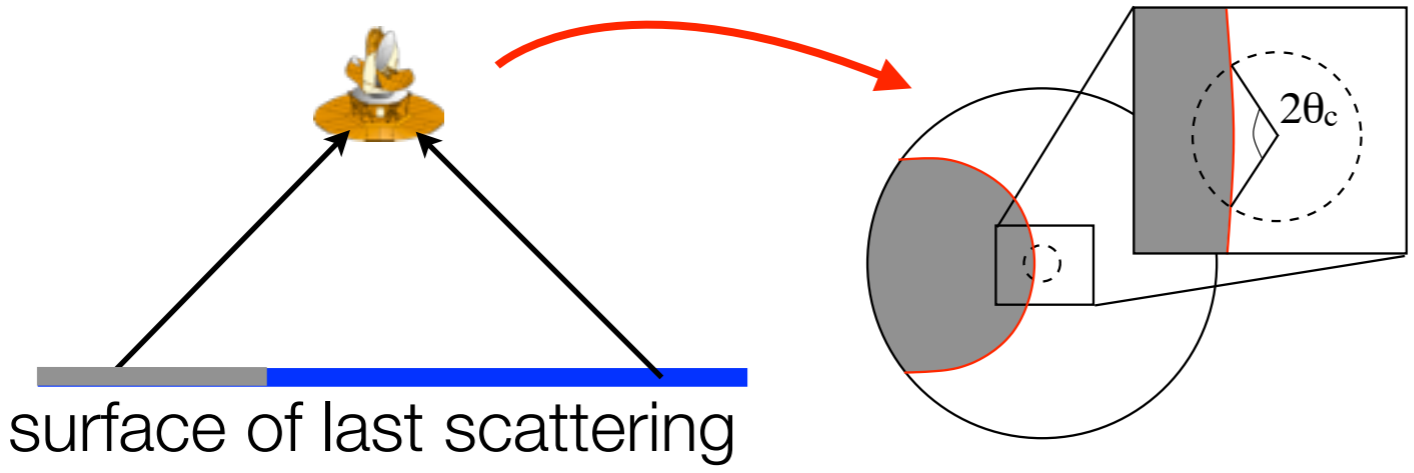
- Bubble collisions perturb the epoch of inflation inside our bubble.



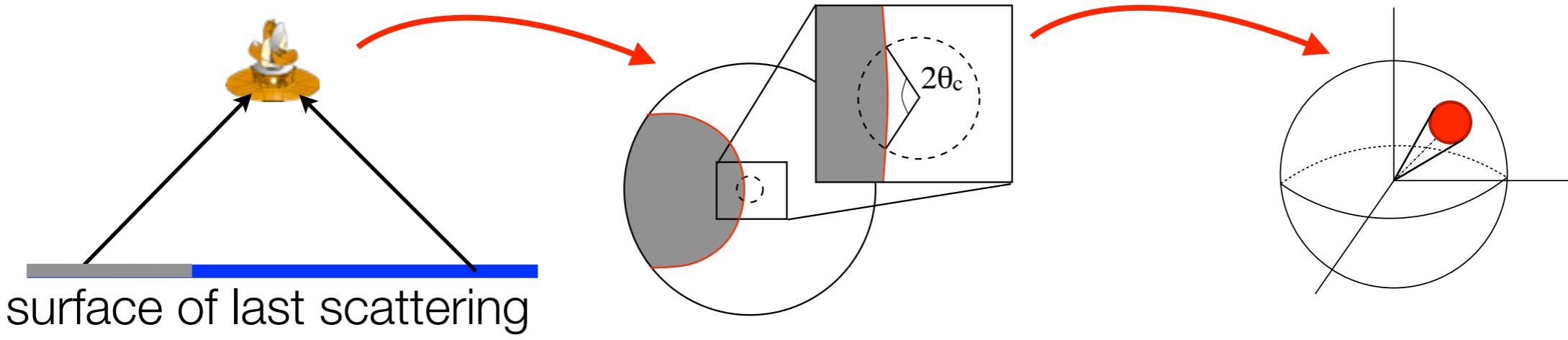
Observational Signatures



Observational Signatures

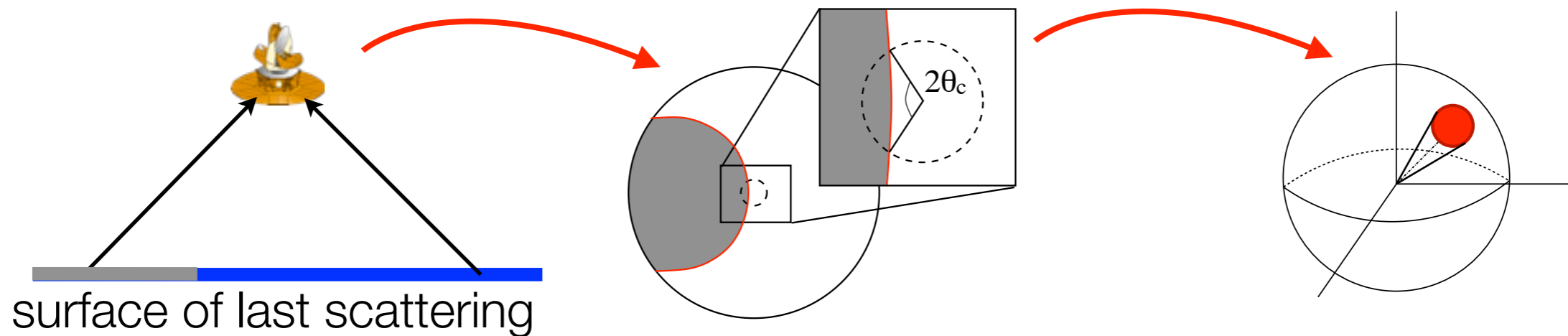


Observational Signatures



Symmetry+causality: effects confined to a disc.

Observational Signatures



Symmetry+causality: effects confined to a disc.

- Generic signature (thanks inflation!):

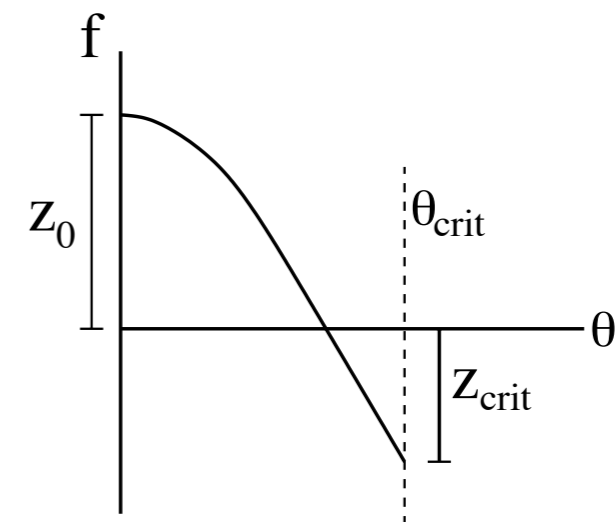
$$\frac{\Delta T(\hat{\mathbf{n}})}{T} \simeq f(\hat{\mathbf{n}}) + \delta_{\Lambda CDM}(\hat{\mathbf{n}})$$

f : analytic arguments and numerics

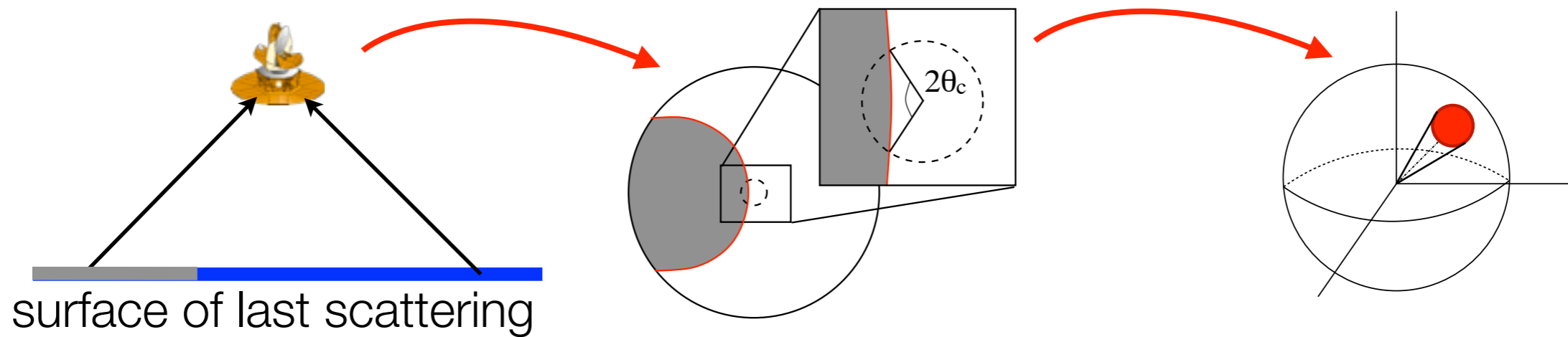
Feeney, MCJ, Mortlock, Peiris

Chang, Kleban, Levi

Gobetti & Kleban

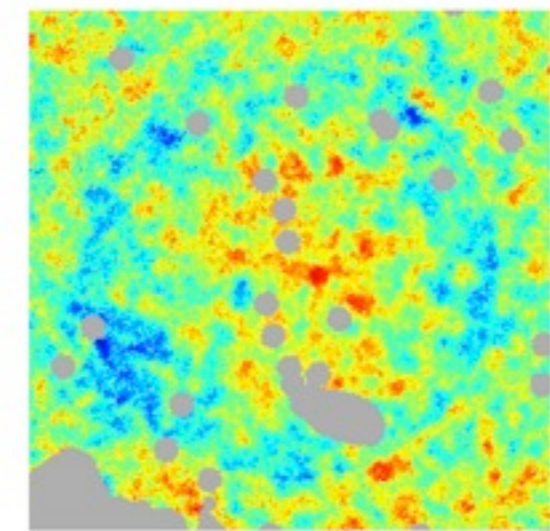
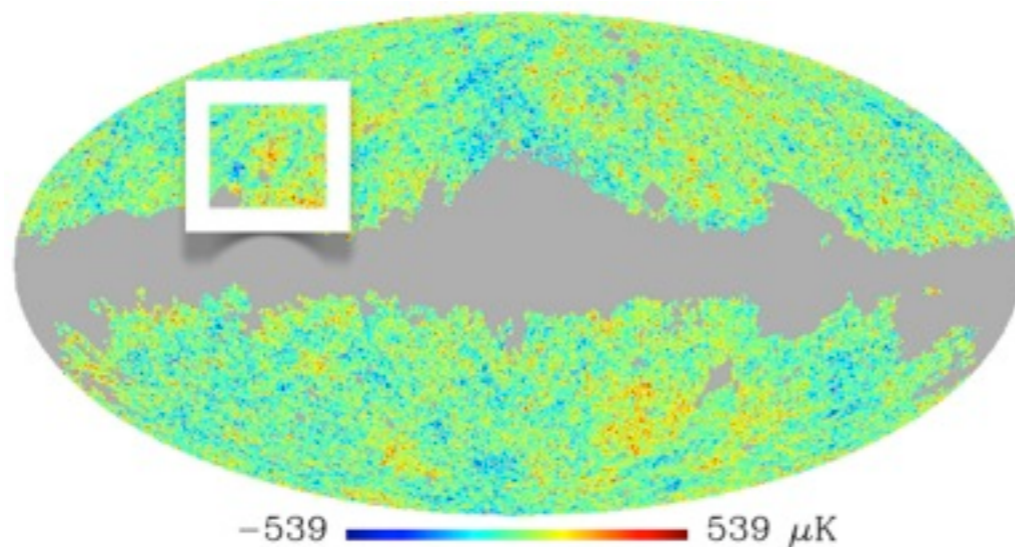


Observational Signatures



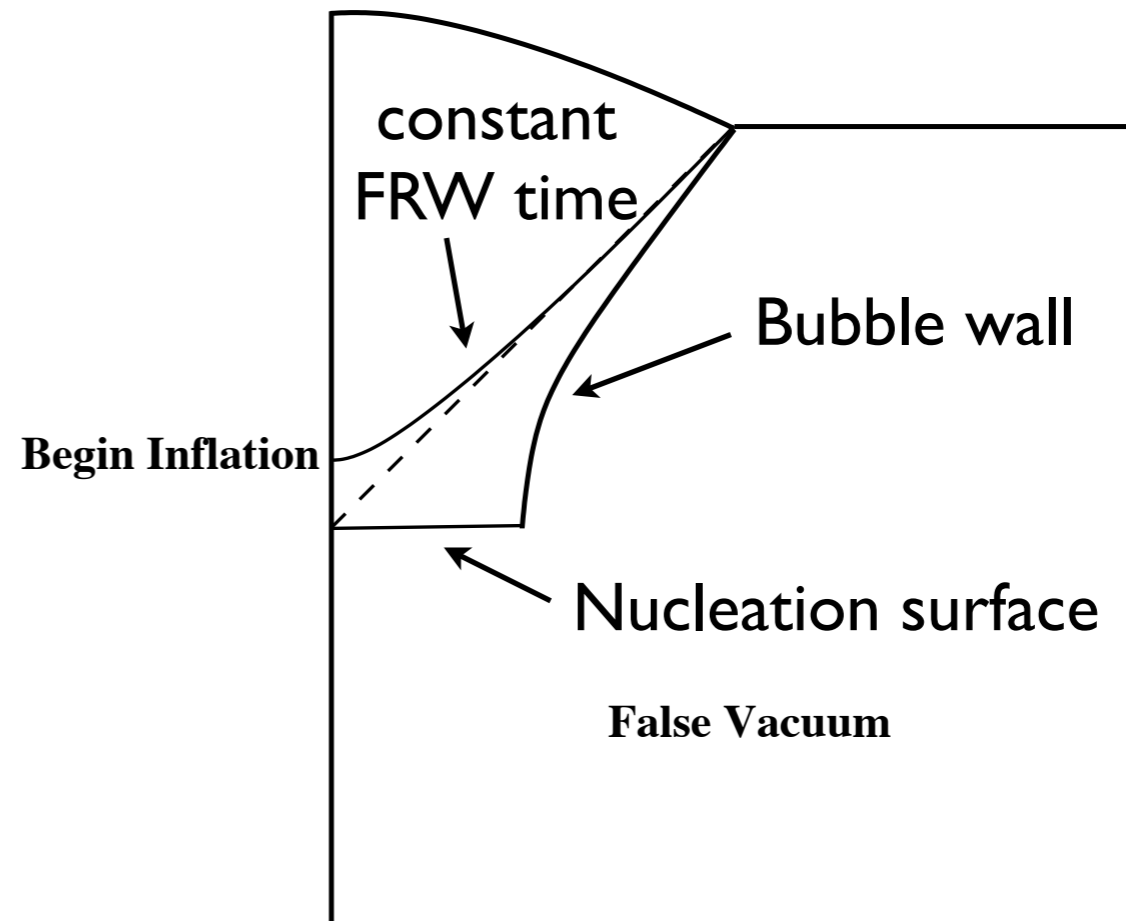
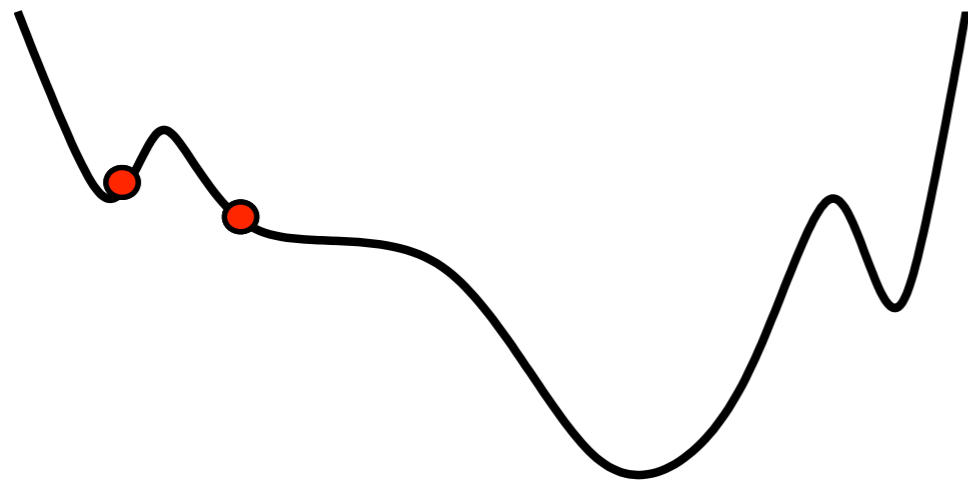
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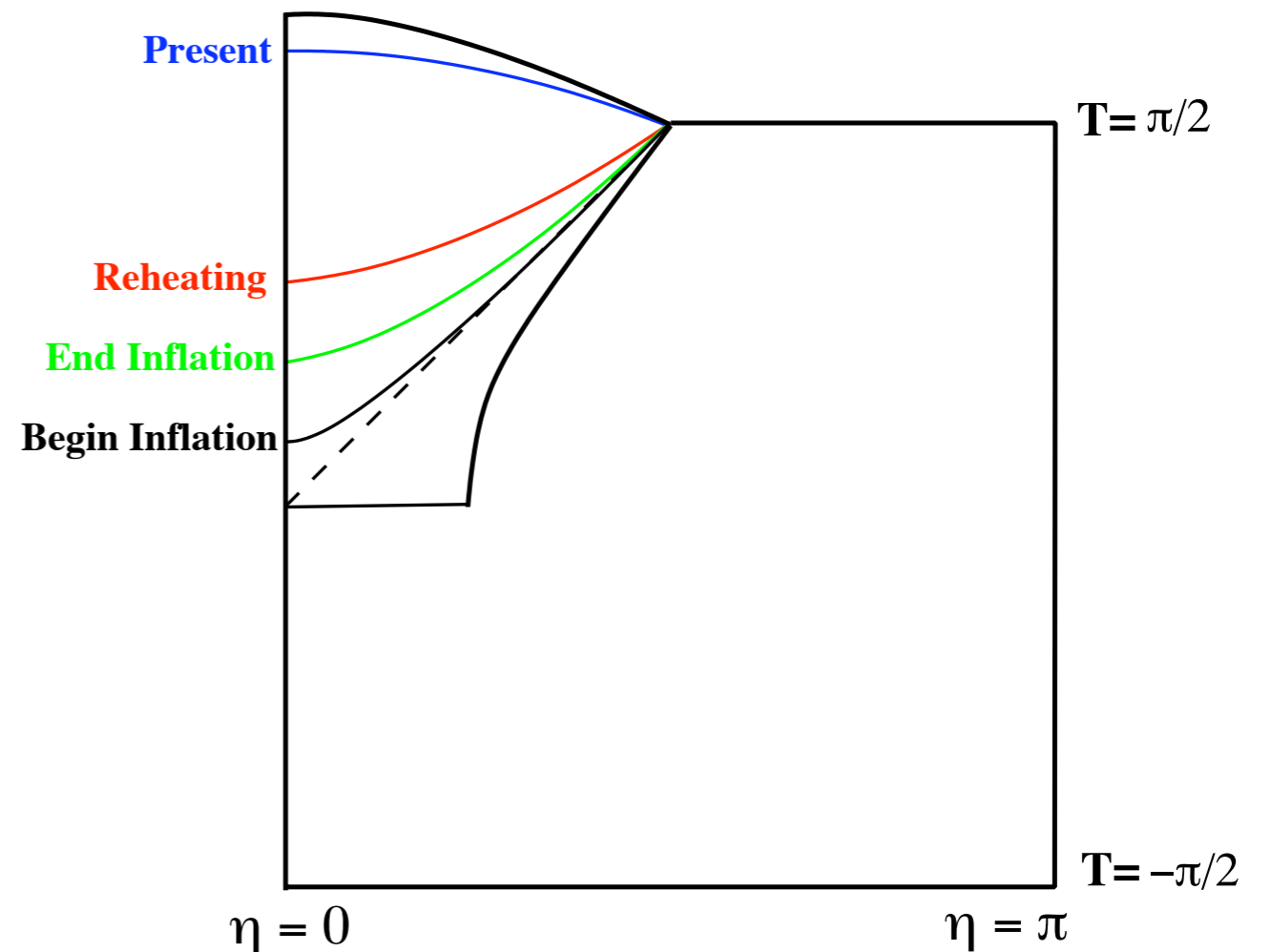
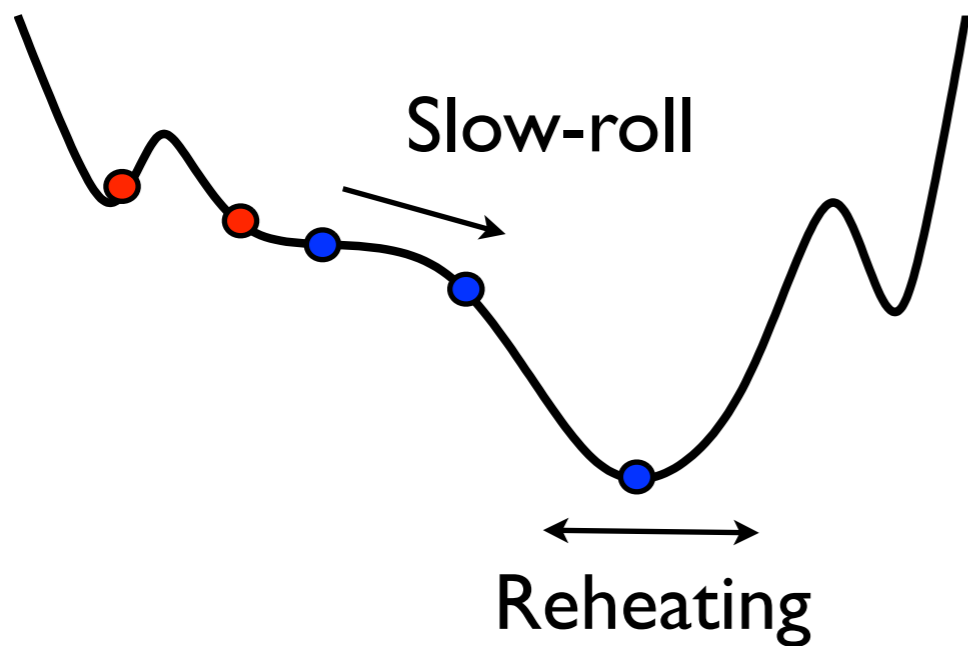
Counting collisions

- How many collisions are there?



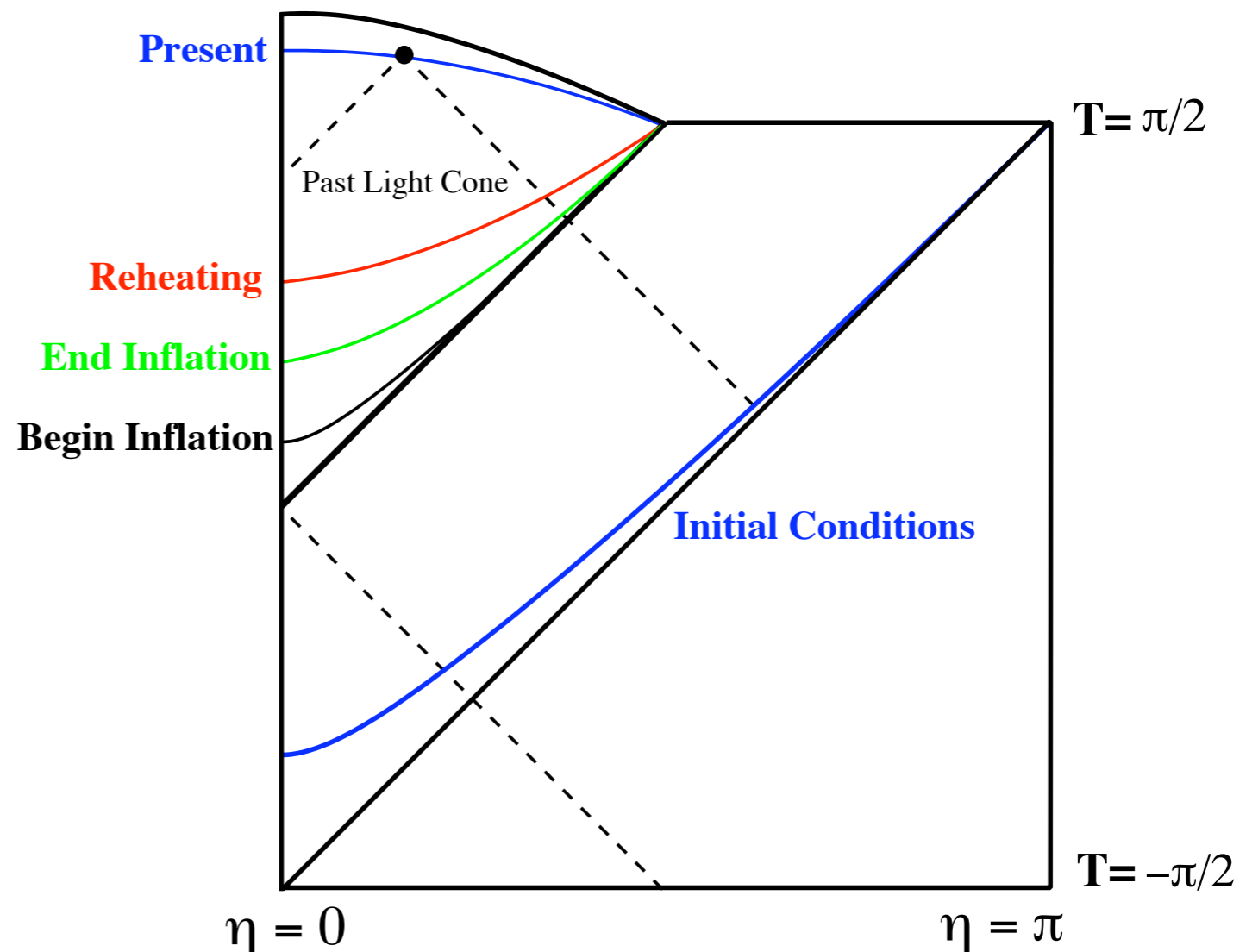
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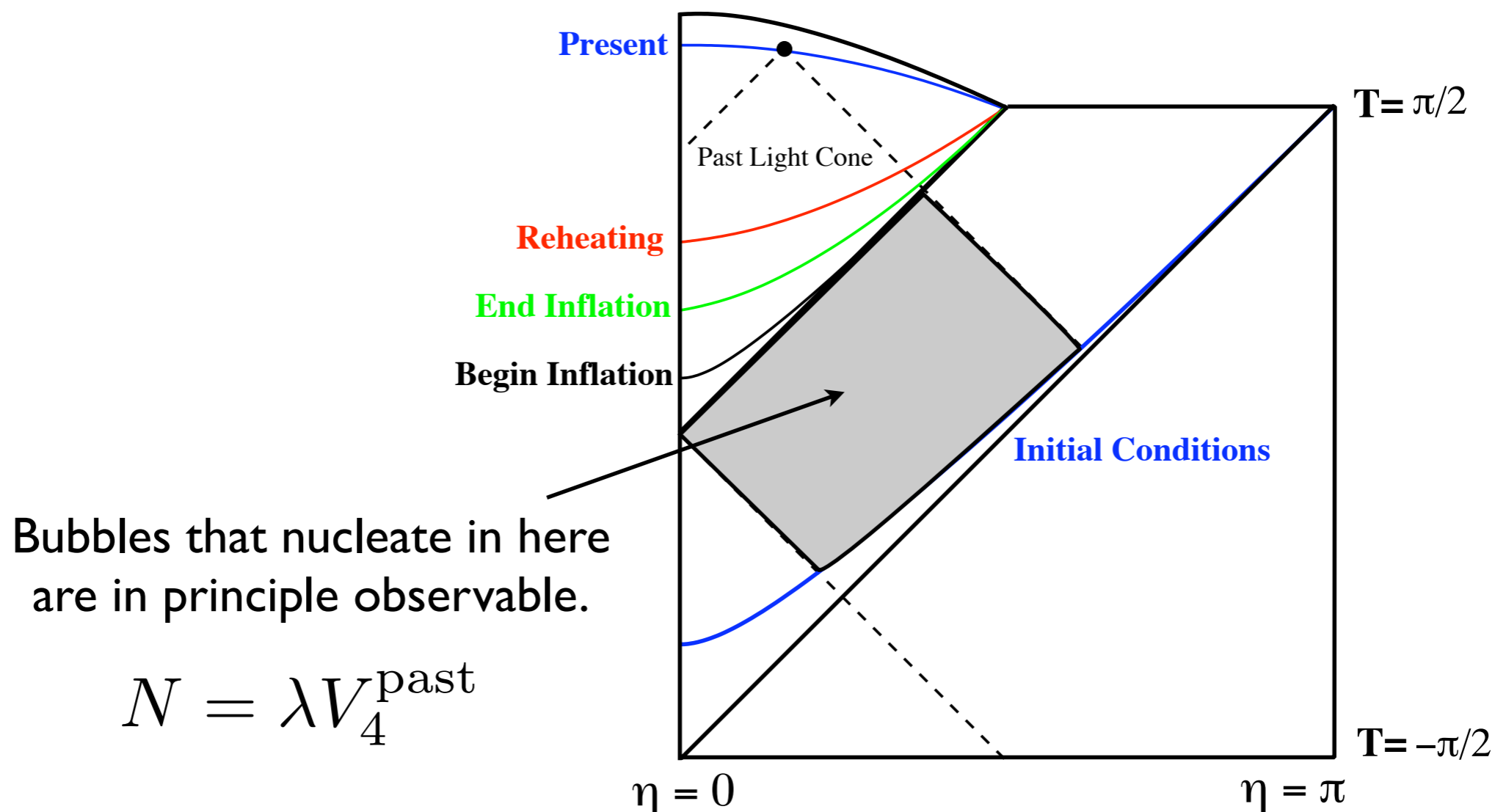
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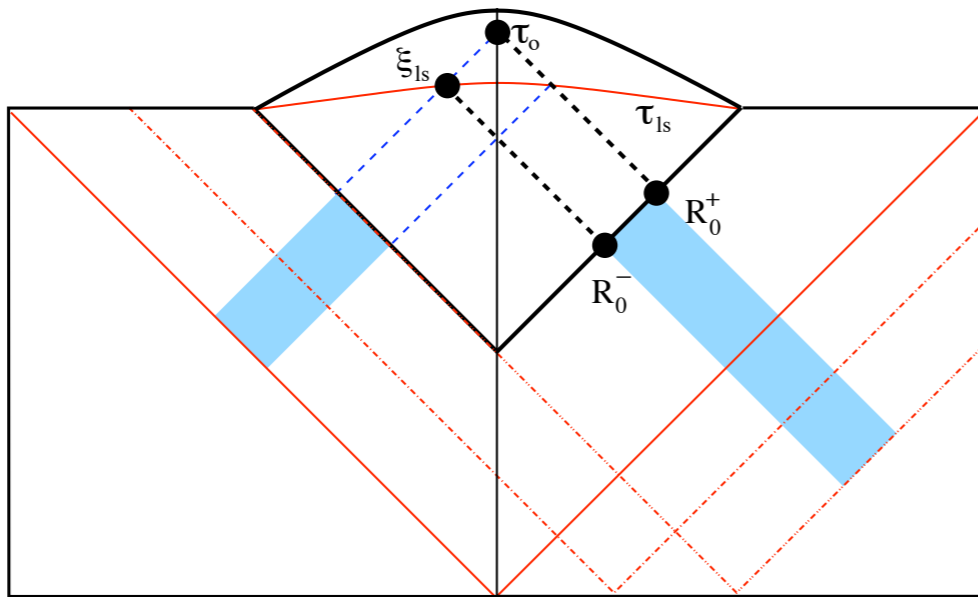
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Counting collisions

- Counting only collisions whose disc of influence is smaller than the whole sky:

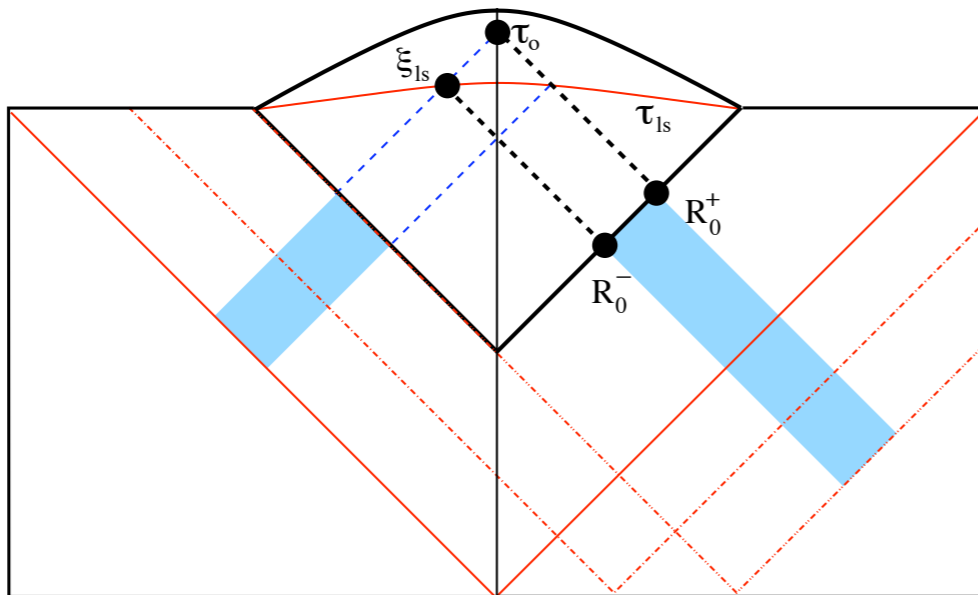


$$N \simeq \frac{16\pi\lambda}{3H_F^4} \left(\frac{H_F^2}{H_I^2} \right) \sqrt{\Omega_c}$$

also Kleban et. al.

Counting collisions

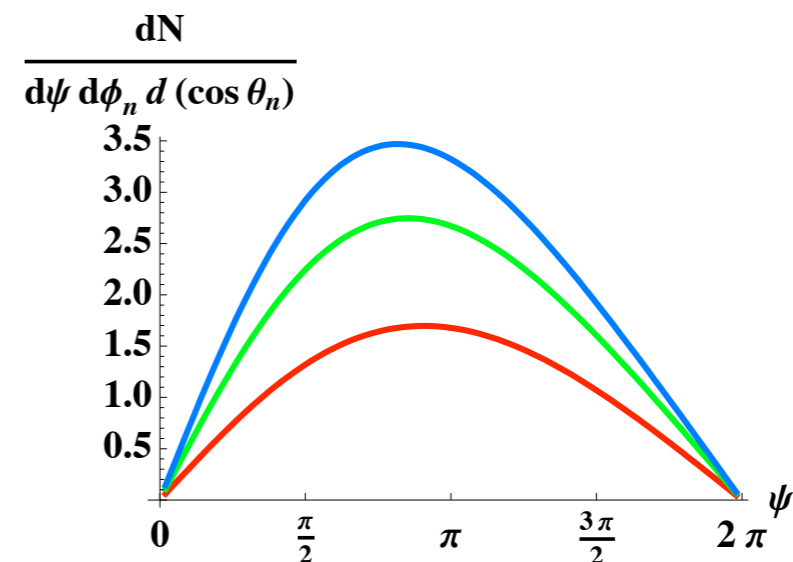
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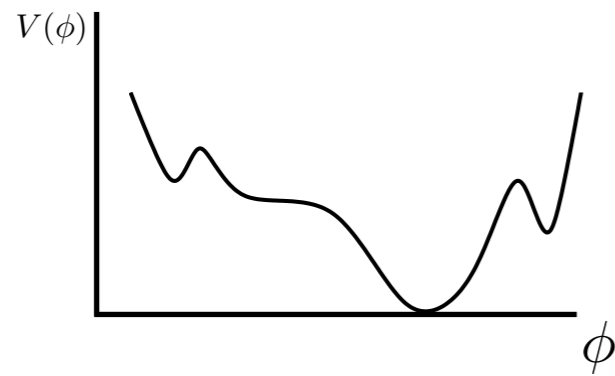
also Kleban et. al.

- The collisions are very nearly isotropic, and the distribution of disc sizes on the CMB sky relatively flat:



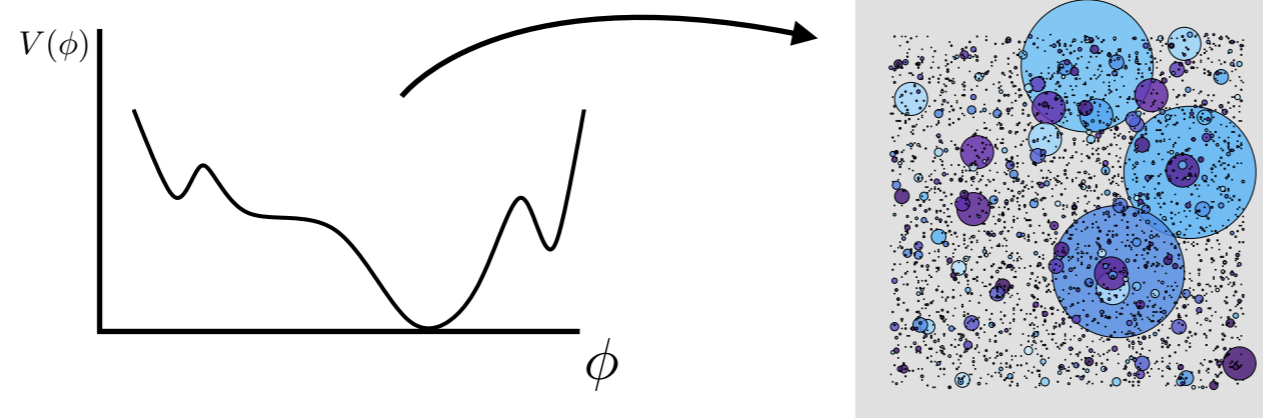
Bubble collisions model

- The model:



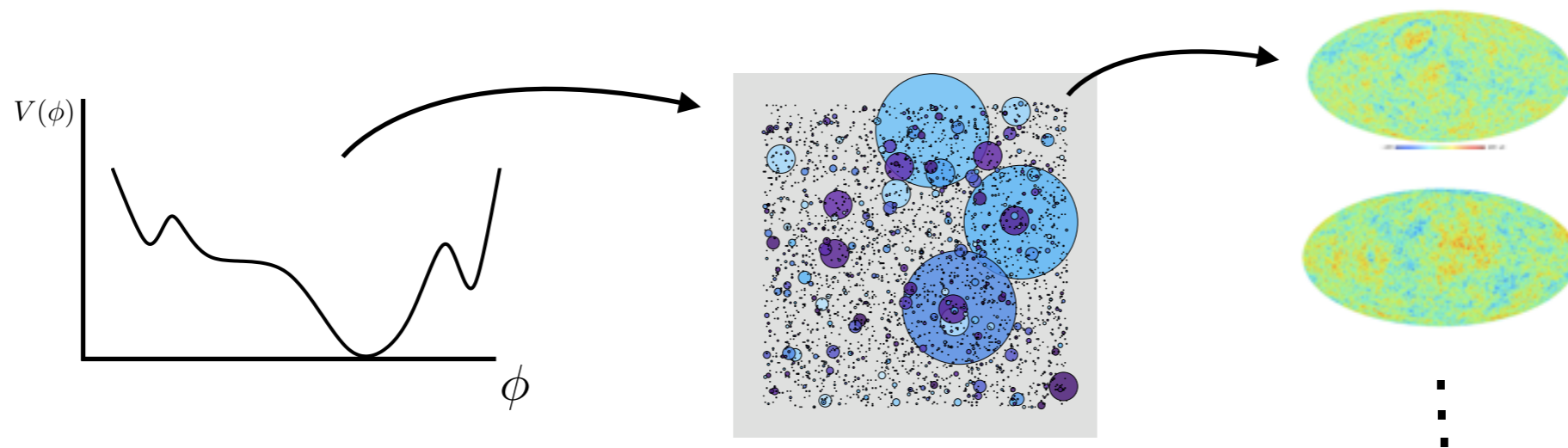
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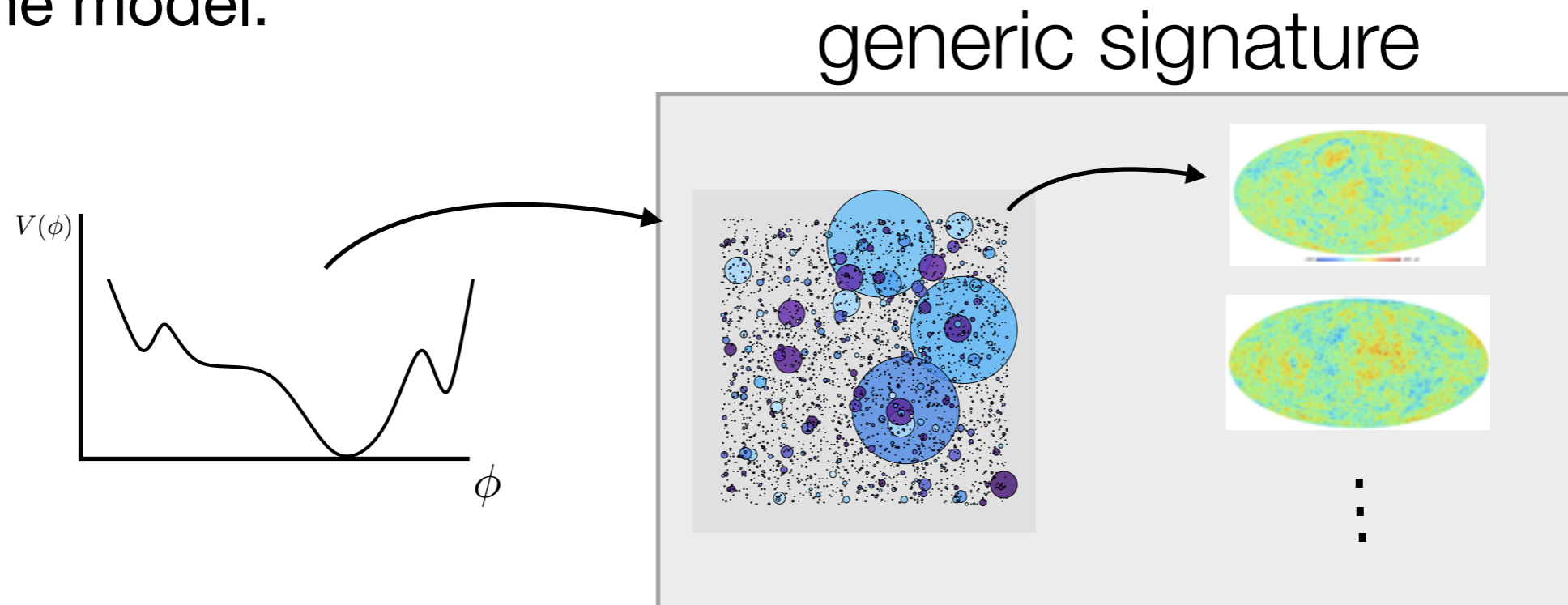
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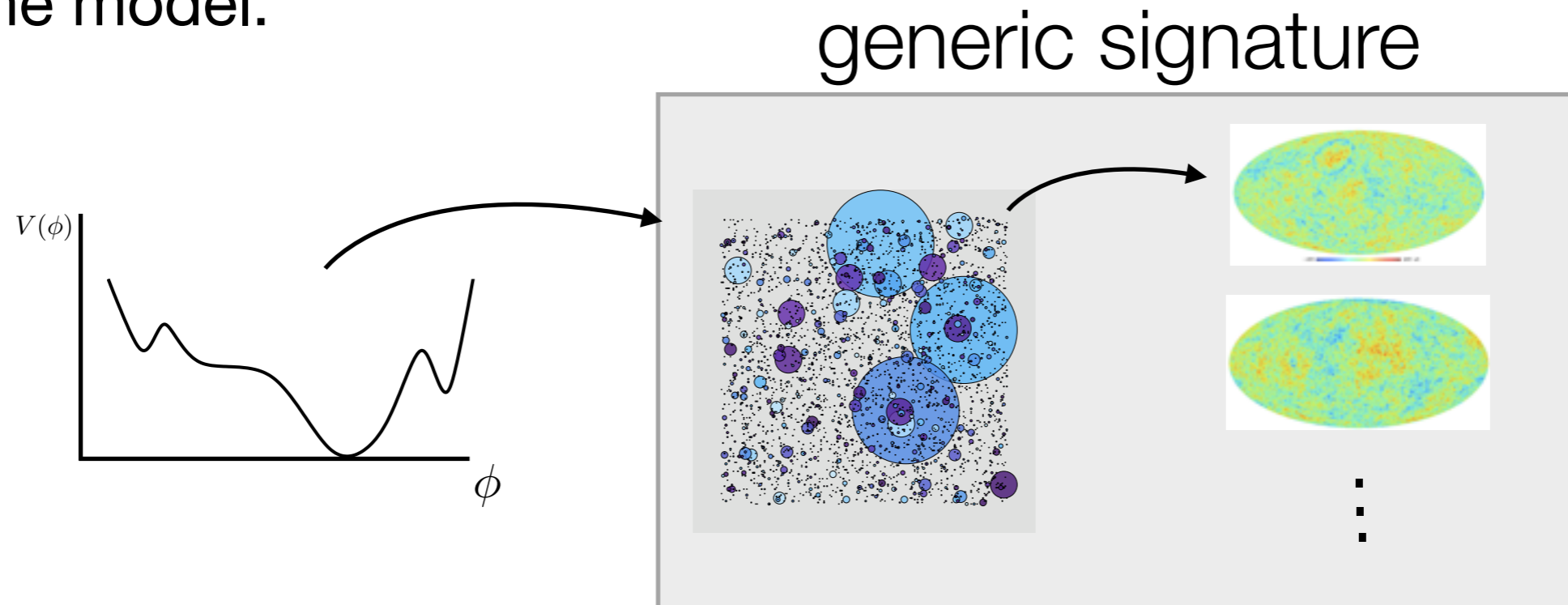
Bubble collisions model

- The model:



Bubble collisions model

- The model:



$$\bar{N}_s$$

expected number of collisions

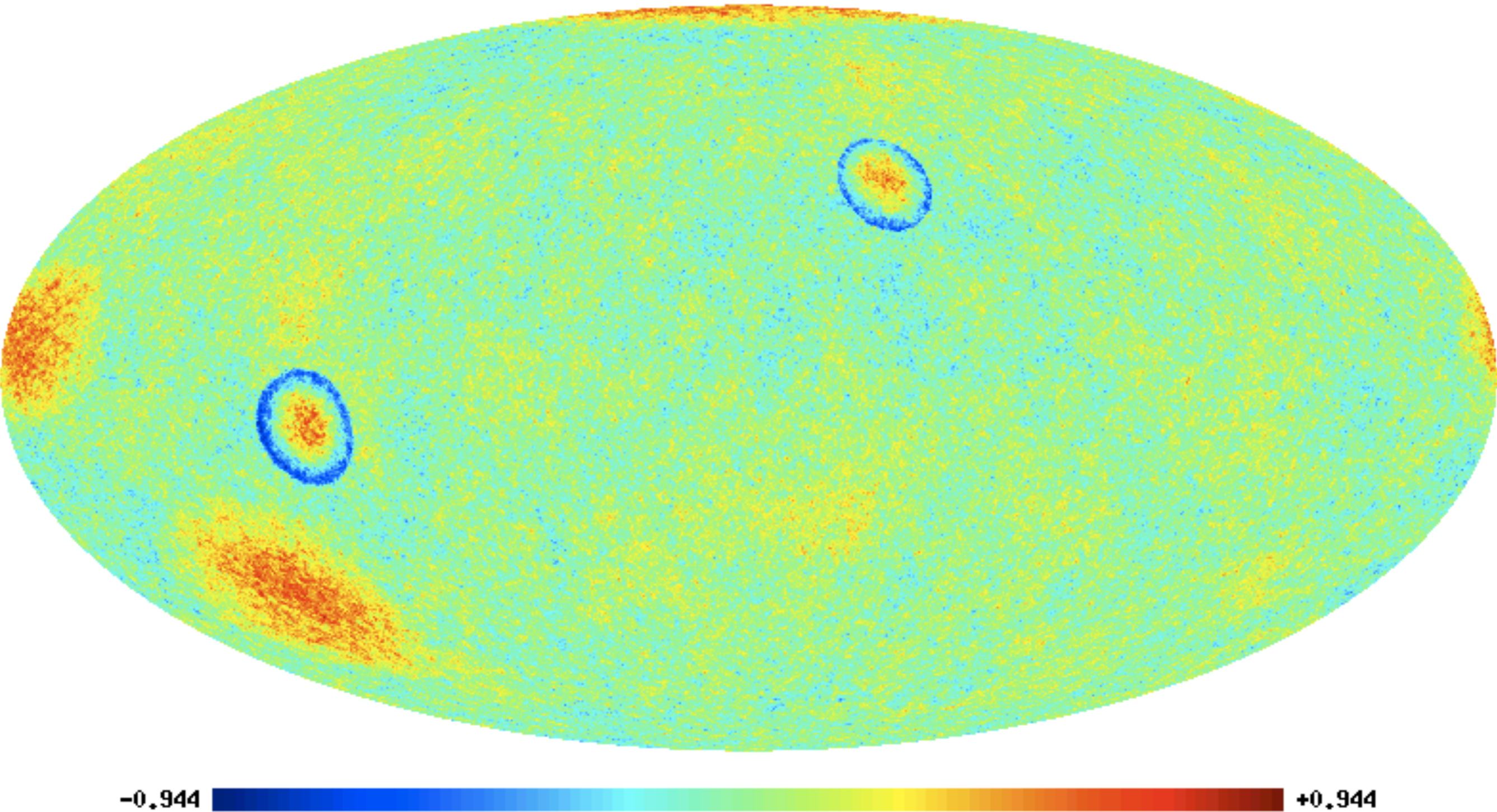
$$\mathbf{m}$$

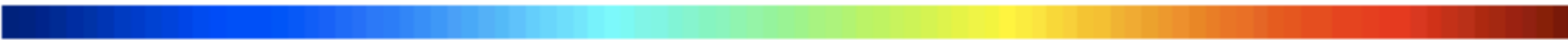
parameters characterizing each collision

$$\text{Pr}(N_s, \mathbf{m})$$

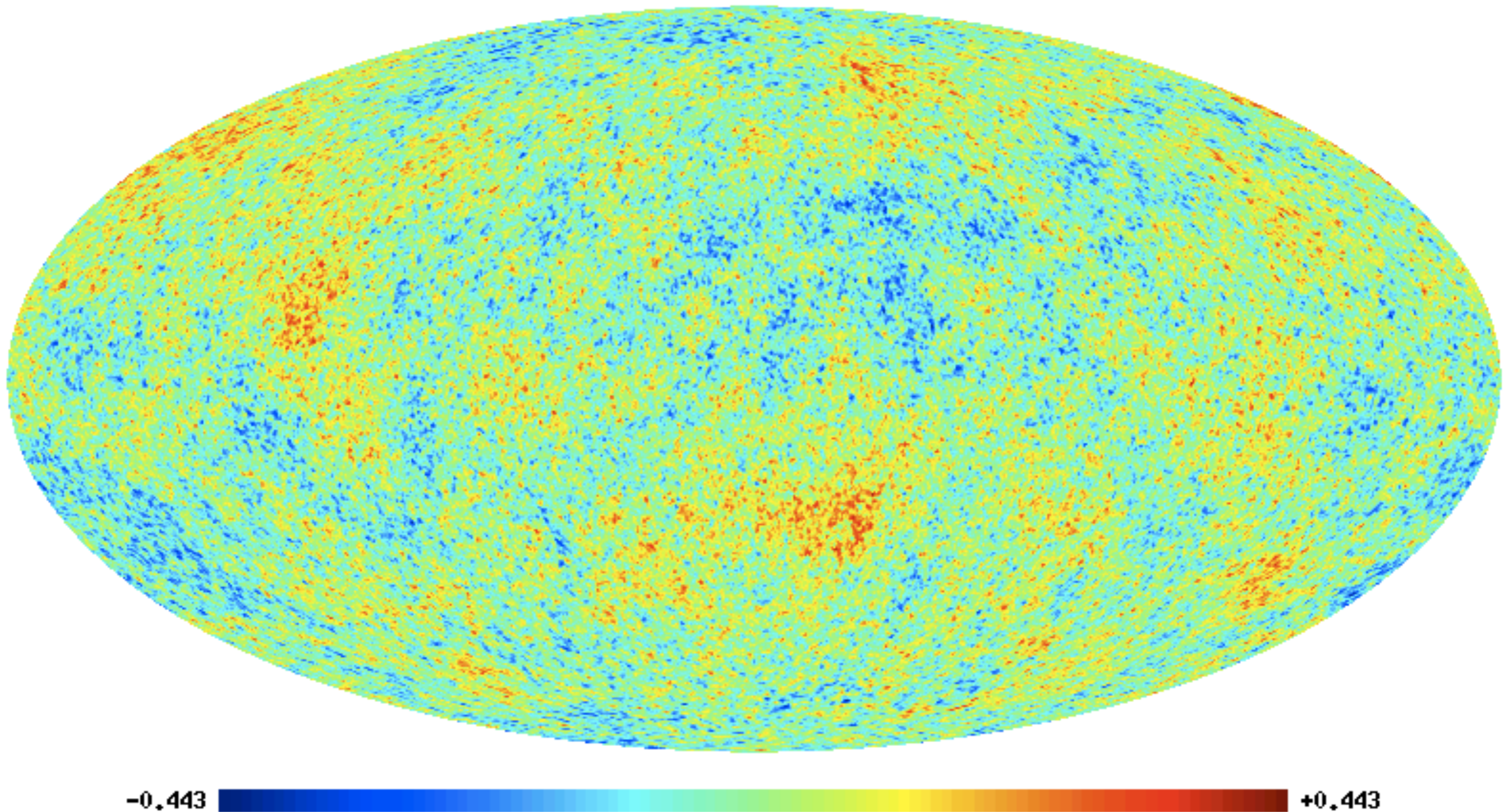
How many of each type do I expect to find?

Collisions (exaggerated) + CMB + instrumental noise



-0.944  +0.944

Collisions (realistic) + CMB + instrumental noise



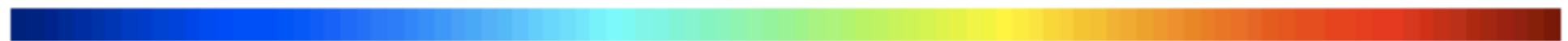
-0.443

+0.443

Collisions (realistic) + CMB + instrumental noise

Does the data prefer a theory with collisions?

-0.443

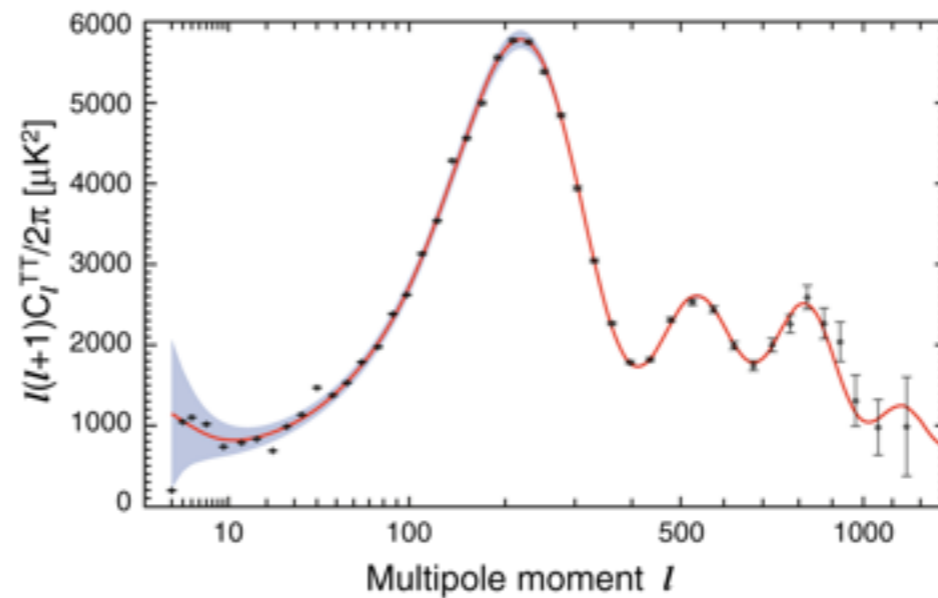
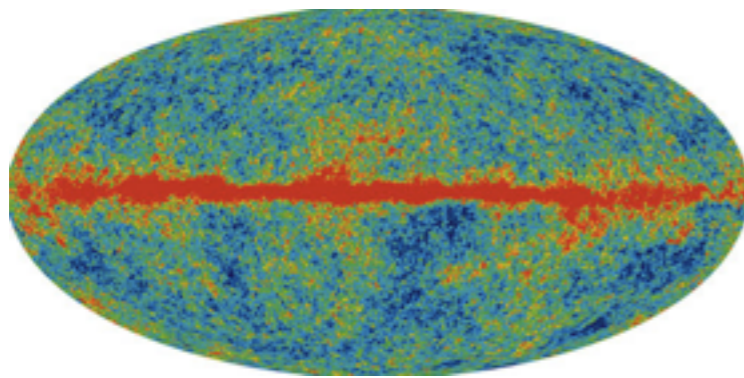


+0.443

Searching for collisions

Feeney, MCJ, Mortlock, Peiris

- Lambda-CDM: very successful at describing the CMB power spectrum.

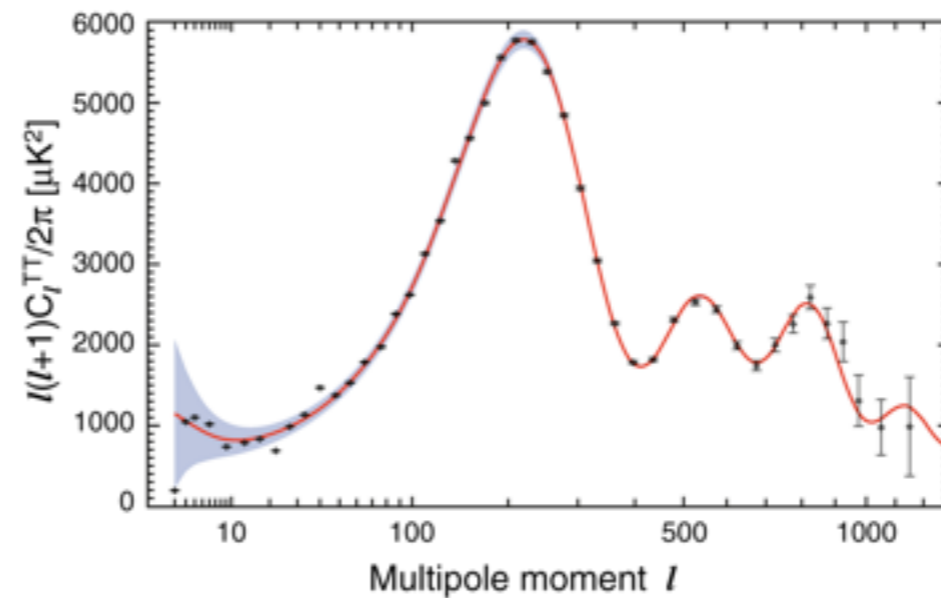
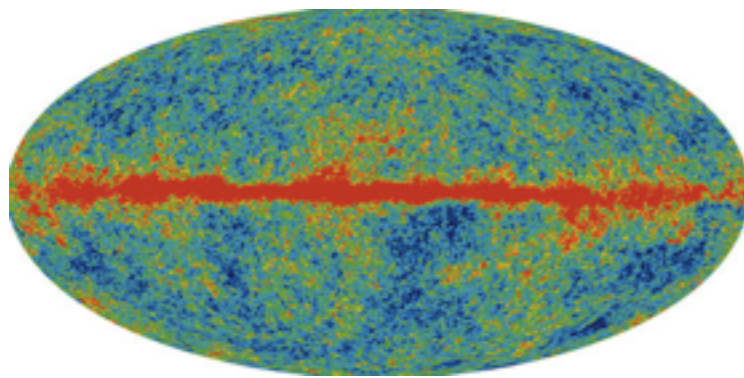


WMAP 7-year
data

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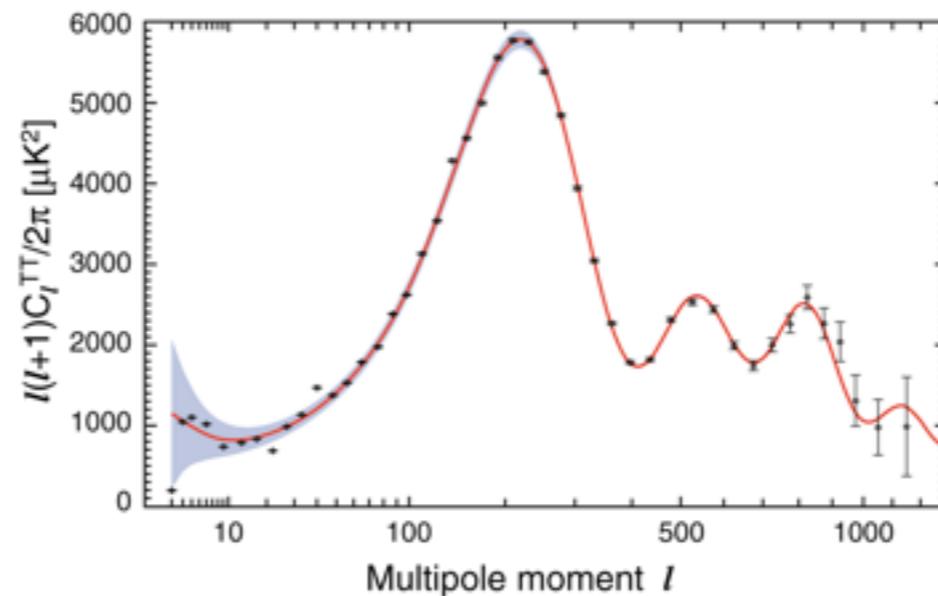
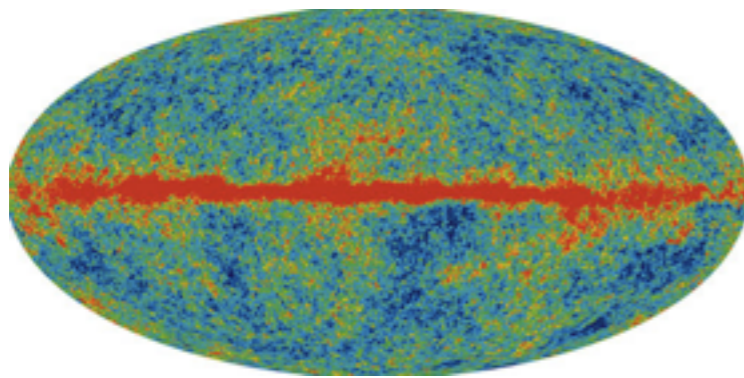
WMAP 7-year data

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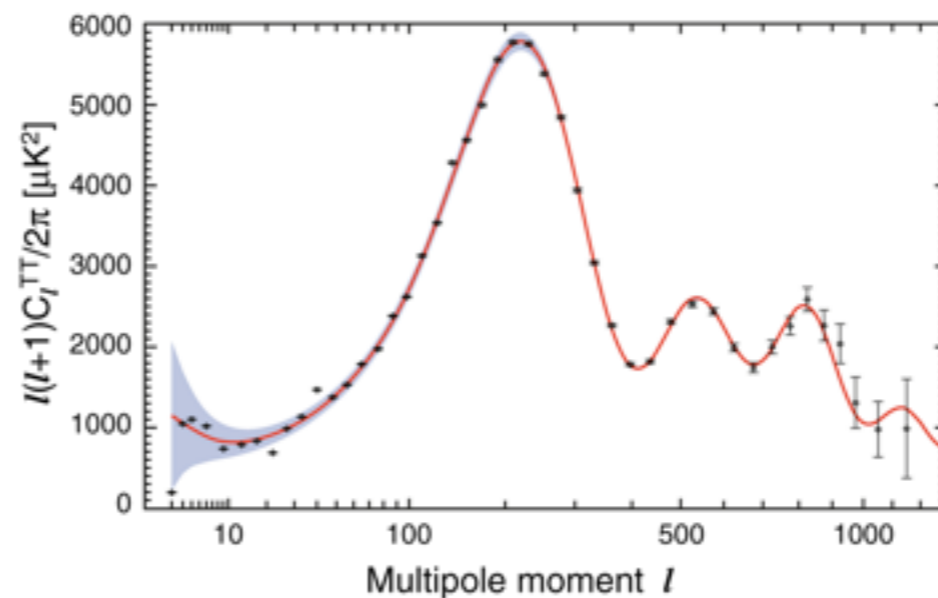
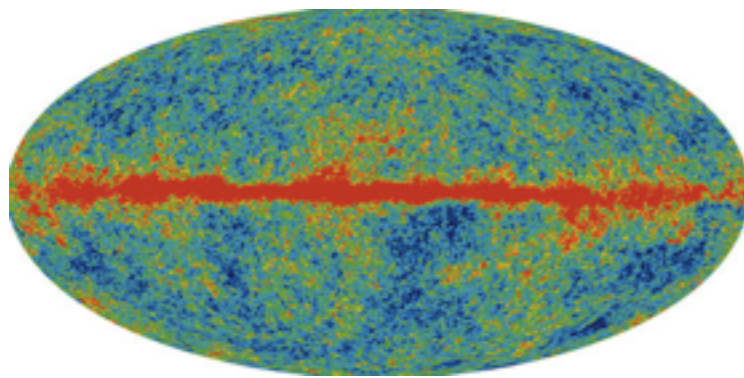
WMAP 7-year data

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WMAP 7-year
data

- Are there anomalies?
- Frequentist statistics: how discrepant is the data assuming the null hypothesis?
- Bayesian model selection: does one model fit the data better than another?

Bayesian statistics

- The goal: $P(\text{Model}, \Theta \mid \text{data})$



How should I bet?

Bayesian statistics

- The goal: $P(\text{Model}, \Theta \mid \text{data})$



How should I bet?

- Bayes' Theorem:

$$P(\text{Model}, \Theta \mid \text{data}) = \frac{P(\Theta)P(\text{data} \mid \text{Model}, \Theta)}{P(\text{data} \mid \text{Model})}$$

Bayesian statistics

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- Theory prior: $P(\Theta) \quad \int P(\Theta)d\Theta = 1$

- Likelihood: $P(\text{data} \mid \text{Model}, \Theta)$

- Evidence (model averaged likelihood): $P(\text{data} \mid \text{Model})$

$$P(\text{data} \mid \text{Model}) = \int d\Theta P(\Theta)P(\text{data} \mid \text{Model}, \Theta)$$

Bayesian statistics

- The likelihood is used to quantify how consistent data is with a set of model parameters.

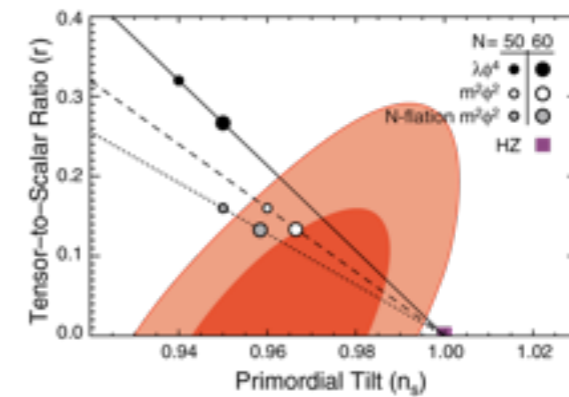
$$P(\text{data} \mid \text{Model}, \Theta)$$

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→
exclusion plots

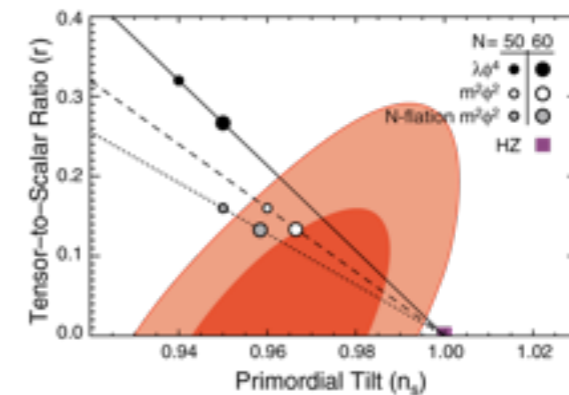


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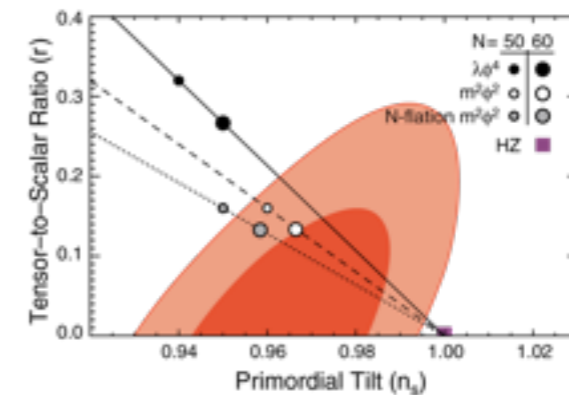
- This does NOT tell us how we should rank competing theories trying to describe the same data.

Bayesian statistics

- The likelihood is used to quantify how consistent data is with a set of model parameters.

$$P(\text{data} \mid \text{Model}, \Theta)$$

→
exclusion plots



- This does NOT tell us how we should rank competing theories trying to describe the same data.
- To do so, we can apply Bayes' theorem at the level of Models:

$$P(\text{Model} \mid \text{data}) = \frac{P(\text{Model})P(\text{data} \mid \text{Model})}{P(\text{data})}$$

Bayesian model selection

- Let's say I have a model that fits the data fairly well, should I introduce a more complicated model that might fit it even better?

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Bayesian model selection

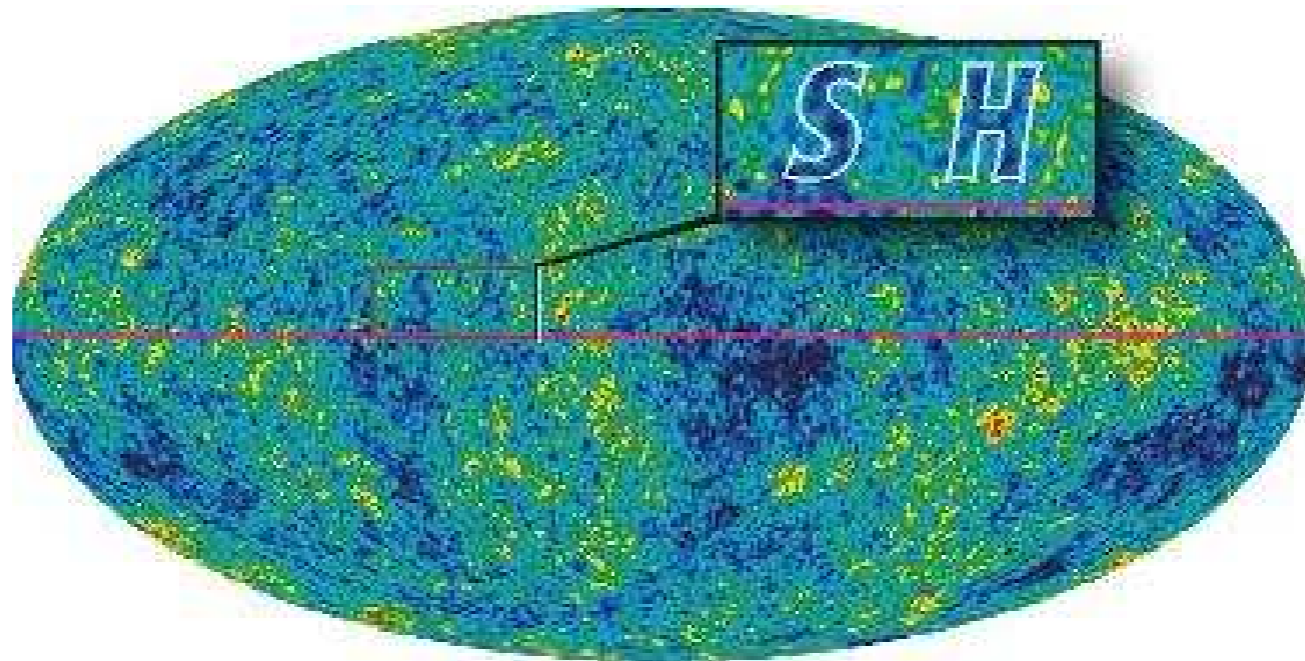
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- The evidence naturally implements Occam's razor: the simpler model should be favored. Tension between volume of parameter space and goodness of fit.

$$P(\text{data} \mid \text{Model}) = \int d\Theta P(\Theta)P(\text{data} \mid \text{Model}, \Theta)$$

Is This Significant?



- Model 1: Lambda CDM.
- Model 2: Stephen Hawking's creation, signed copy.

$$\frac{\Pr(\text{Model 1}|\text{data})}{\Pr(\text{Model 2}|\text{data})} = \frac{\Pr(\text{Model 1}) \Pr(\text{data}|\text{Model 1})}{\Pr(\text{Model 2}) \Pr(\text{data}|\text{Model 2})}$$

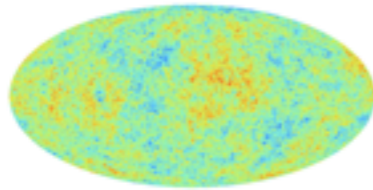
Searching for collisions

- What any good Bayesian wants:

$$\frac{\Pr(\text{Model 1}|\text{Data})}{\Pr(\text{Model 2}|\text{Data})}$$

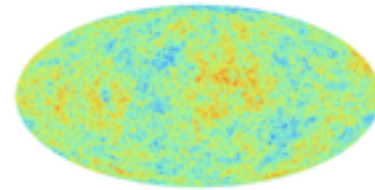


How should I bet?



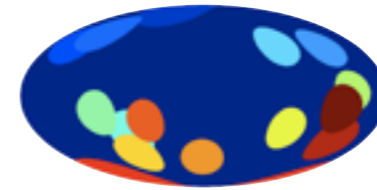
Λ CDM

VS



Λ CDM

+



$\Pr(N_s, \mathbf{m})$

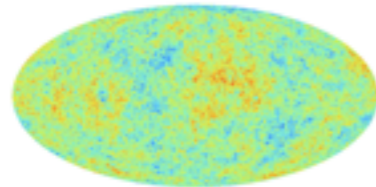
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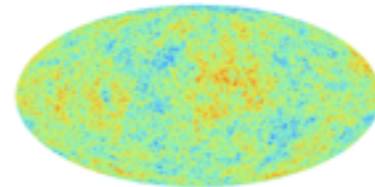


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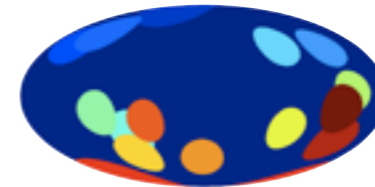
ΛCDM

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ΛCDM

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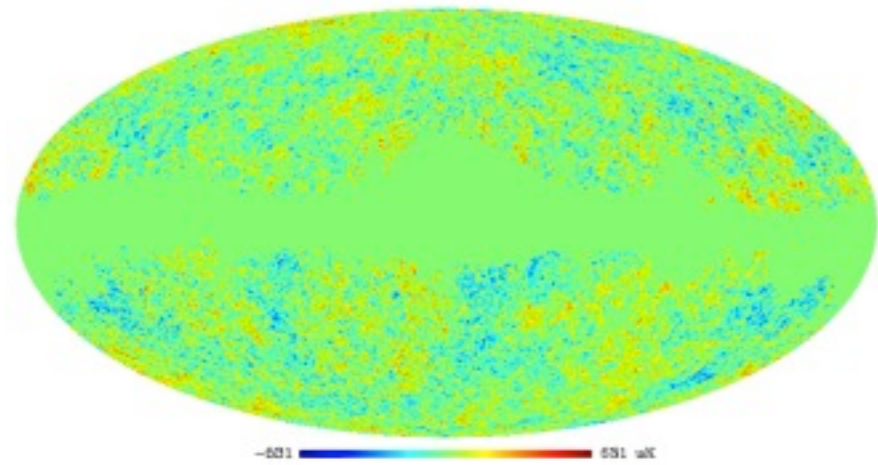


$\Pr(N_s, \mathbf{m})$

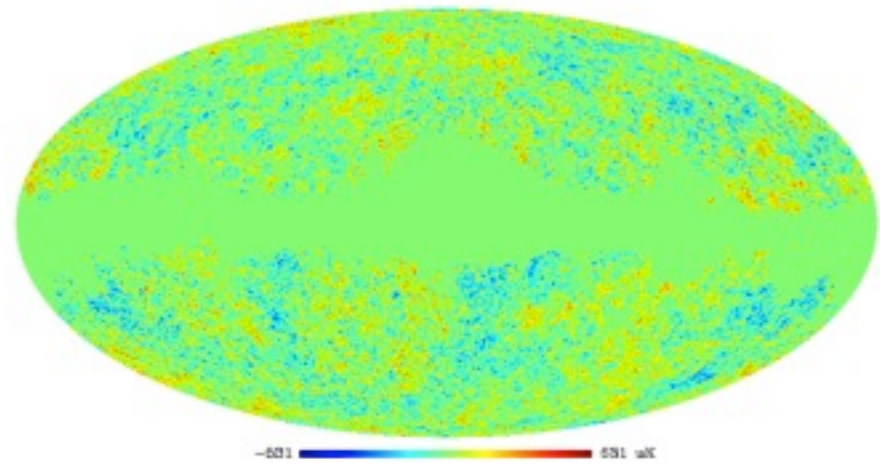
- A convenient theory label: \bar{N}_s . ΛCDM is specified by $\bar{N}_s = 0$.

The expected number of detectable features.

Searching for collisions

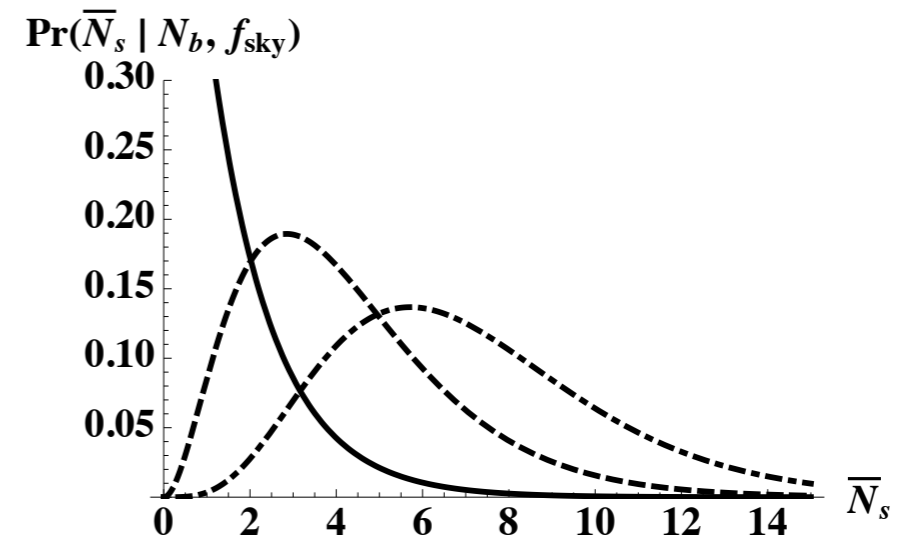


Searching for collisions

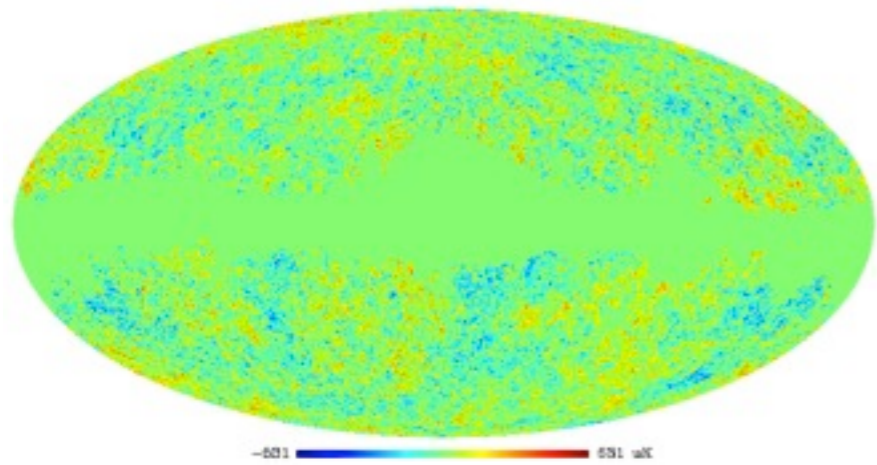


→

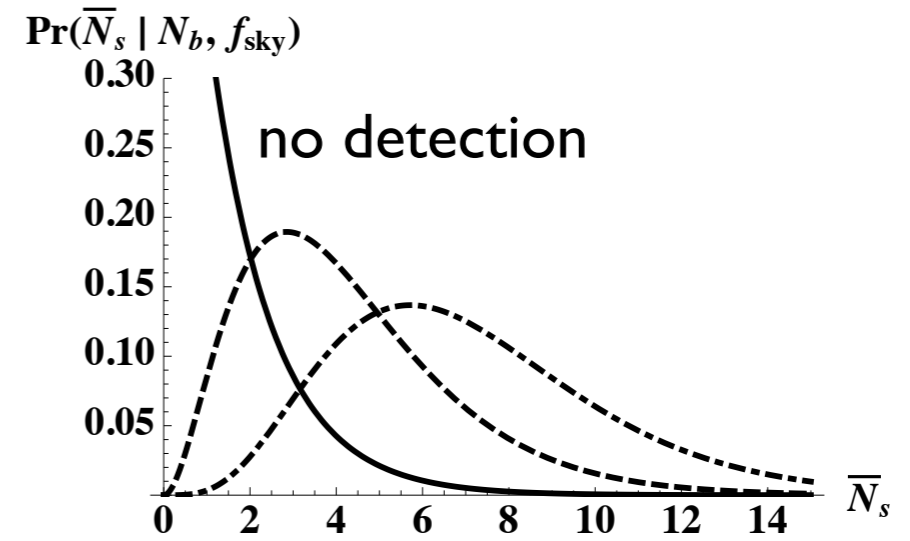
$$Pr(\bar{N}_s | \mathbf{d})$$



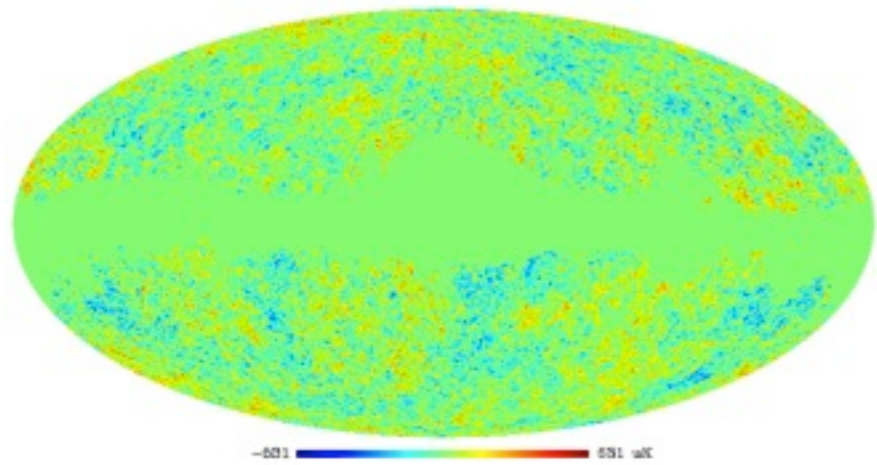
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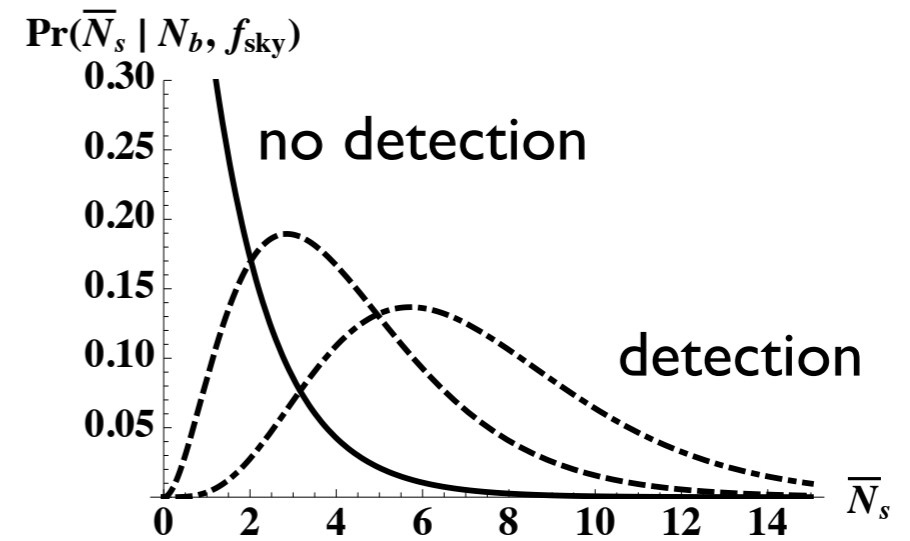
$$\longrightarrow$$
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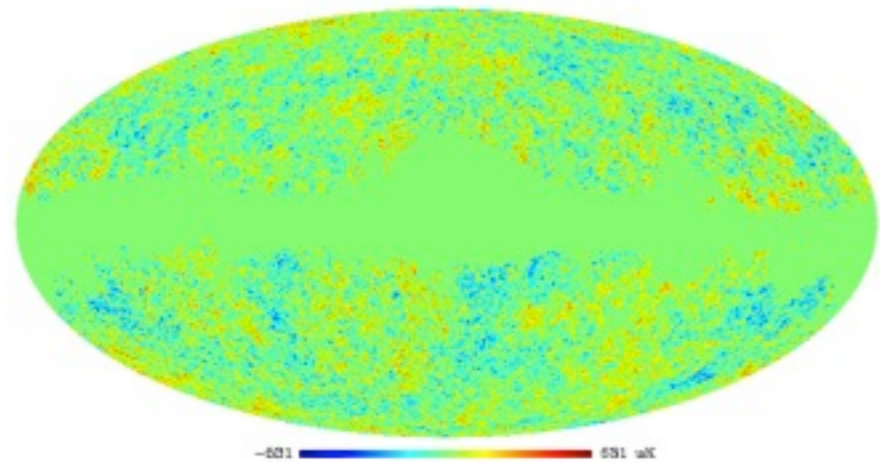
Searching for collisions



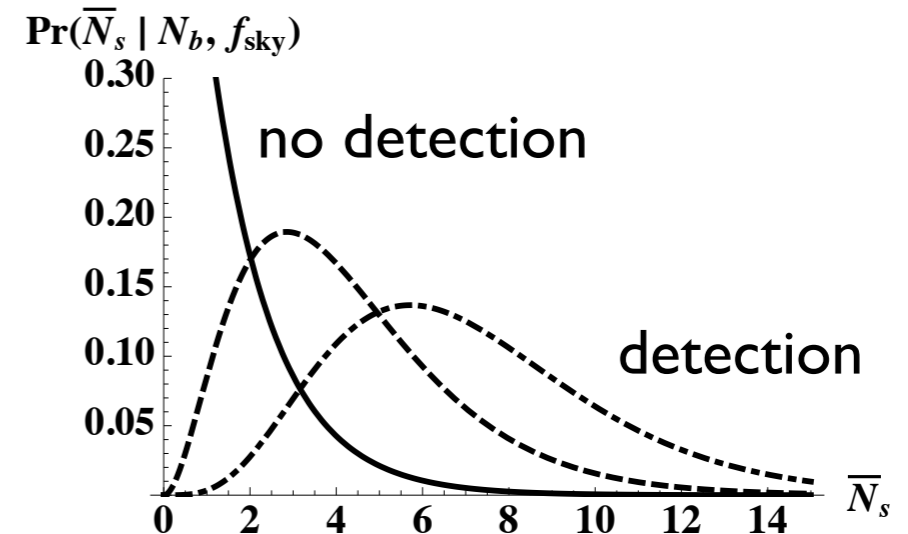
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Searching for collisions

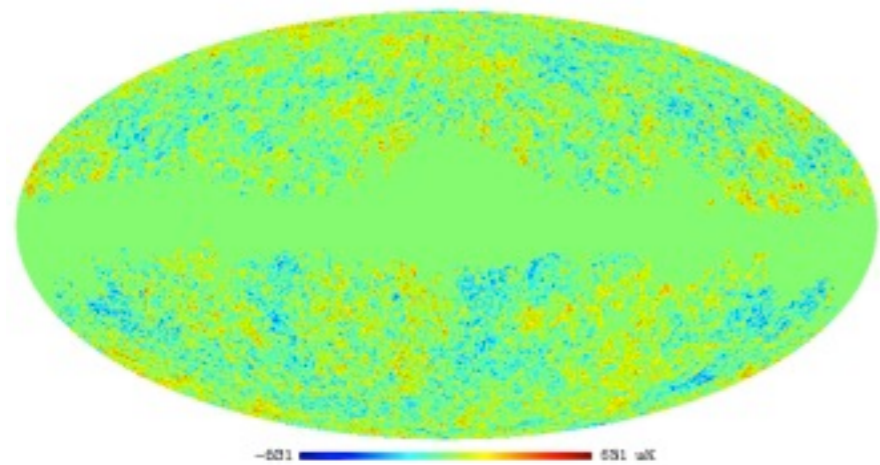


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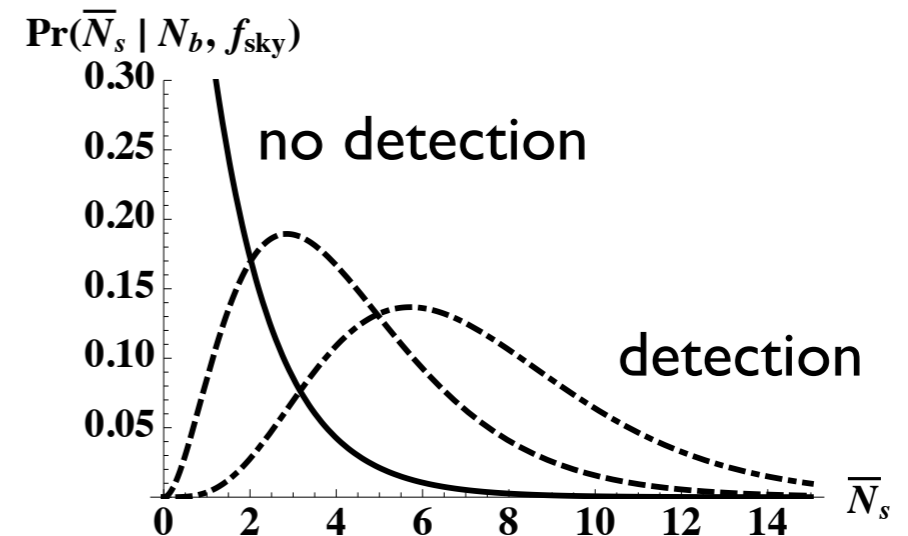


- To calculate this, need to test for:
 - Arbitrary number of templates
 - Arbitrary position on the sky
 - Arbitrary amplitude, shape, and size (lying within prior $\Pr(N_s, \mathbf{m})$)

Searching for collisions



$$Pr(\bar{N}_s | \mathbf{d})$$

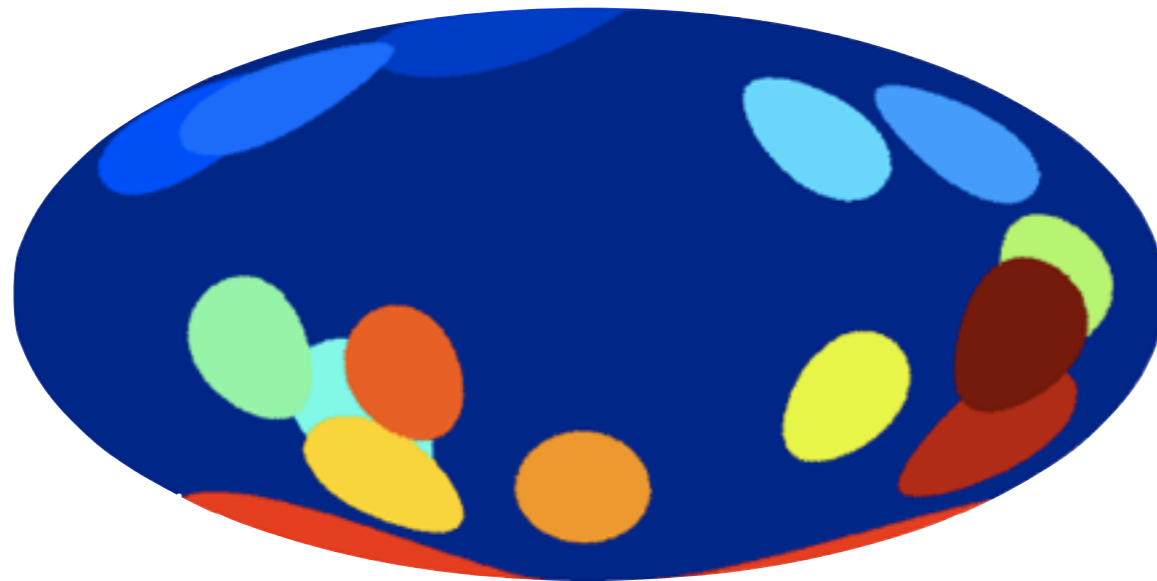


- To calculate this, need to test for:
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Implementing the exact calculation is impossible.

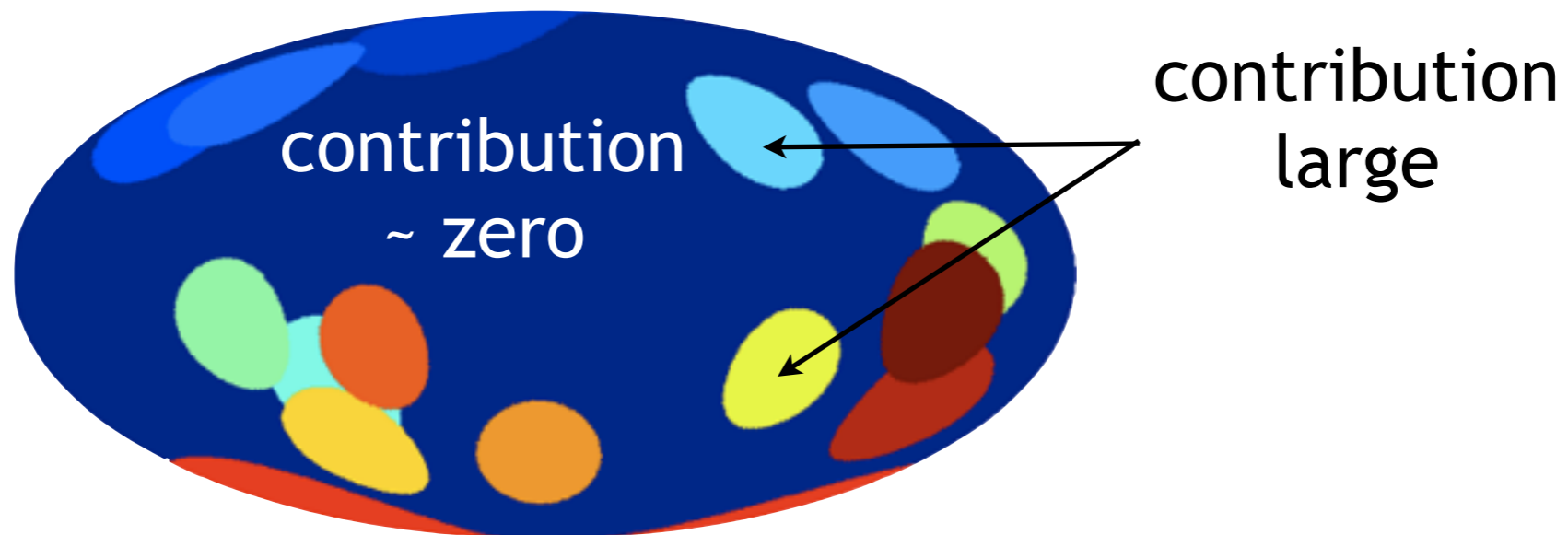
Searching for collisions

- Solution:
 - Locate candidate features with a blind analysis.



Searching for collisions

- Solution:
 - Locate candidate features with a blind analysis.
 - Find an approximation to the probability by integrating only over the regions of parameter space where the contribution is large.



Searching for collisions

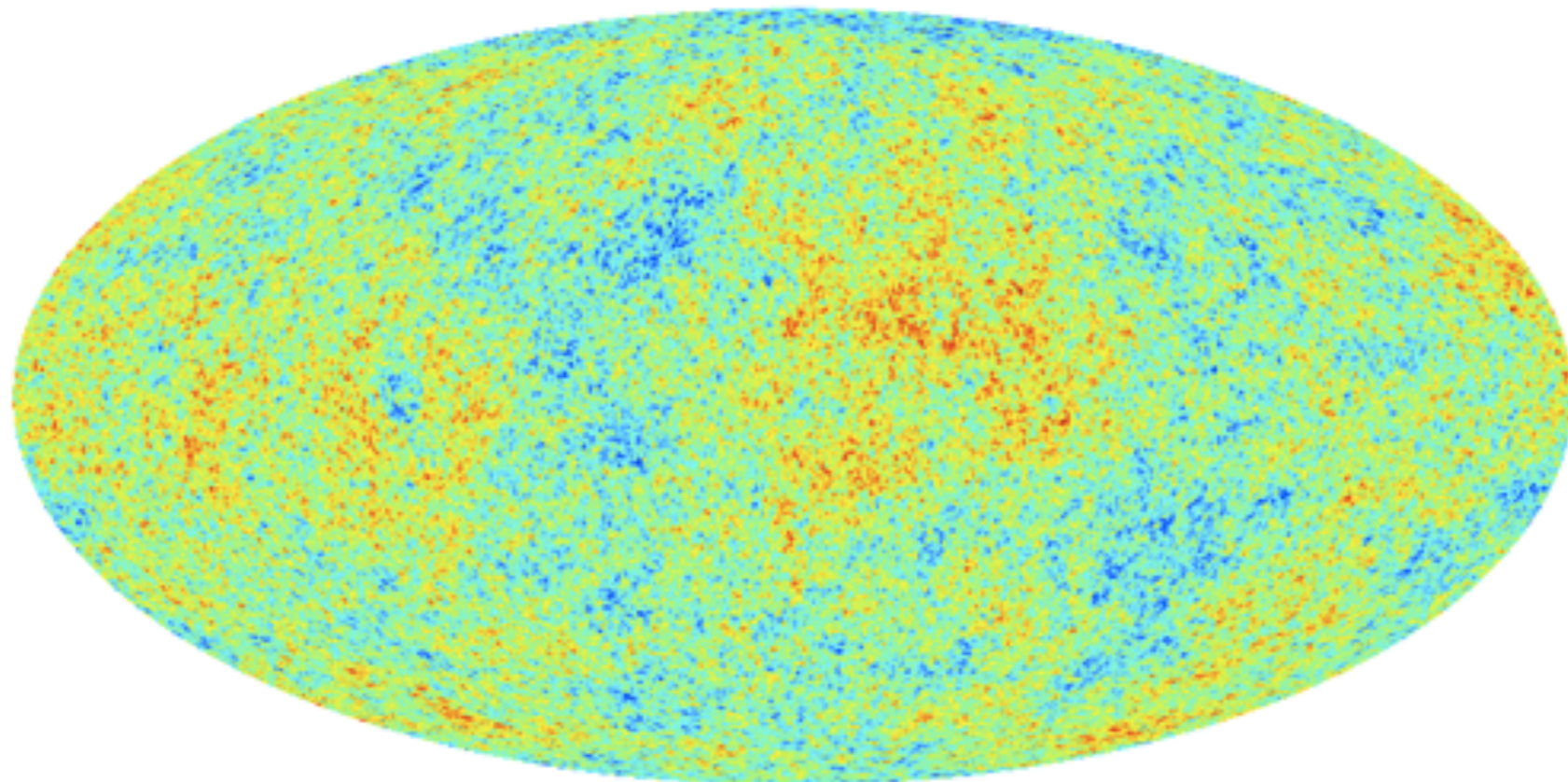
Feeney, [MCJ](#), Mortlock, Peiris

- Blind search for candidates:
 - Filter the CMB (wavelet decomposition, optimal filtering)
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 - Calibrate with simulations that don't contain collisions.

Searching for collisions

Feeney, [MCJ](#), Mortlock, Peiris

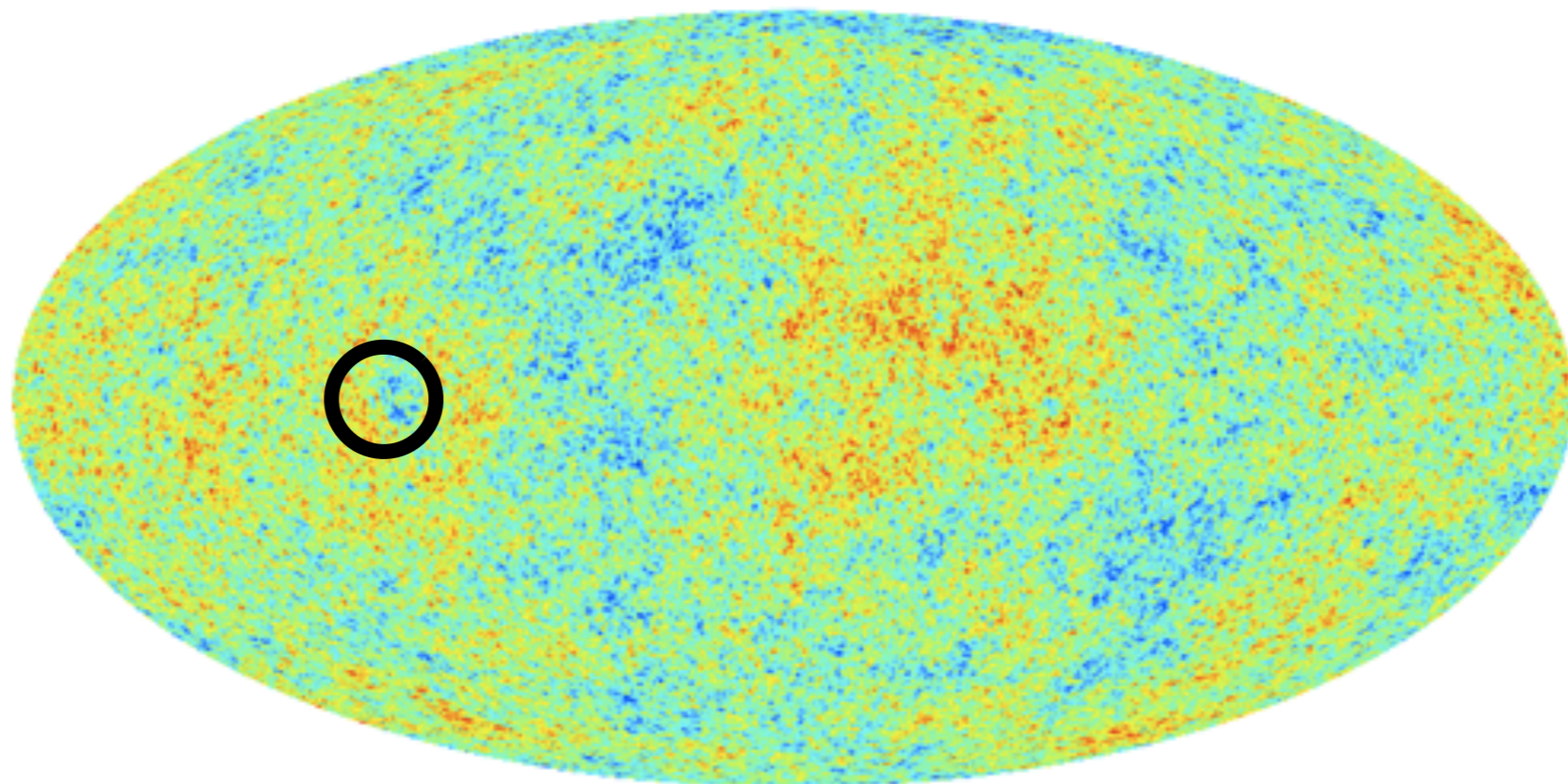
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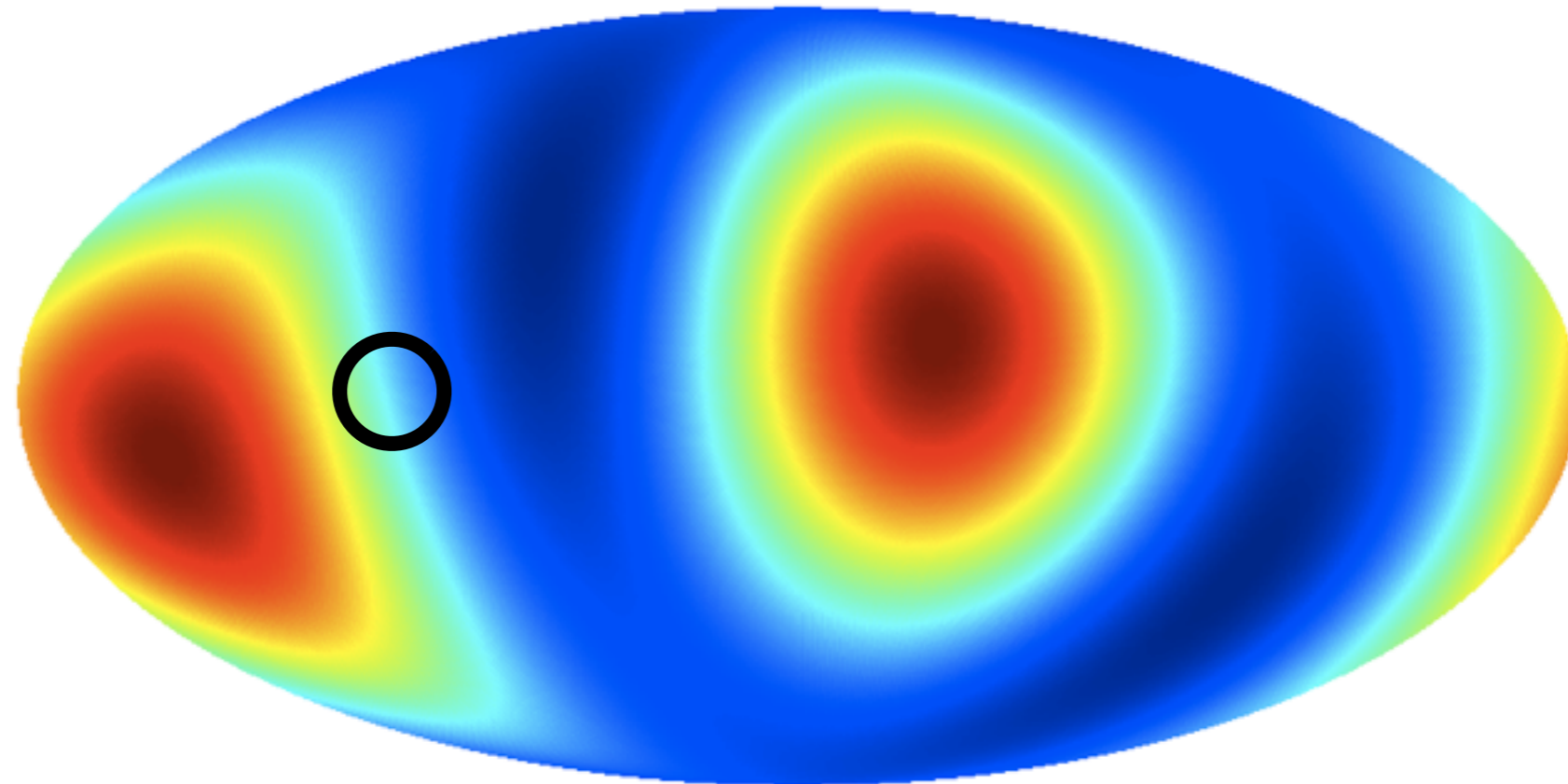
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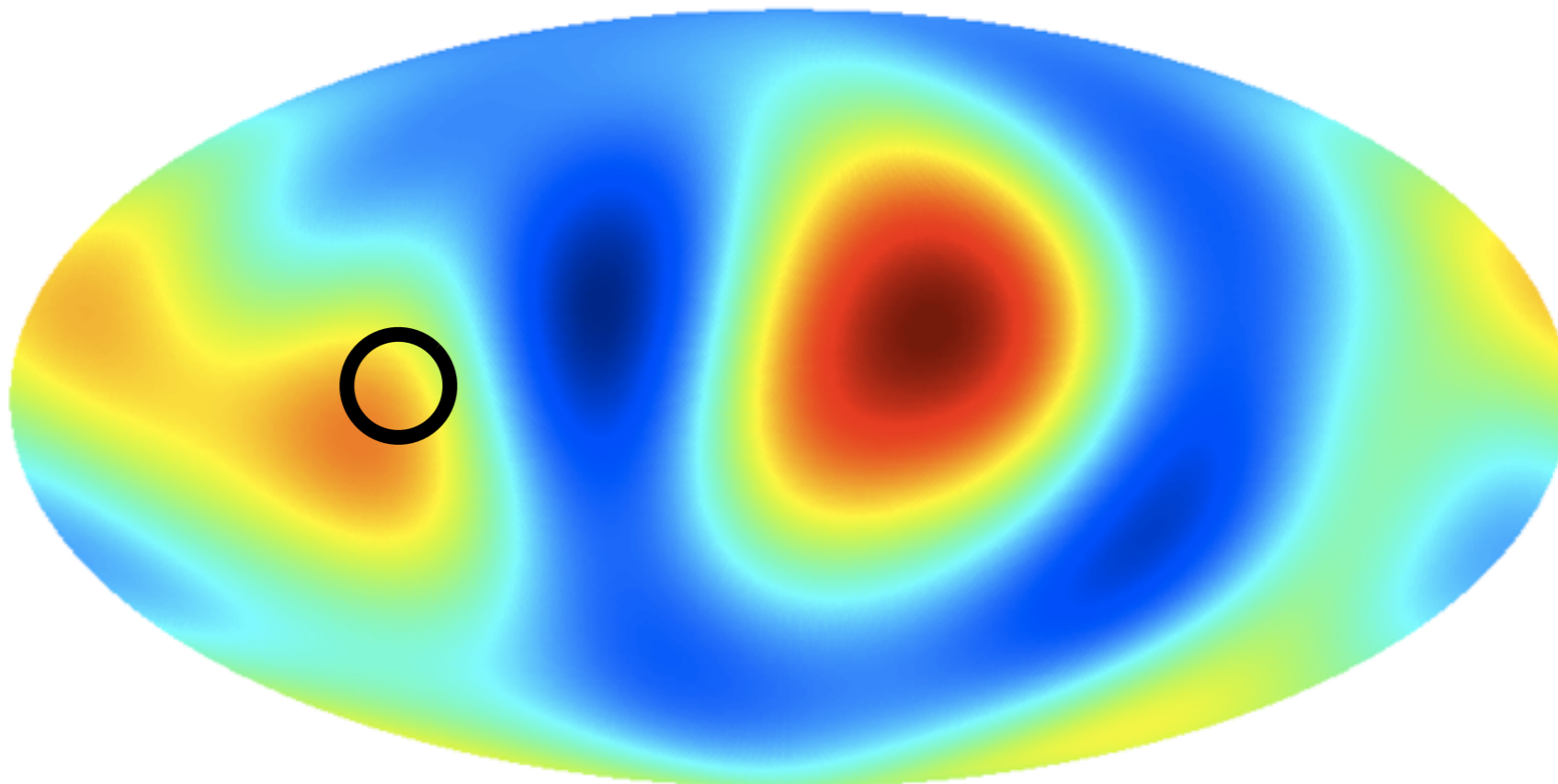
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Searching for collisions

Feeney, MCJ, Mortlock, Peiris

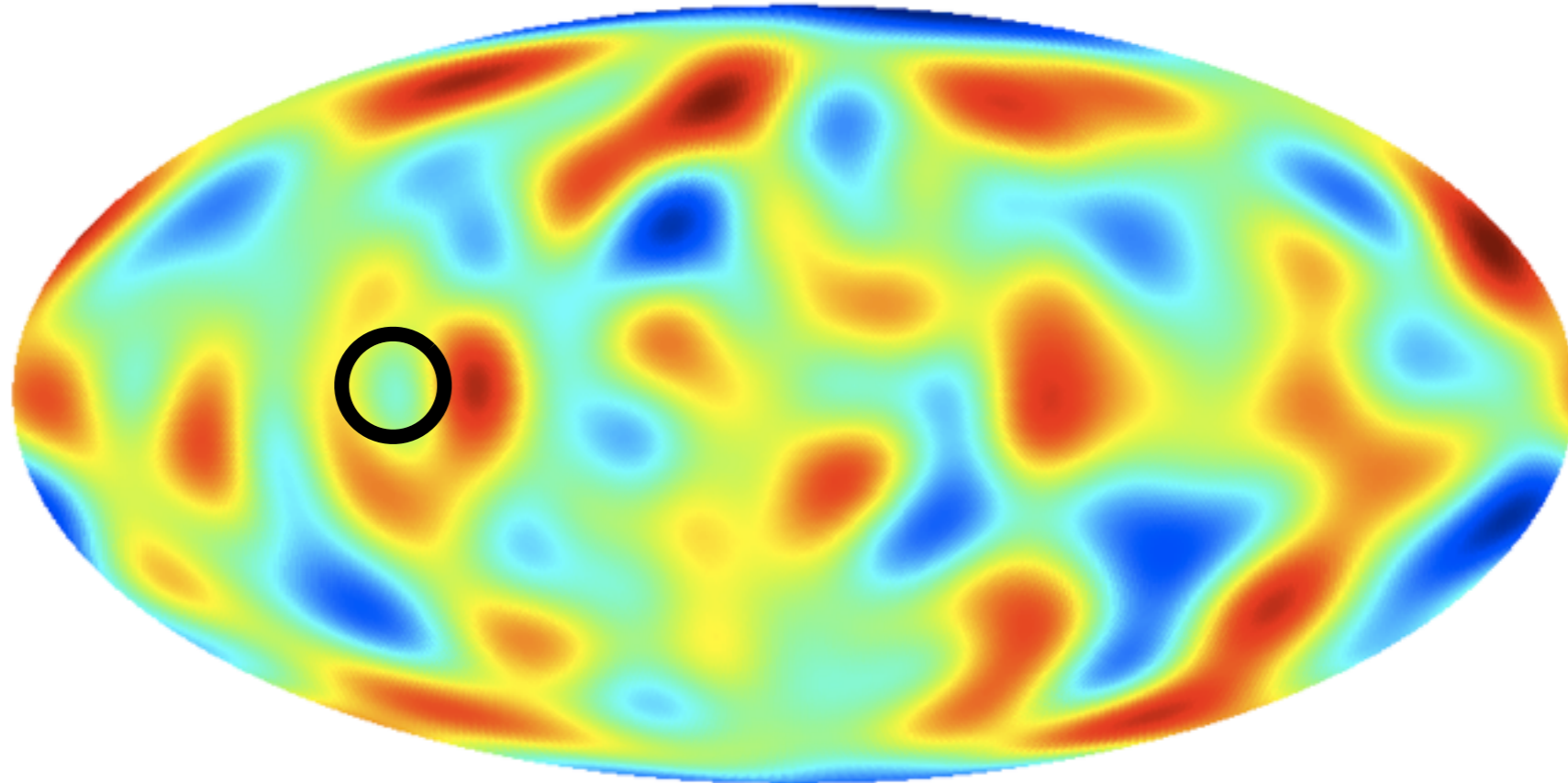
- Blind search for candidates:
 - Filter the CMB (wavelet decomposition, optimal filtering)
 - Judge significance of features against expectations from LCDM.
 - Calibrate with simulations that don't contain collisions.



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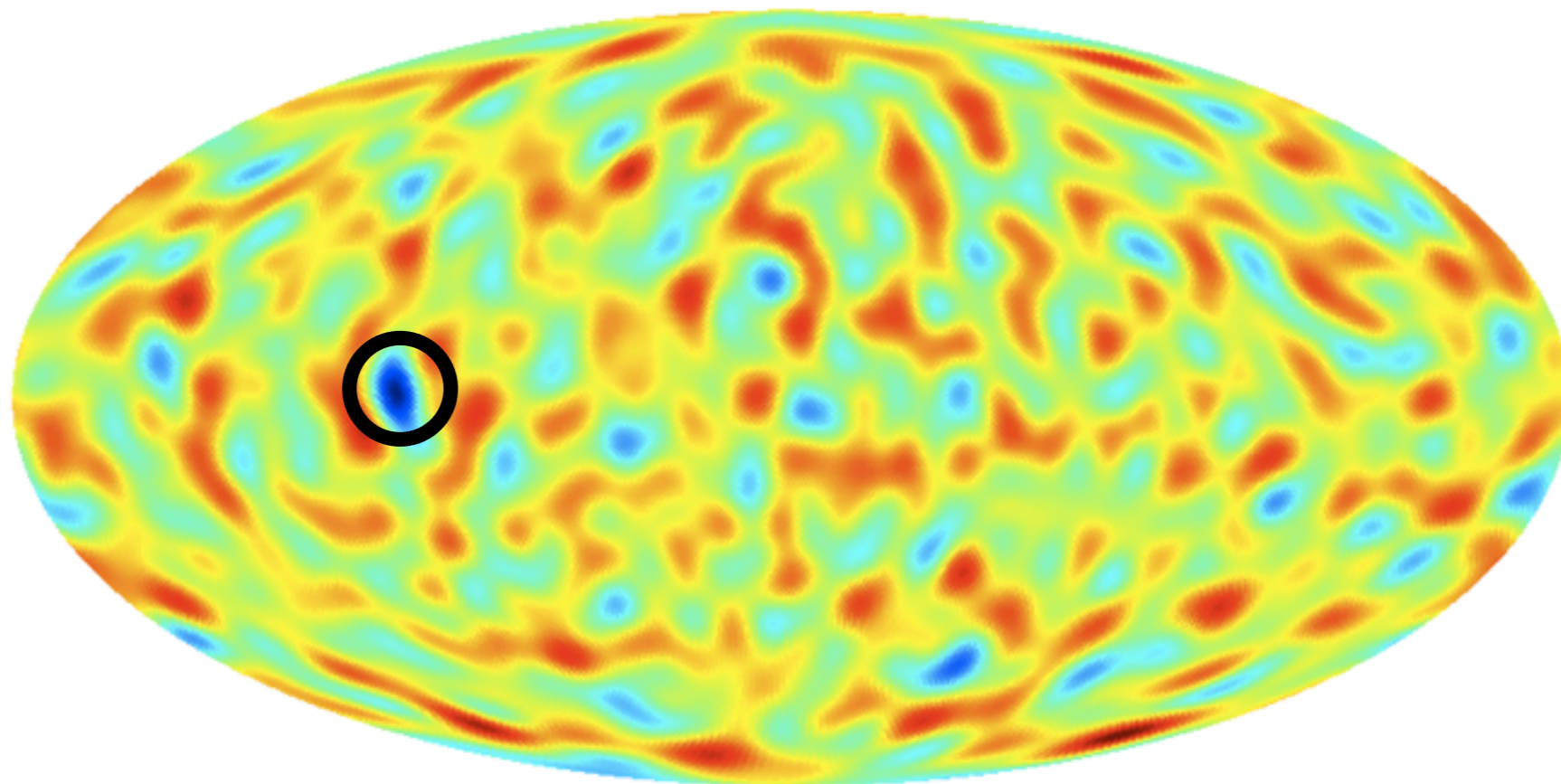
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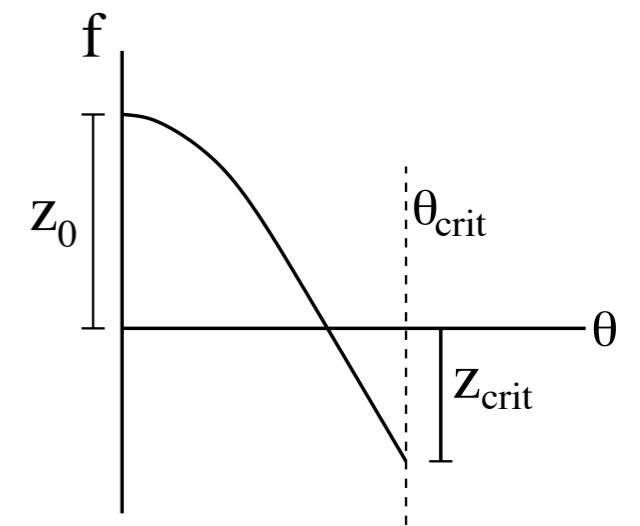
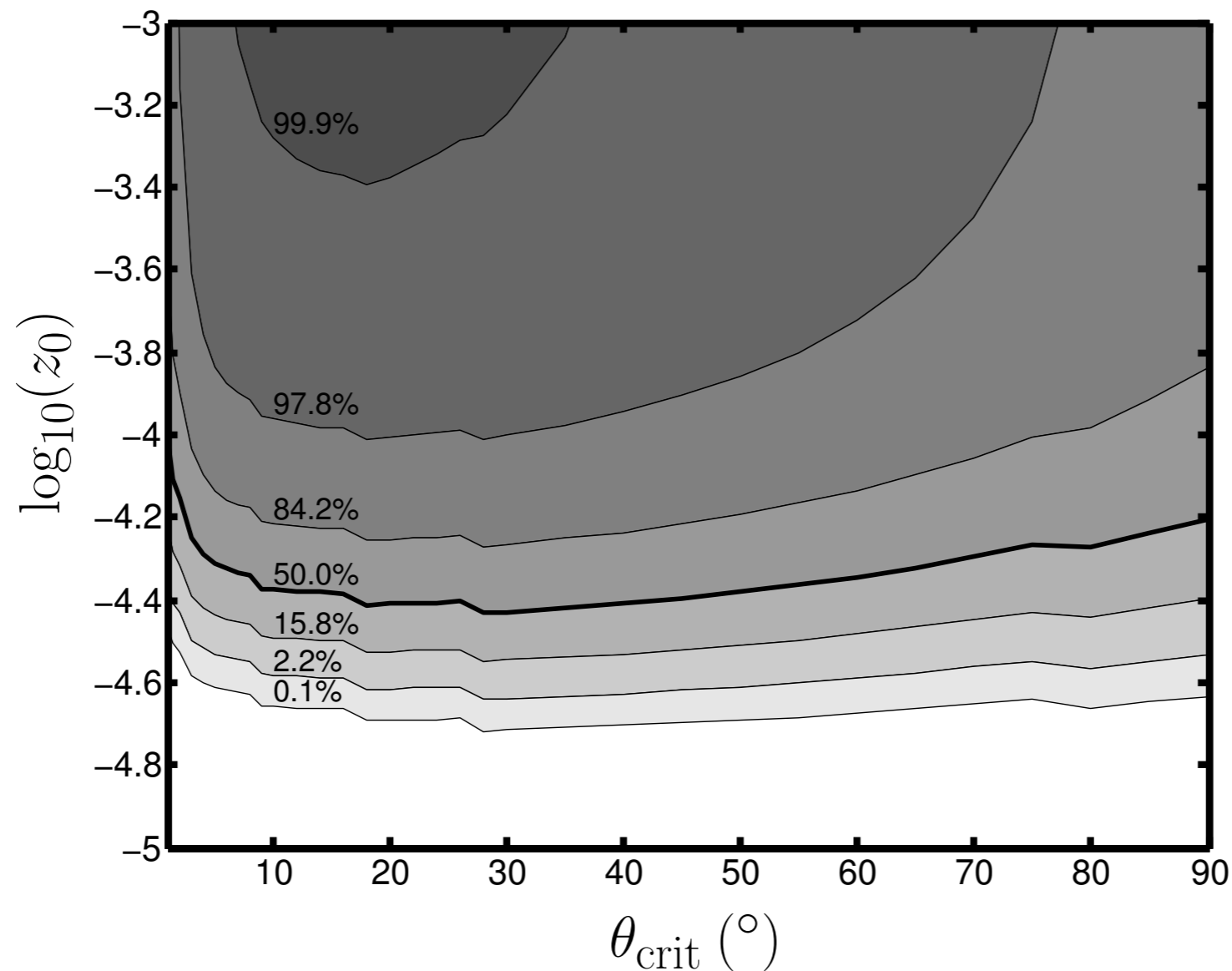
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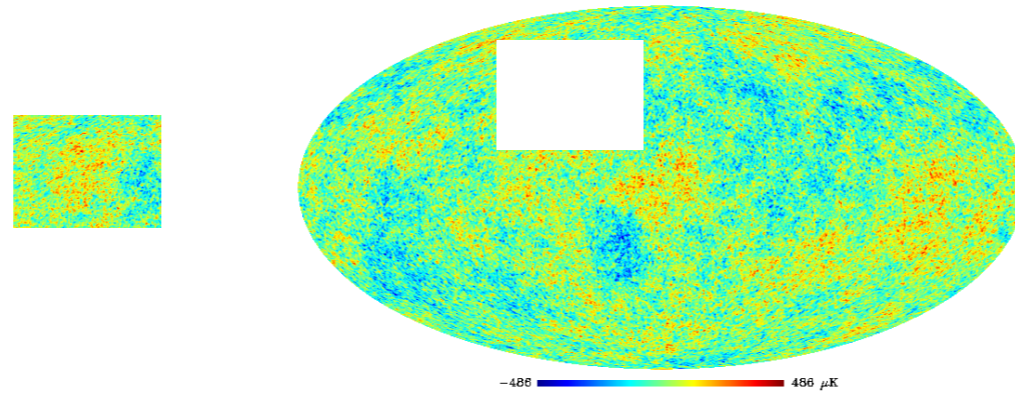
Searching for collisions

- Blind search for candidates:
- Keep candidates that lie above threshold:



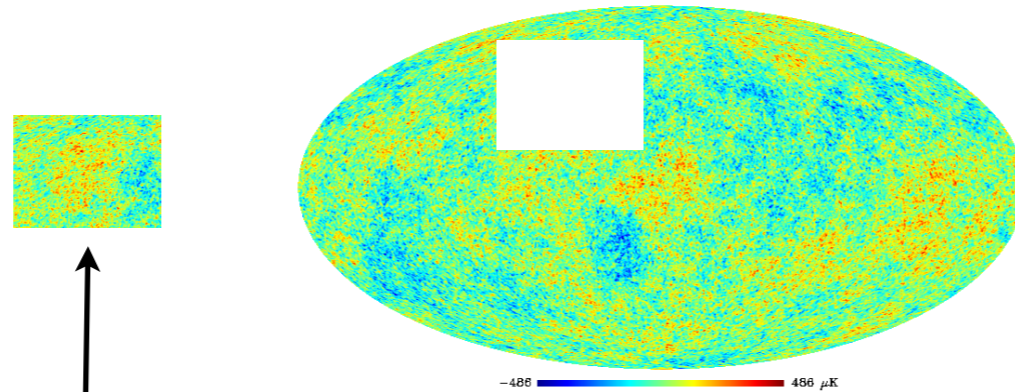
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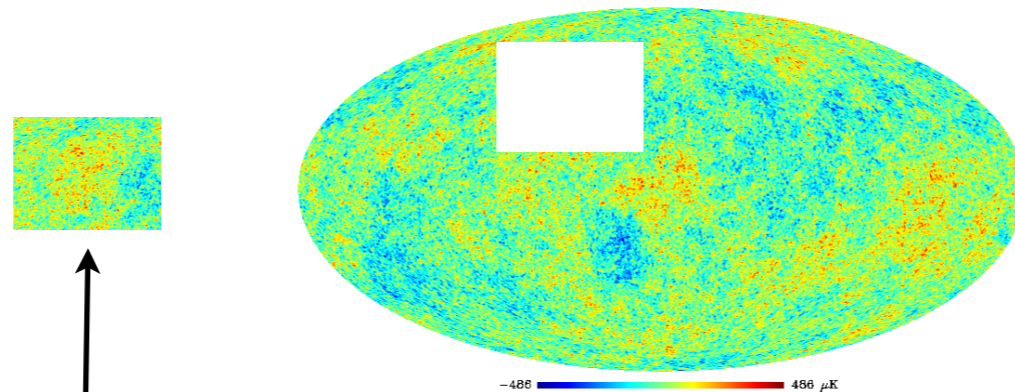


$$\rho_b = \frac{\int d\mathbf{m} \Pr(\mathbf{m}) L_b(\mathbf{d}|\mathbf{m})}{L_b(\mathbf{d}|\mathbf{0})}$$

Evidence ratio in the blob: how much better does one describe the data by adding a template?

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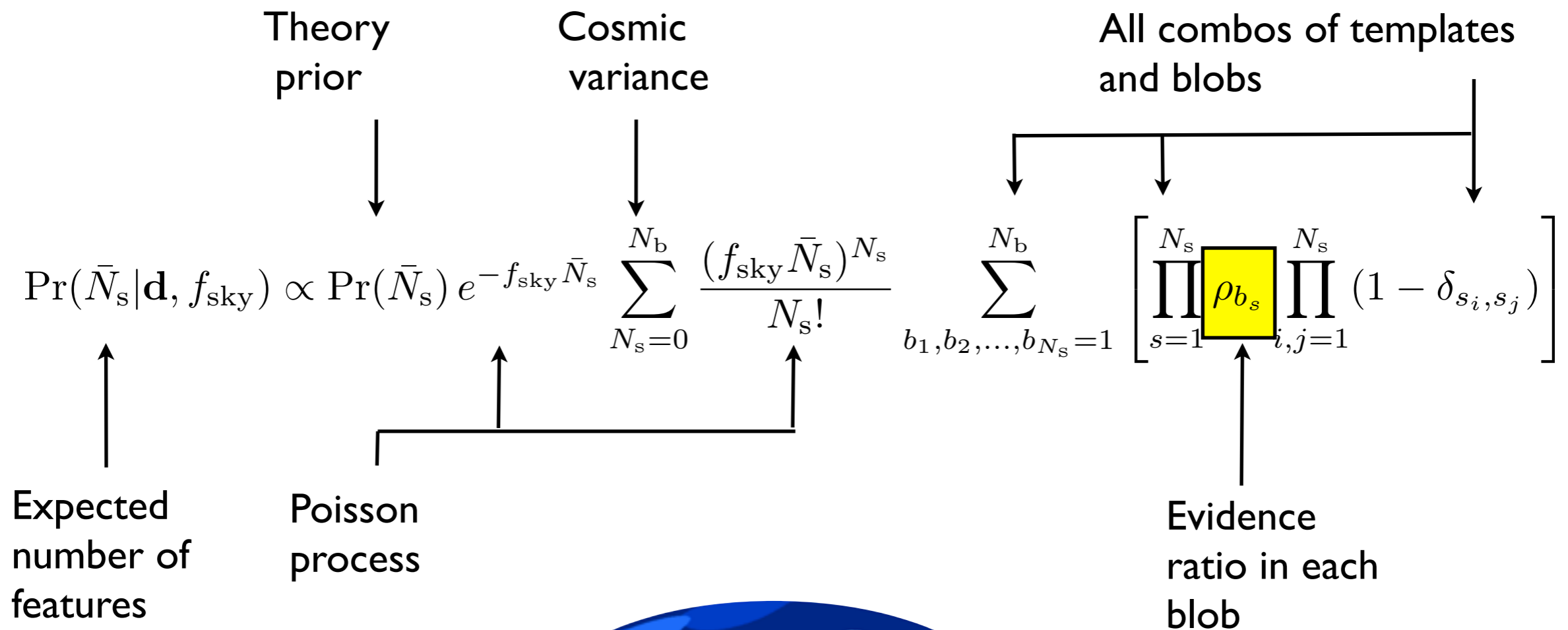
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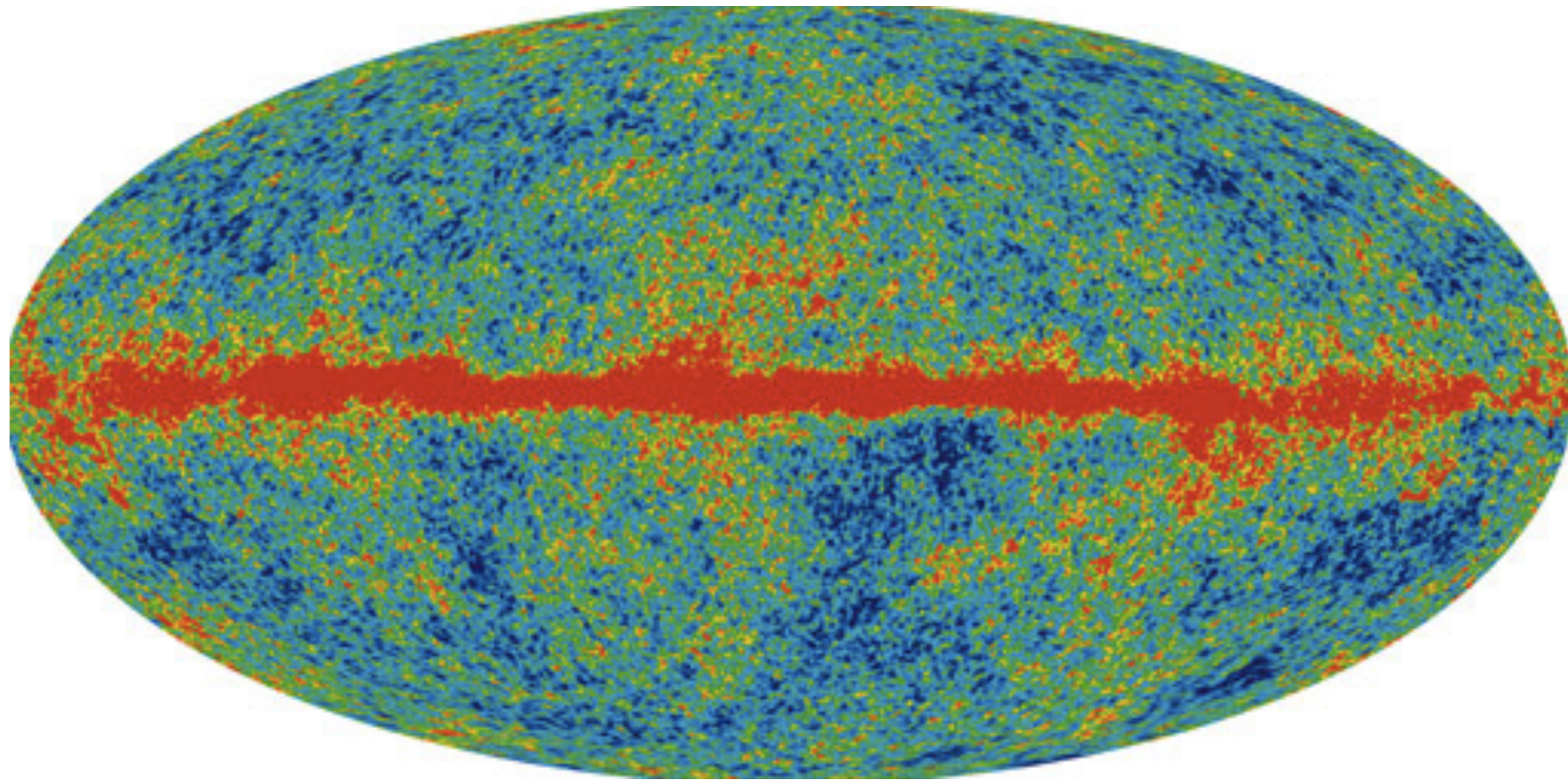
- Pixel-based likelihood $L_b(\mathbf{d}|\mathbf{m})$ contains: CMB cosmic variance, beam, and spatially varying noise.
- Flat prior on amplitude and shape, prior on size and position from theory.

Searching for collisions

- The general expression for N_b candidates:

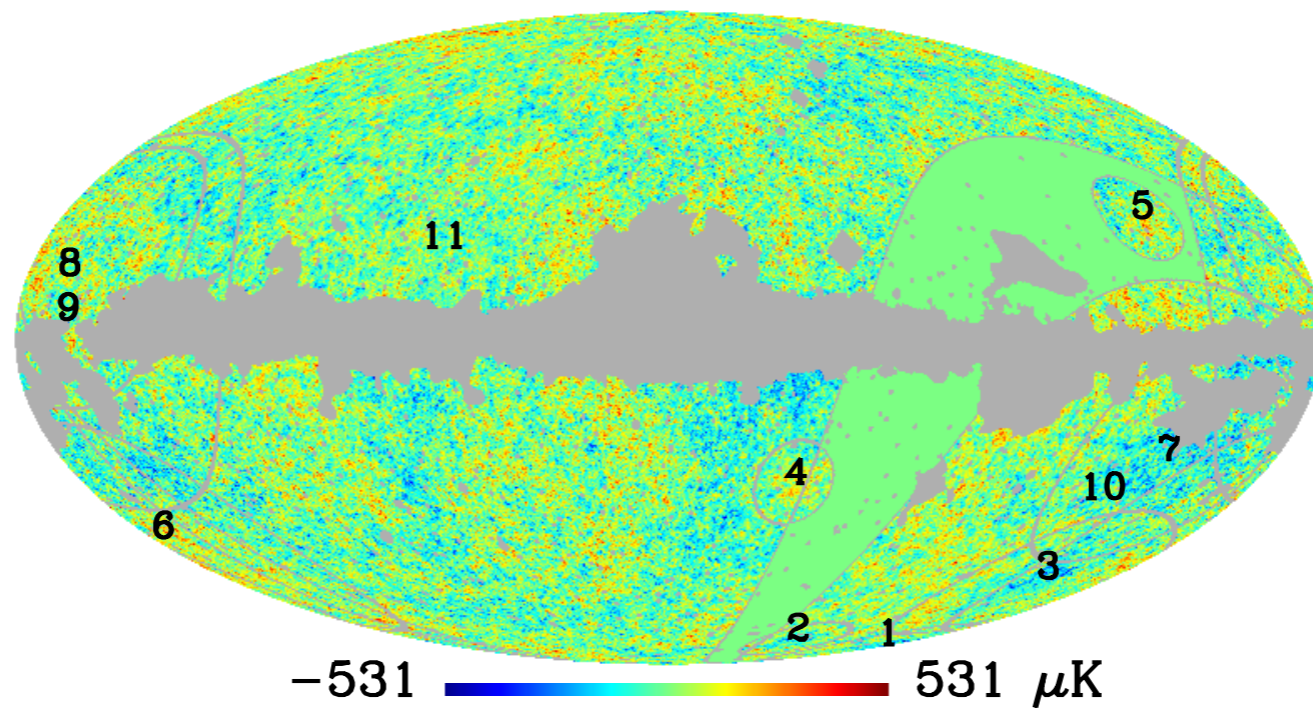
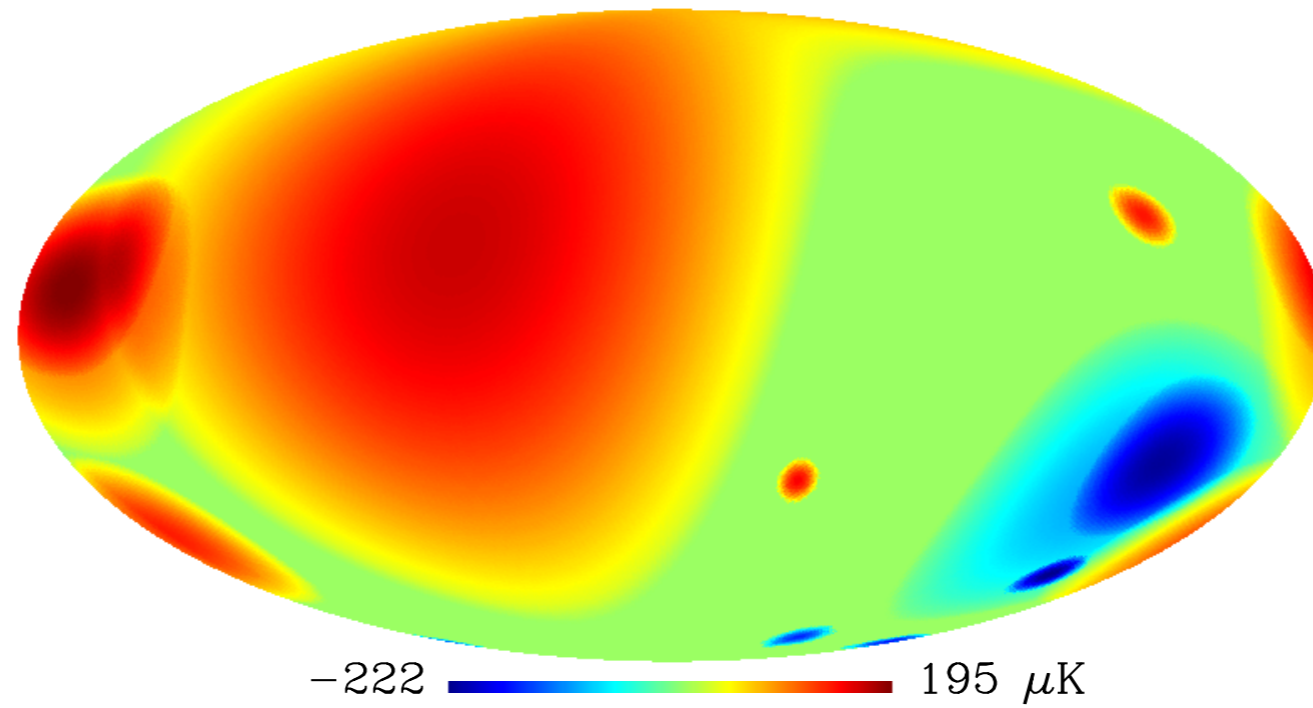


WMAP7 W-Band (94 GHz)

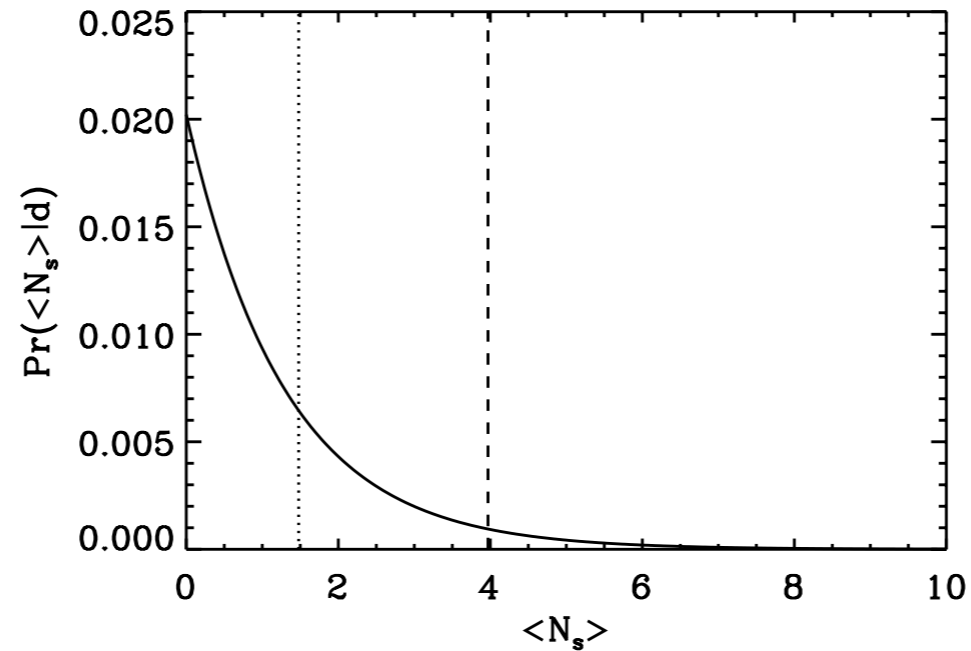


The WMAP7 W-Band data.....

WMAP7 W-Band (94 GHz) : Candidates



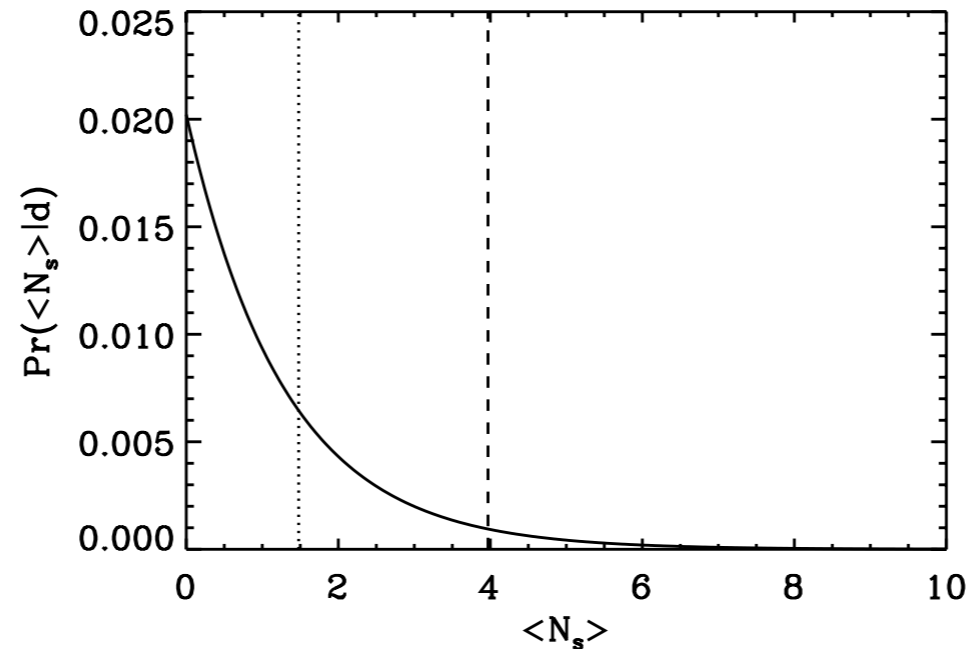
WMAP7 W-Band (94 GHz) : Posterior



- The posterior is peaked around $\bar{N}_s = 0$

The data does not support the bubble collision hypothesis.

WMAP7 W-Band (94 GHz) : Posterior



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The data does not support the bubble collision hypothesis.

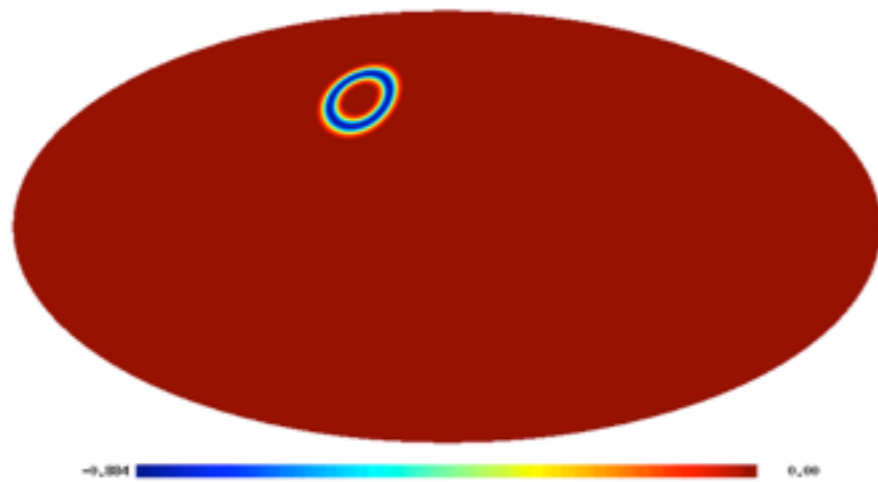
- From the shape of the posterior, we can rule out

$$\bar{N}_s < 1.6 \text{ at } 68\% \text{ CL}$$

What next?

- Check for signals in other datasets.

Polarization signal

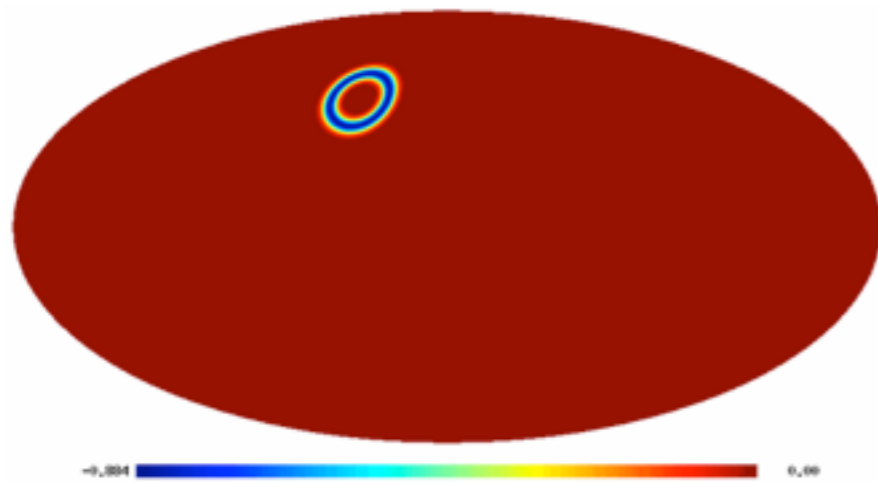


Czech et. al.
Kleban et. al.

What next?

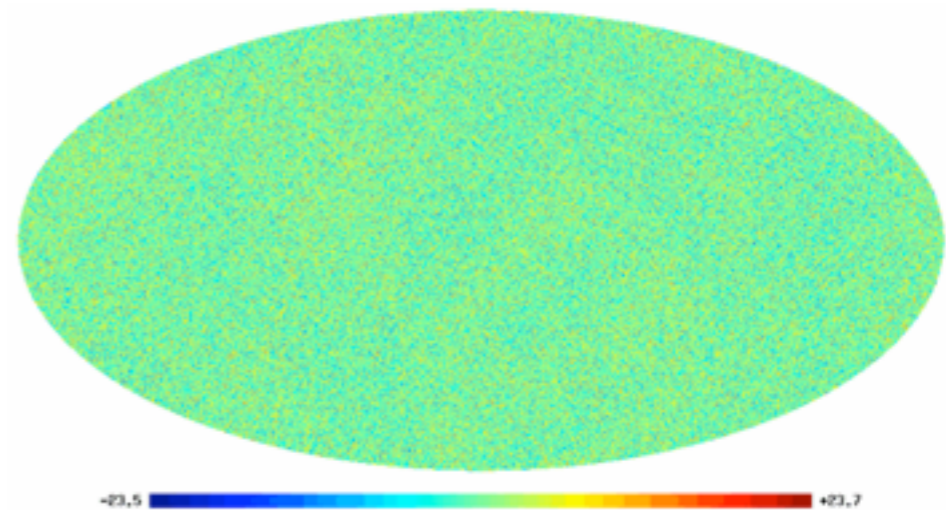
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Polarization signal



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Planck res. with noise



corroborating evidence?

What next?

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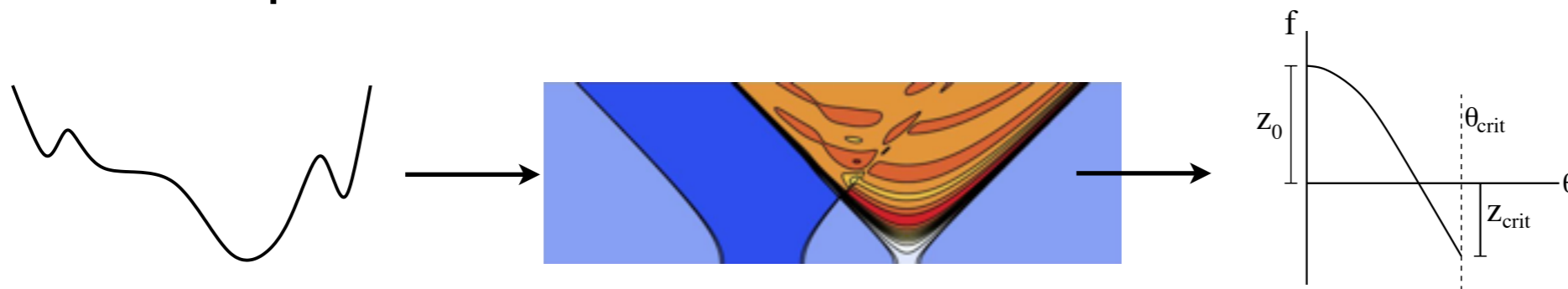
- What region of theory space have we constrained?

Novel connection between numerical relativity and
observational cosmology!

What next?

$$\bar{N}_s < 1.6 \text{ at } 68\% \text{ CL}$$

- What region of theory space have we constrained?
- Numerical simulations are needed to connect the potential to the template!



(Like in inflation: general template for fluctuations needs to be connected to the potential)

Novel connection between numerical relativity and observational cosmology!