

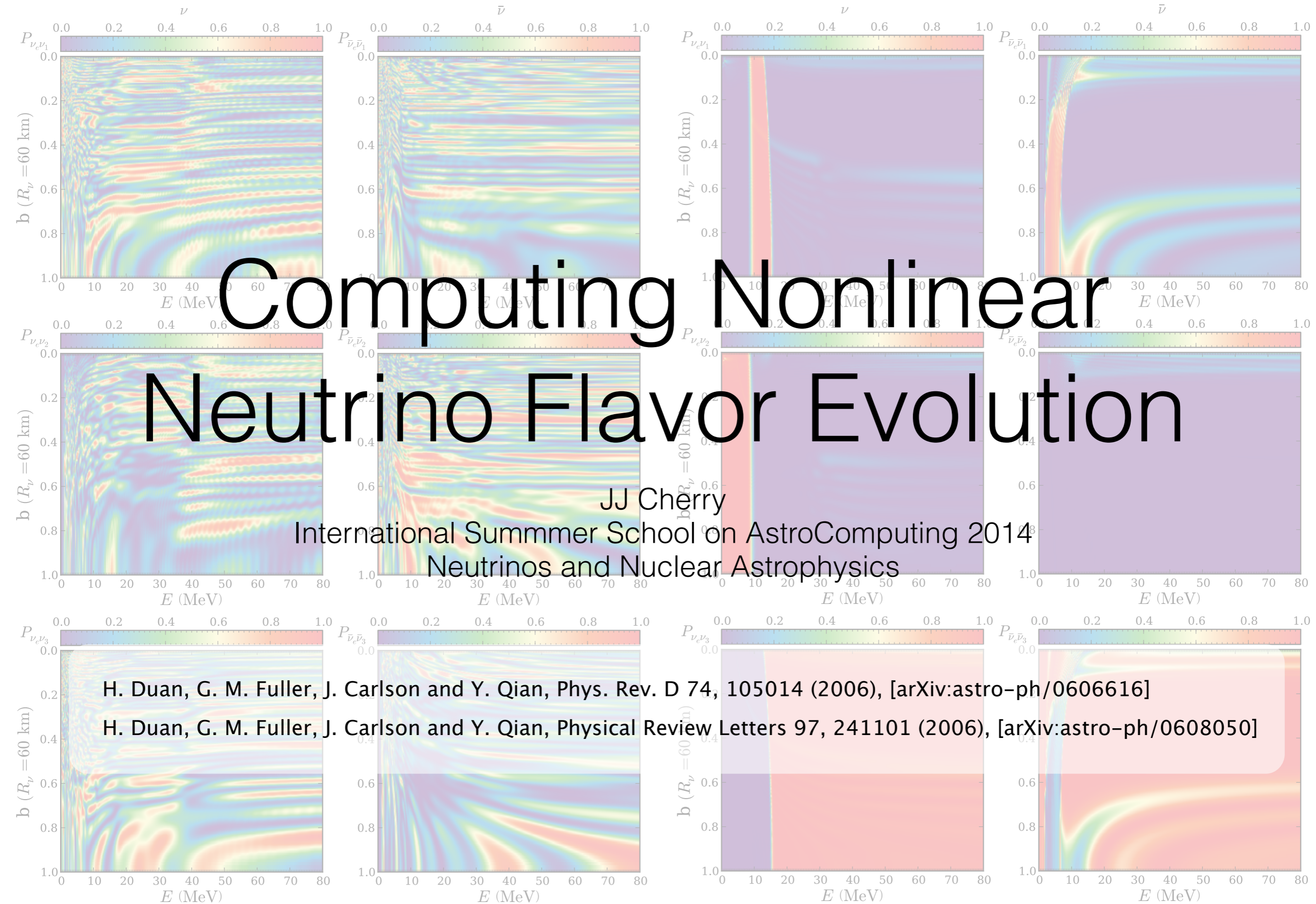
Computing Nonlinear Neutrino Flavor Evolution

JJ Cherry

International Summer School on AstroComputing 2014
Neutrinos and Nuclear Astrophysics

H. Duan, G. M. Fuller, J. Carlson and Y. Qian, Phys. Rev. D 74, 105014 (2006), [arXiv:astro-ph/0606616]

H. Duan, G. M. Fuller, J. Carlson and Y. Qian, Physical Review Letters 97, 241101 (2006), [arXiv:astro-ph/0608050]

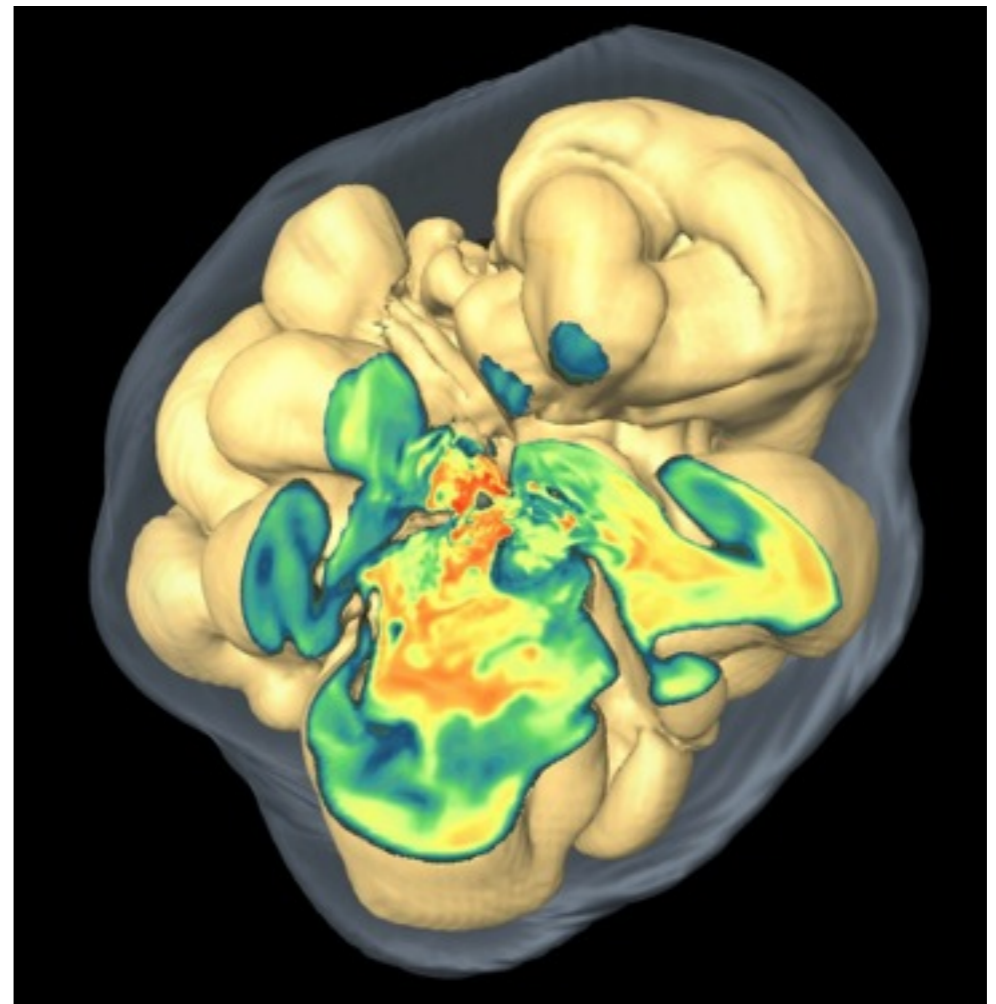
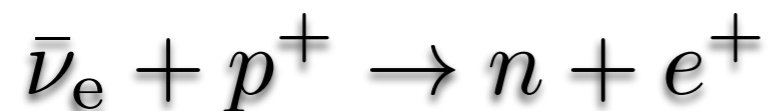
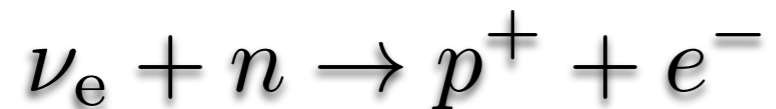


What do we want to learn today?

- Sooner or later, you will be working on a project and someone will point out that there is a miserably complicated problem that you need to solve *BEFORE* you get to the result you are interested in.
- “Some times a project is fun to work on because nobody knows anything about it, and then the experimentalists catch up with you and ask you what is going on.” -G.M. Fuller
- Today, we’ll start with a very tough problem and break down the thought process of how develop a parallel computing approach to solving it.

Why we want to solve nonlinear neutrino flavor evolution

In the supernova environment, neutrino flavor states directly effect heating efficiency and nucleosynthesis.



F. Hanke, A. Marek, B. Müller & H. Th. Janka ([arXiv:1108.4355](https://arxiv.org/abs/1108.4355))

For a baryon to be ejected for the supernova, it must absorb ~ 10 neutrinos to gain enough energy to escape the region around the PNS.

Coherent Forward Scattering: Neutrino Flavor Evolution

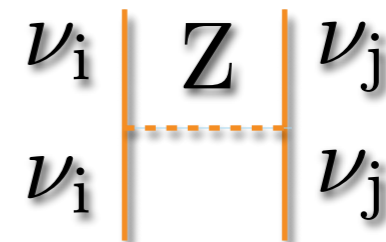
$$\psi_{\nu,i} = \begin{bmatrix} \text{amplitude to be } \nu_e \\ \text{amplitude to be } \nu_\mu \\ \text{amplitude to be } \nu_\tau \end{bmatrix}$$

$$i \frac{\partial}{\partial t} \psi_{\nu,i} = (H_{\text{vac},i} + H_{e,i} + H_{\nu\nu,i}) \psi_{\nu,i}$$

neutrino-electron
charged current
forward exchange
scattering



neutrino-neutrino
neutral current
forward scattering



Neutrino Mixing: How do we associate flavor states to mass states?

$$\begin{pmatrix} |\nu_e\rangle \\ |\nu_\mu\rangle \\ |\nu_\tau\rangle \end{pmatrix} = U_m \begin{pmatrix} |\nu_1\rangle \\ |\nu_2\rangle \\ |\nu_3\rangle \end{pmatrix}$$

4 mixing parameters

$$\theta_{12}, \theta_{23}, \theta_{13}, \delta$$

$$U_m = U_{23}U_{13}U_{12} =$$

$$\begin{pmatrix} c_{12}c_{13} & s_{12}c_{13} & s_{13}e^{-i\delta} \\ -s_{12}c_{23} - c_{12}s_{13}s_{13}e^{i\delta} & c_{12}c_{23} - s_{12}s_{13}s_{13}e^{i\delta} & c_{13}s_{12} \\ s_{12}s_{23} - c_{12}s_{13}c_{13}e^{i\delta} & c_{12}s_{23} - s_{12}s_{13}c_{13}e^{i\delta} & c_{13}c_{23} \end{pmatrix}$$

$$\sin^2 2\theta_{23} \approx 1.0$$

$$\tan^2 \theta_{12} \approx 0.42 - 0.45$$

$$\sin^2 2\theta_{13} = 0.09 \pm .021$$

F. P. An, et. al., Observation of electron-antineutrino disappearance at Daya Bay, ([arXiv:](#)

Neutrino Mass: how oscillation happens

We know the mass-squared differences: $\left\{ \begin{array}{l} \Delta m_{\odot}^2 \approx 7.6 \times 10^{-5} \text{ eV}^2 \\ \Delta m_{\text{atm}}^2 \approx 2.4 \times 10^{-3} \text{ eV}^2 \end{array} \right.$

$$\text{e.g., } \Delta m_{12}^2 = m_2^2 - m_1^2$$

$$i \frac{\partial |\Psi\rangle}{\partial t} = \hat{H} |\Psi\rangle \rightarrow \hat{H} = (\hat{p}^2 + \hat{m}^2)^{(1/2)} \approx \hat{p} + \hat{m}^2 / 2\hat{p}$$

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$$i \frac{\partial |\Psi_m\rangle}{\partial t} = \left[\left(p + \frac{m_1^2 + m_2^2 + m_3^2}{4p} \right) \hat{I} + \frac{1}{2p} \begin{pmatrix} -\frac{\Delta m_{21}^2 + \Delta m_{31}^2}{3} & 0 & 0 \\ 0 & \frac{2\Delta m_{21}^2 - \Delta m_{31}^2}{3} & 0 \\ 0 & 0 & \frac{2\Delta m_{31}^2 - \Delta m_{21}^2}{3} \end{pmatrix} \right] |\Psi_m\rangle$$

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In the Flavor Basis:

$$H_{\text{vac}} = \frac{1}{2E_\nu} \times U_m \begin{pmatrix} -\frac{\Delta m_{21}^2 + \Delta m_{31}^2}{3} & 0 & 0 \\ 0 & \frac{2\Delta m_{21}^2 - \Delta m_{31}^2}{3} & 0 \\ 0 & 0 & \frac{2\Delta m_{31}^2 - \Delta m_{21}^2}{3} \end{pmatrix} U_m^\dagger$$

The Matter Potential

$$H_{\text{mat}} = \begin{pmatrix} \sqrt{2}G_{\text{F}}n_e(r, \theta, \phi) & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$



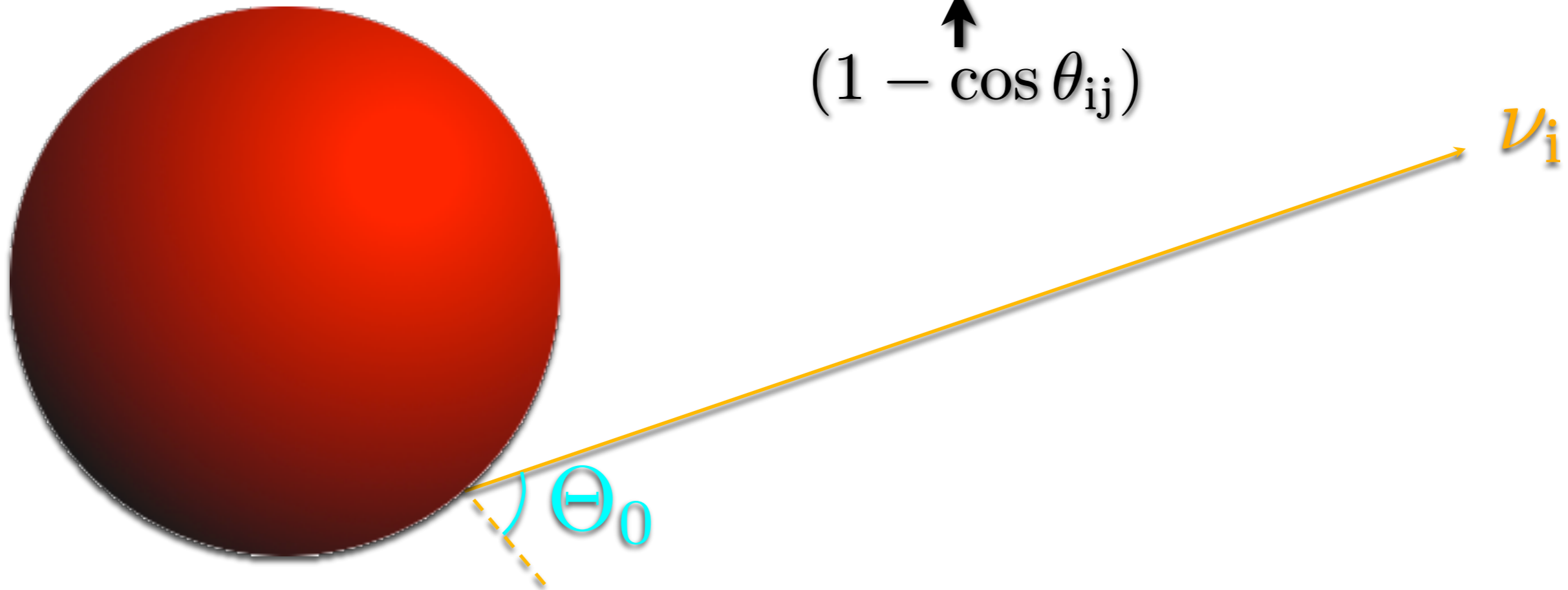
Again, only the traceless piece contributes.

$$H_e = \begin{pmatrix} -\frac{2\sqrt{2}G_{\text{F}}n_e(r, \theta, \phi)}{3} & 0 & 0 \\ 0 & \frac{\sqrt{2}G_{\text{F}}n_e(r, \theta, \phi)}{3} & 0 \\ 0 & 0 & \frac{\sqrt{2}G_{\text{F}}n_e(r, \theta, \phi)}{3} \end{pmatrix}$$

Neutrino Self-Coupling: Flavor States and Geometry

$$H_{\nu\nu,i} = \sqrt{2}G_F \sum_j \left(1 - \hat{k}_i \cdot \hat{k}_j\right) n_{\nu,j} \psi_{\nu,j} \psi_{\nu,j}^\dagger - \sqrt{2}G_F \sum_j \left(1 - \hat{k}_i \cdot \hat{k}_j\right) n_{\bar{\nu},j} \psi_{\bar{\nu},j} \psi_{\bar{\nu},j}^\dagger$$

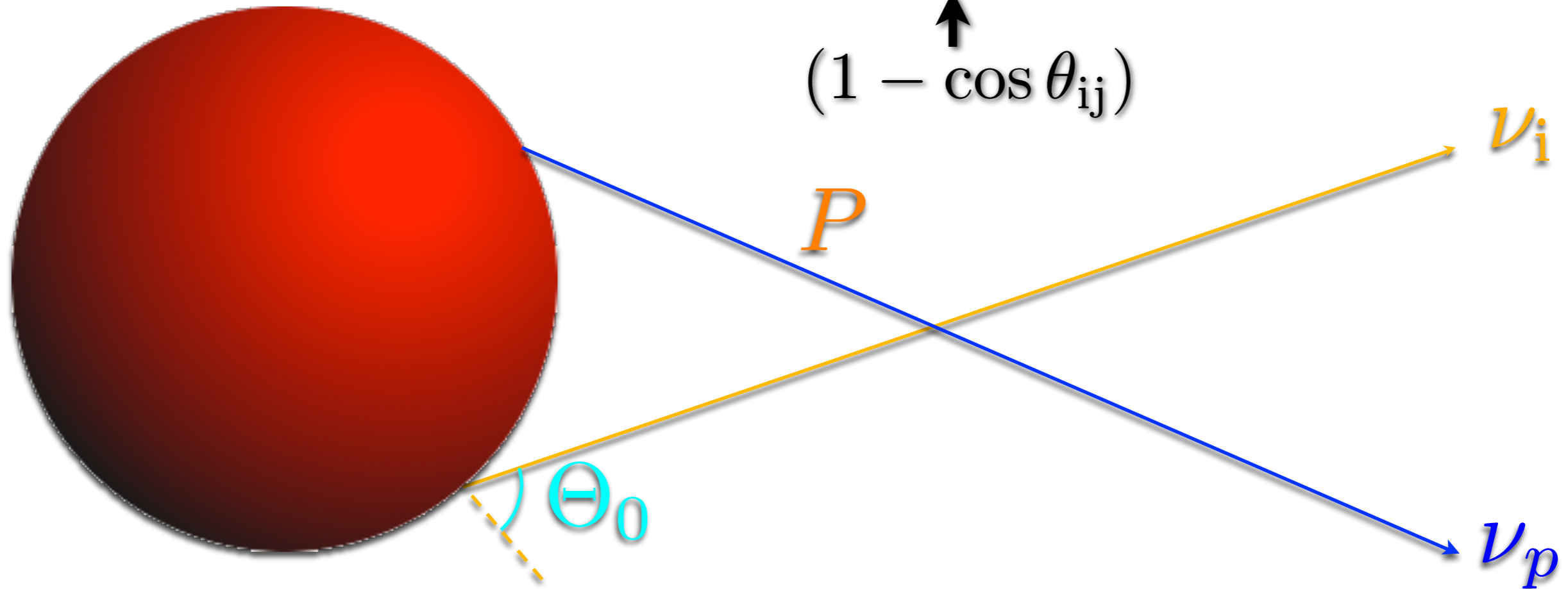
\uparrow
 $(1 - \cos \theta_{ij})$



All together, we solve about $10^6 - 10^7$ non-linearly coupled differential equations at each radial step.

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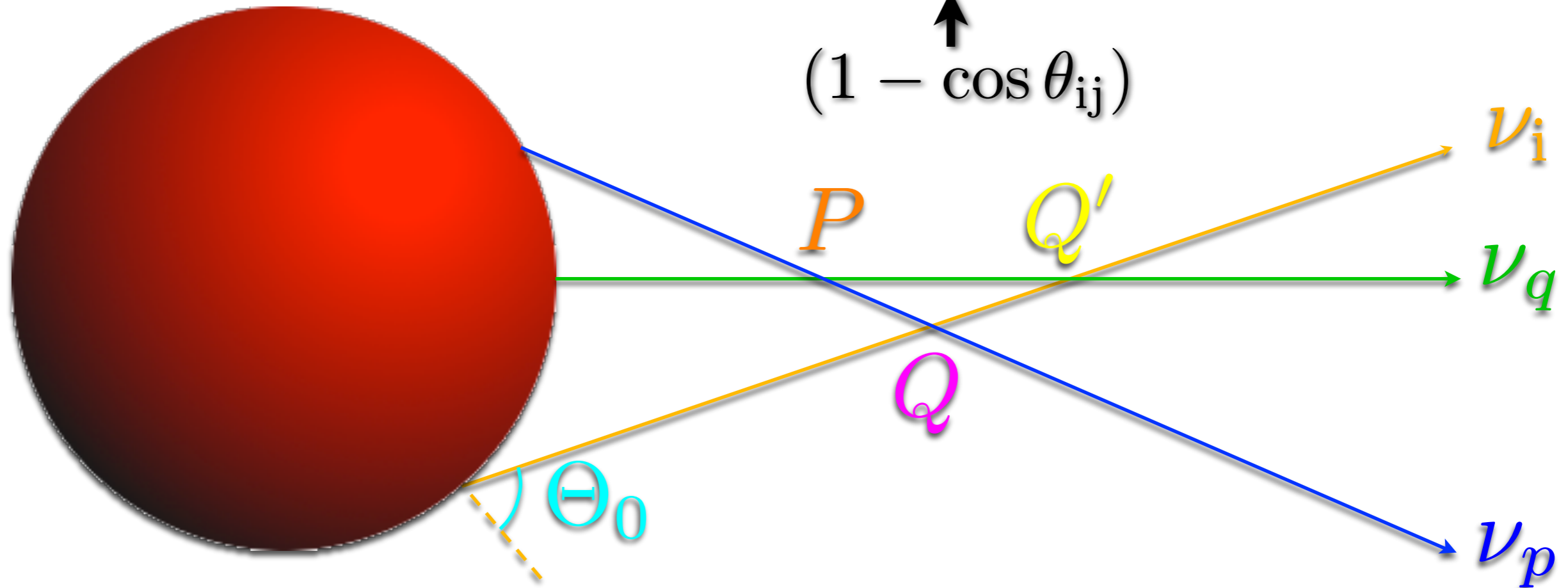
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Taking Stock

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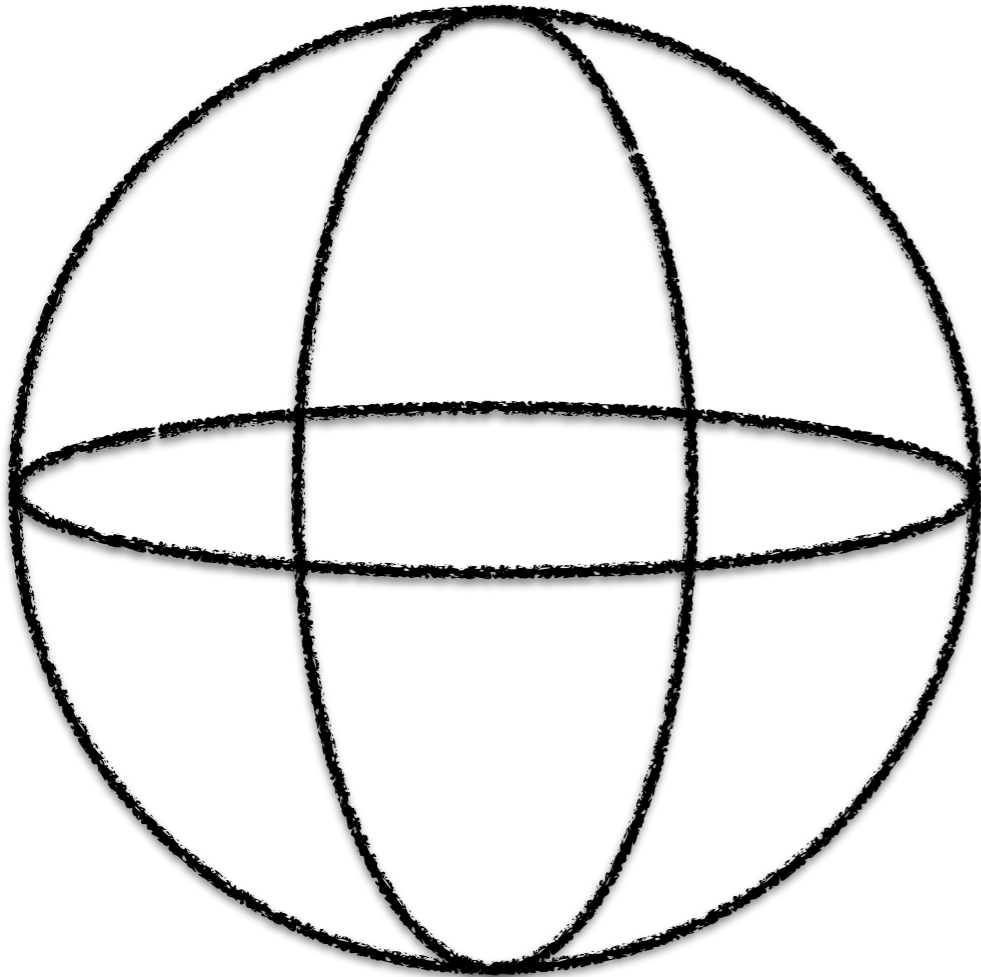
$$H_{e,i}(n_e [r, \theta_i, \phi_i])$$

$$H_{\nu\nu,i}(r, \theta_i, \phi_i, \sum_j n_{\nu,j} \psi_{\nu,j} \psi_{\nu,j}^\dagger [r, E_j, \theta_j, \phi_j])$$

Nature only helps a bit, we still have 6 dimensions to deal with!

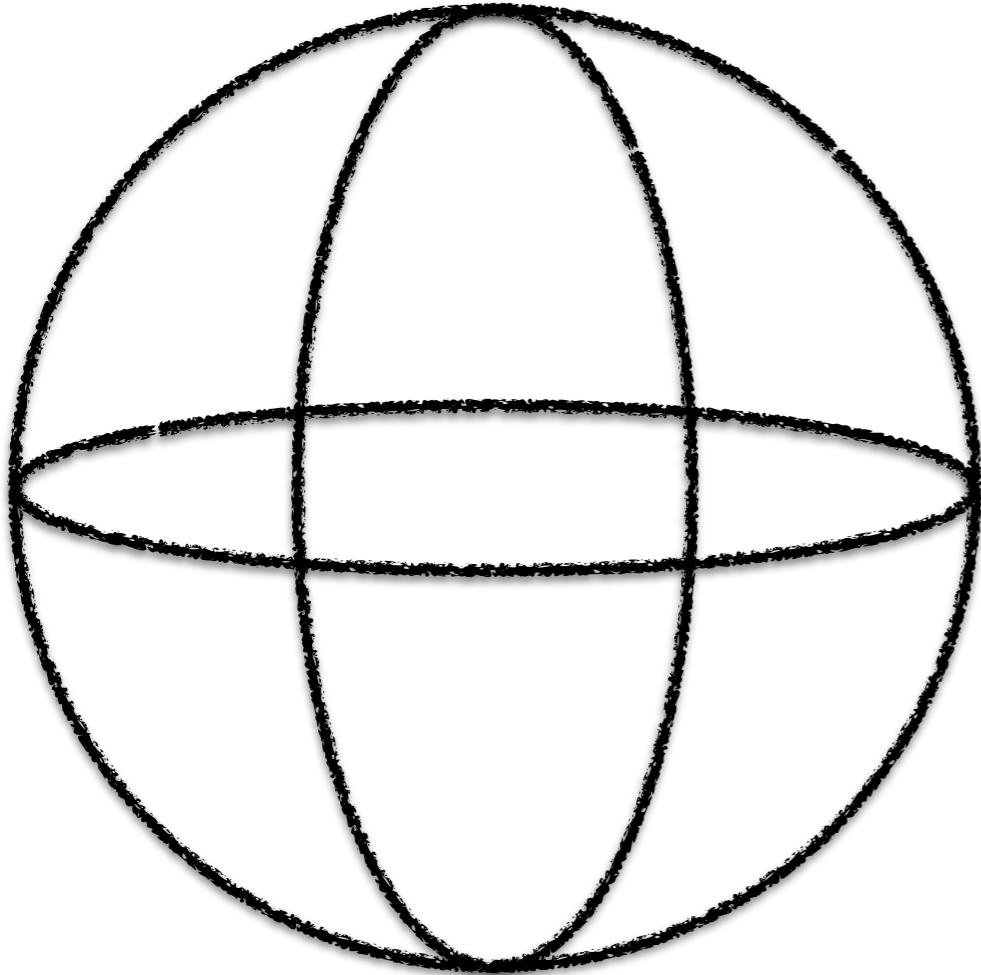
Spherical Symmetry is our Friend

$$H_{e,i}(n_e [r, \theta_i, \phi_i])$$



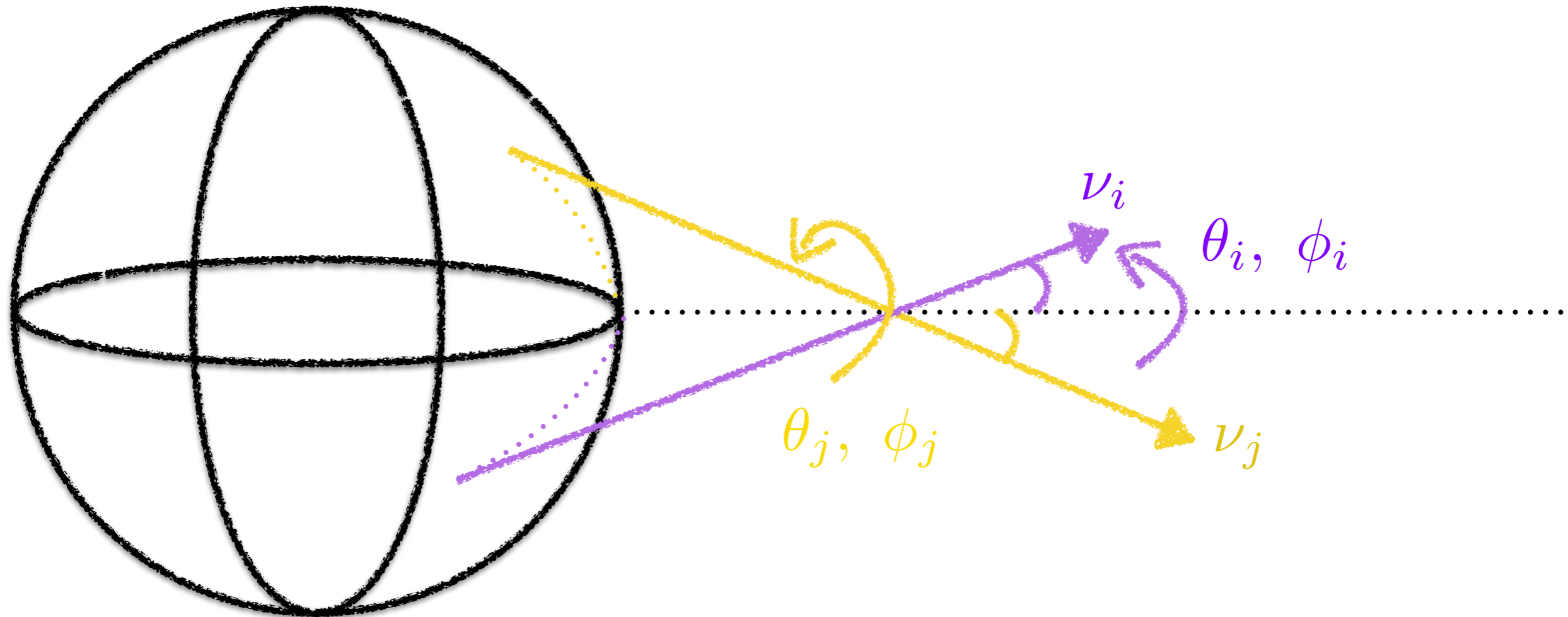
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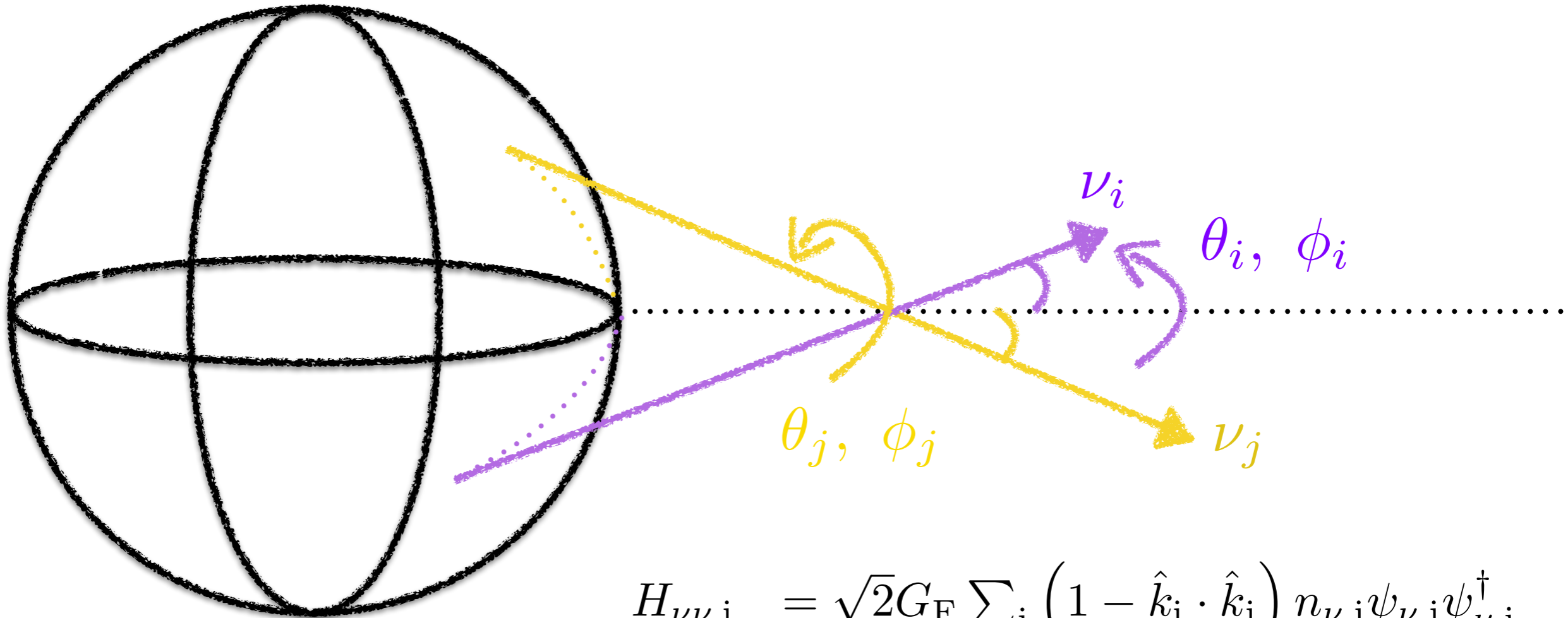
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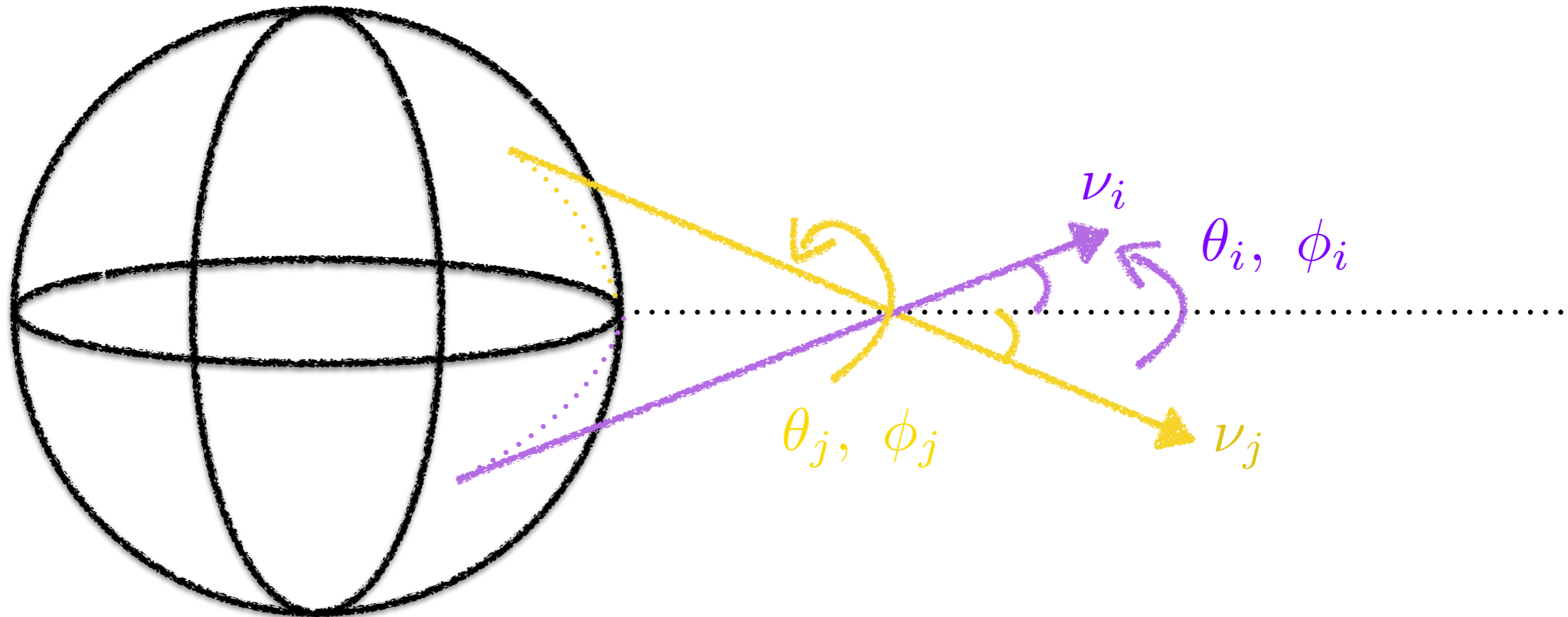


$$H_{\nu\nu,i} = \sqrt{2}G_F \sum_j \left(1 - \hat{k}_i \cdot \hat{k}_j\right) n_{\nu,j} \psi_{\nu,j} \psi_{\nu,j}^\dagger - \sqrt{2}G_F \sum_j \left(1 - \hat{k}_i \cdot \hat{k}_j\right) n_{\bar{\nu},j} \psi_{\bar{\nu},j} \psi_{\bar{\nu},j}^\dagger$$

\uparrow
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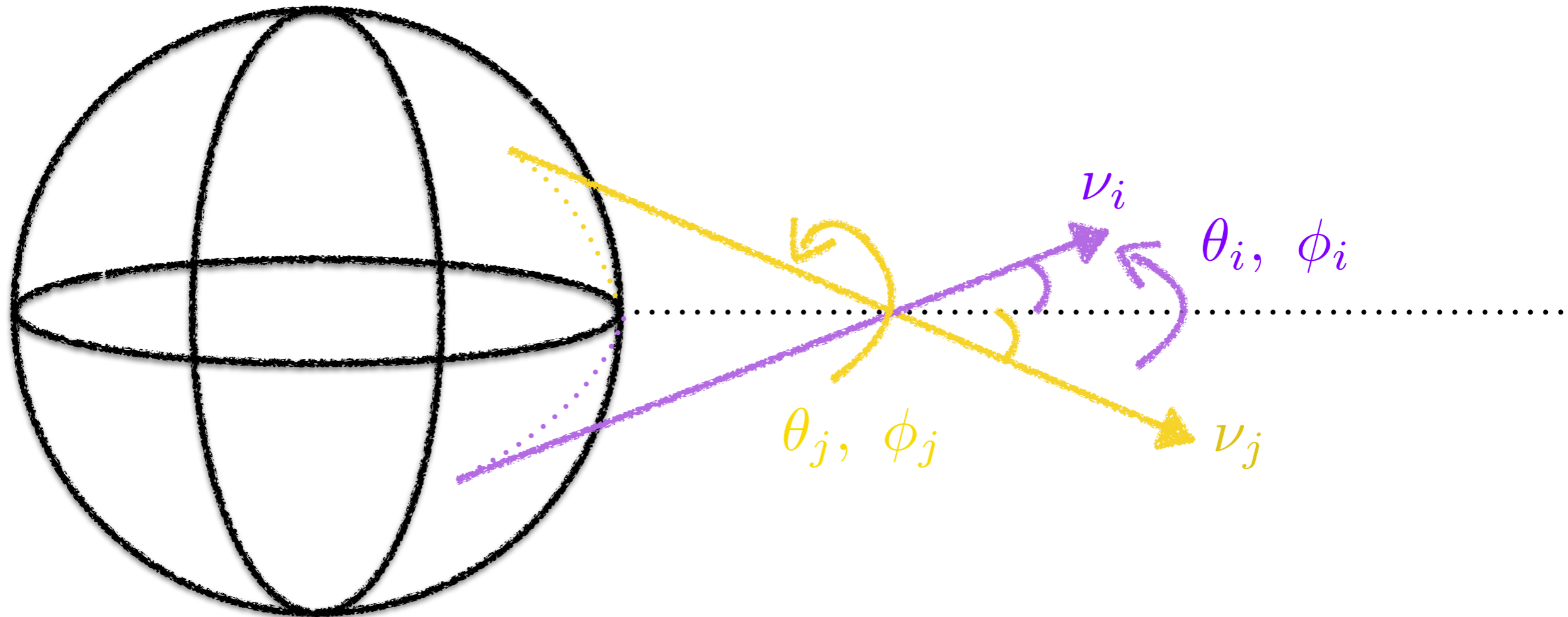
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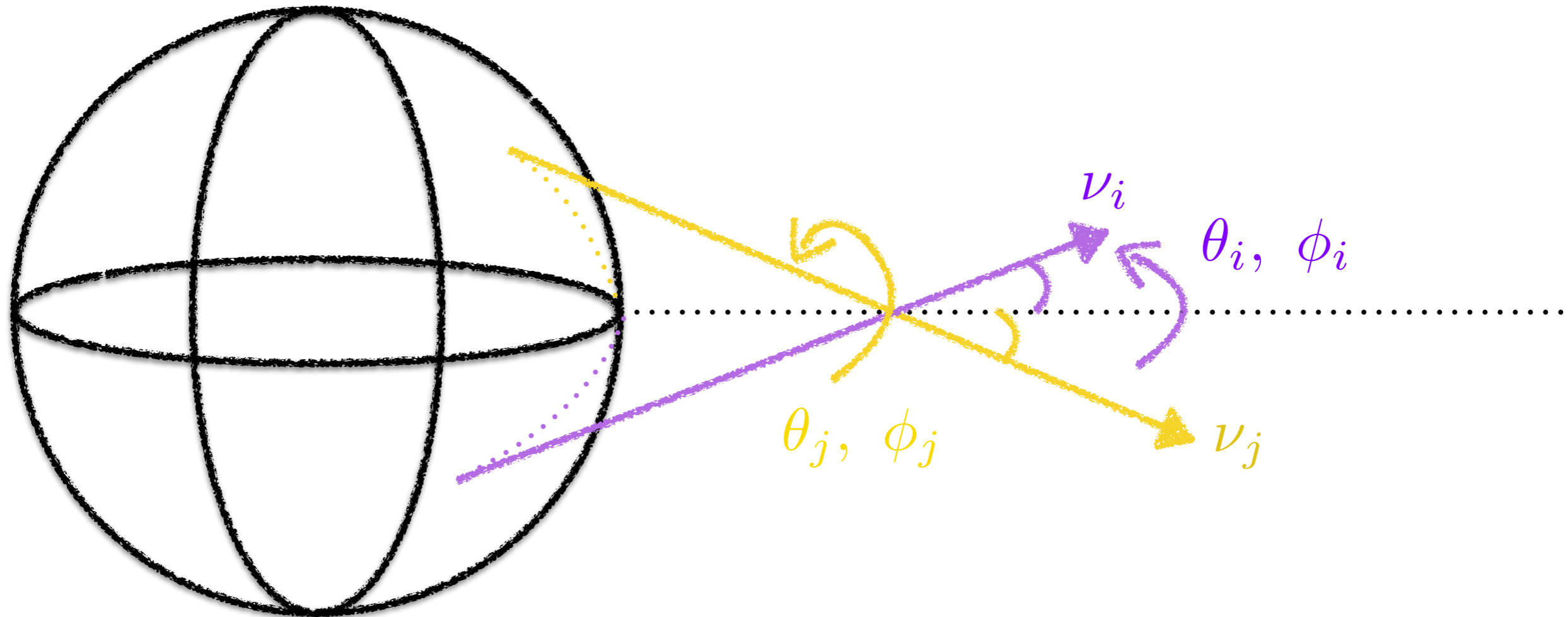
$$H_{e,i}(n_e [r, \cancel{\theta_i}, \cancel{\phi_i}])$$



$$\hat{k}_i \cdot \hat{k}_j = \cos \theta_i \cos \theta_j + \sin \theta_i \sin \theta_j (\cos \phi_i \cos \phi_j + \sin \phi_i \sin \phi_j)$$

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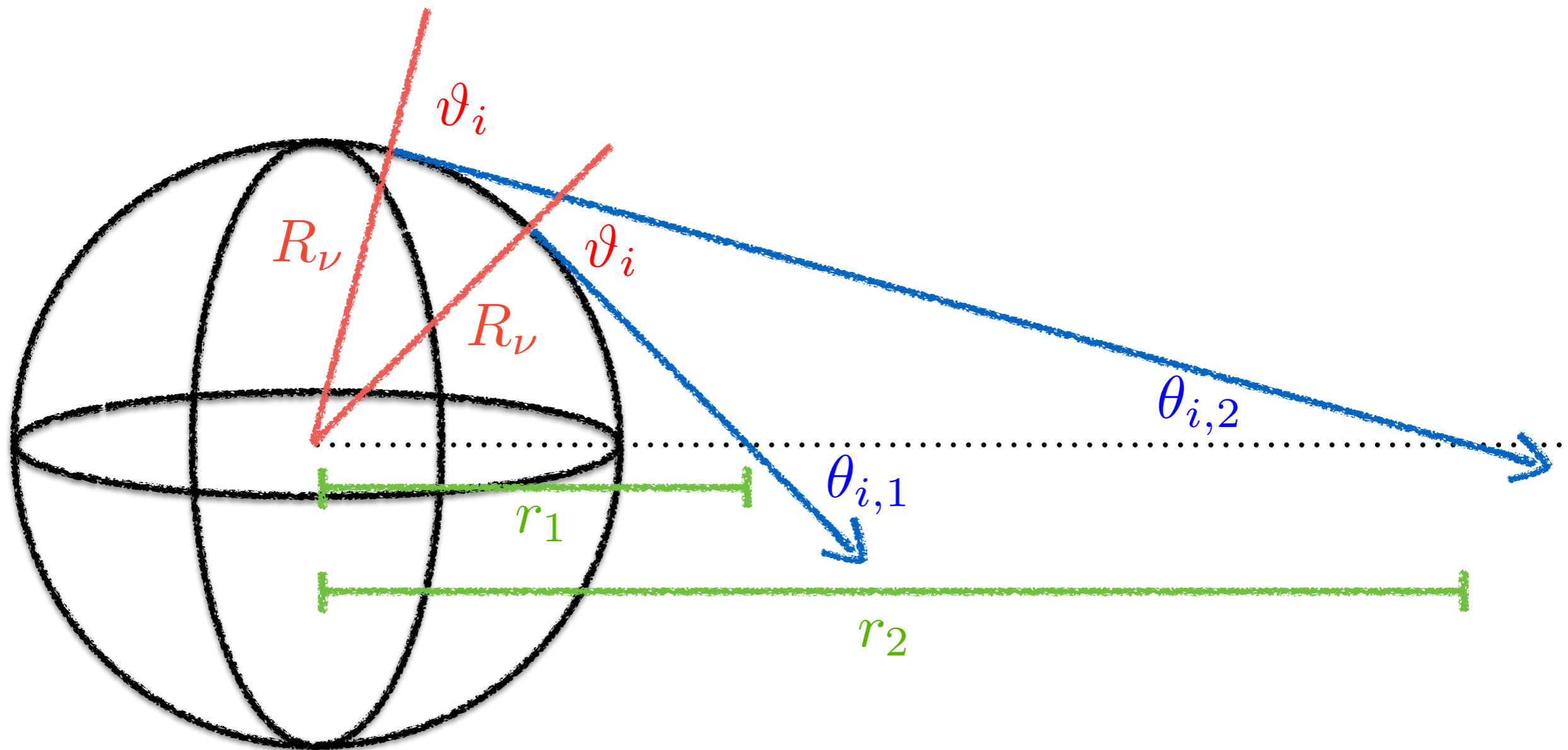
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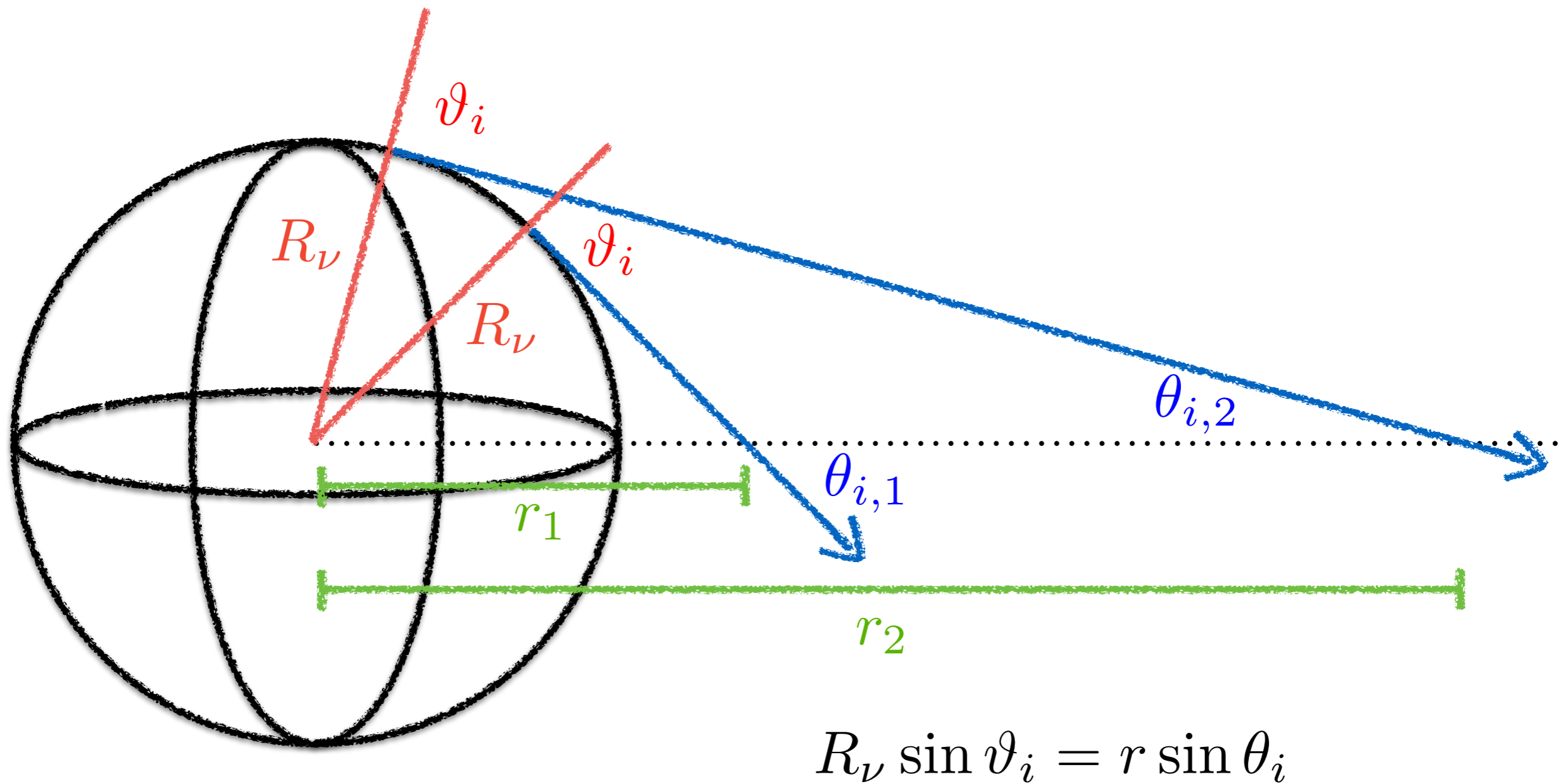
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$$\frac{1}{2\pi} \int_0^{2\pi} \hat{k}_i \cdot \hat{k}_j d\phi_j = \cos \theta_i \cos \theta_j$$

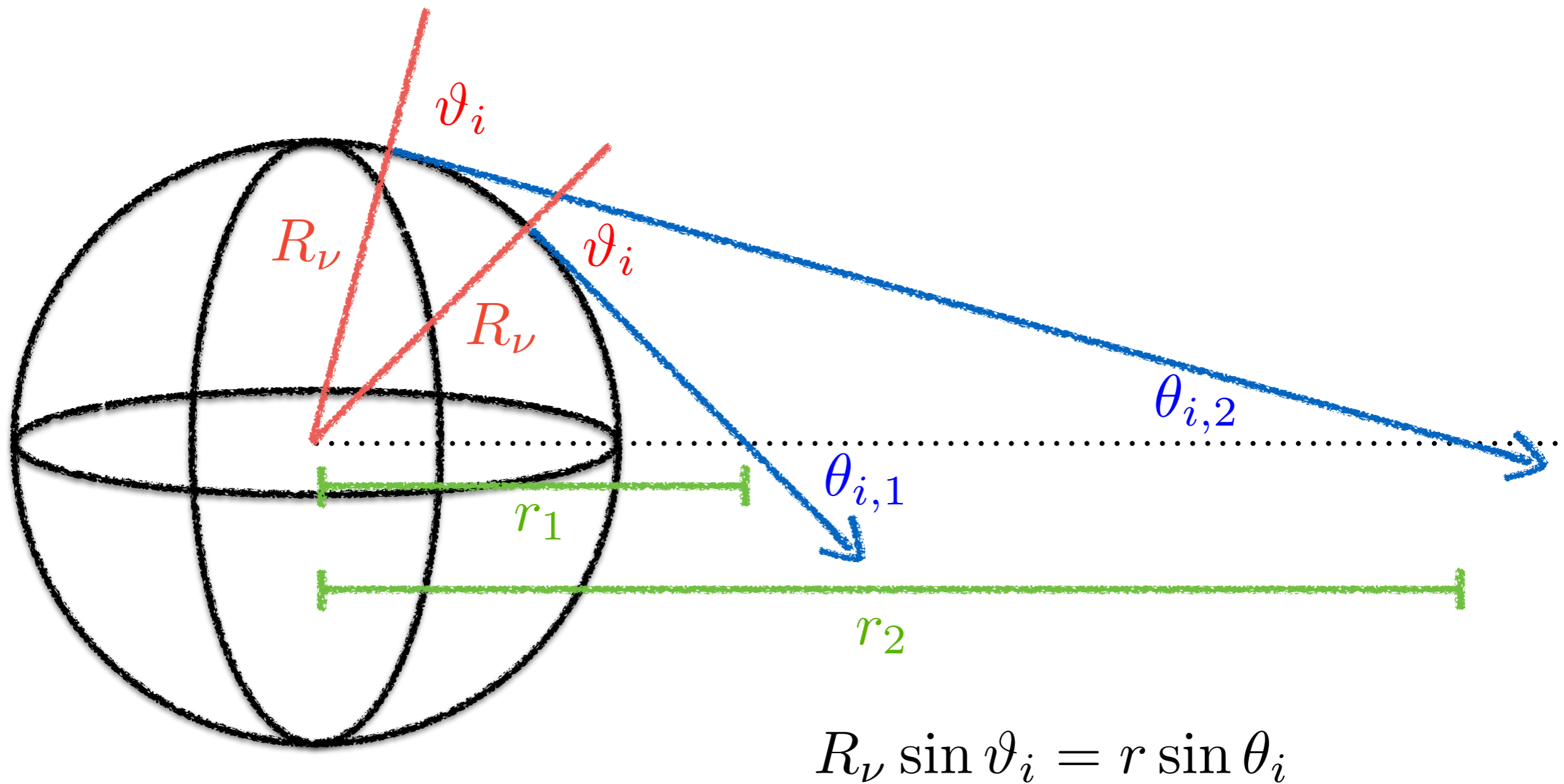
Basic Trigonometry is our Friend, as well



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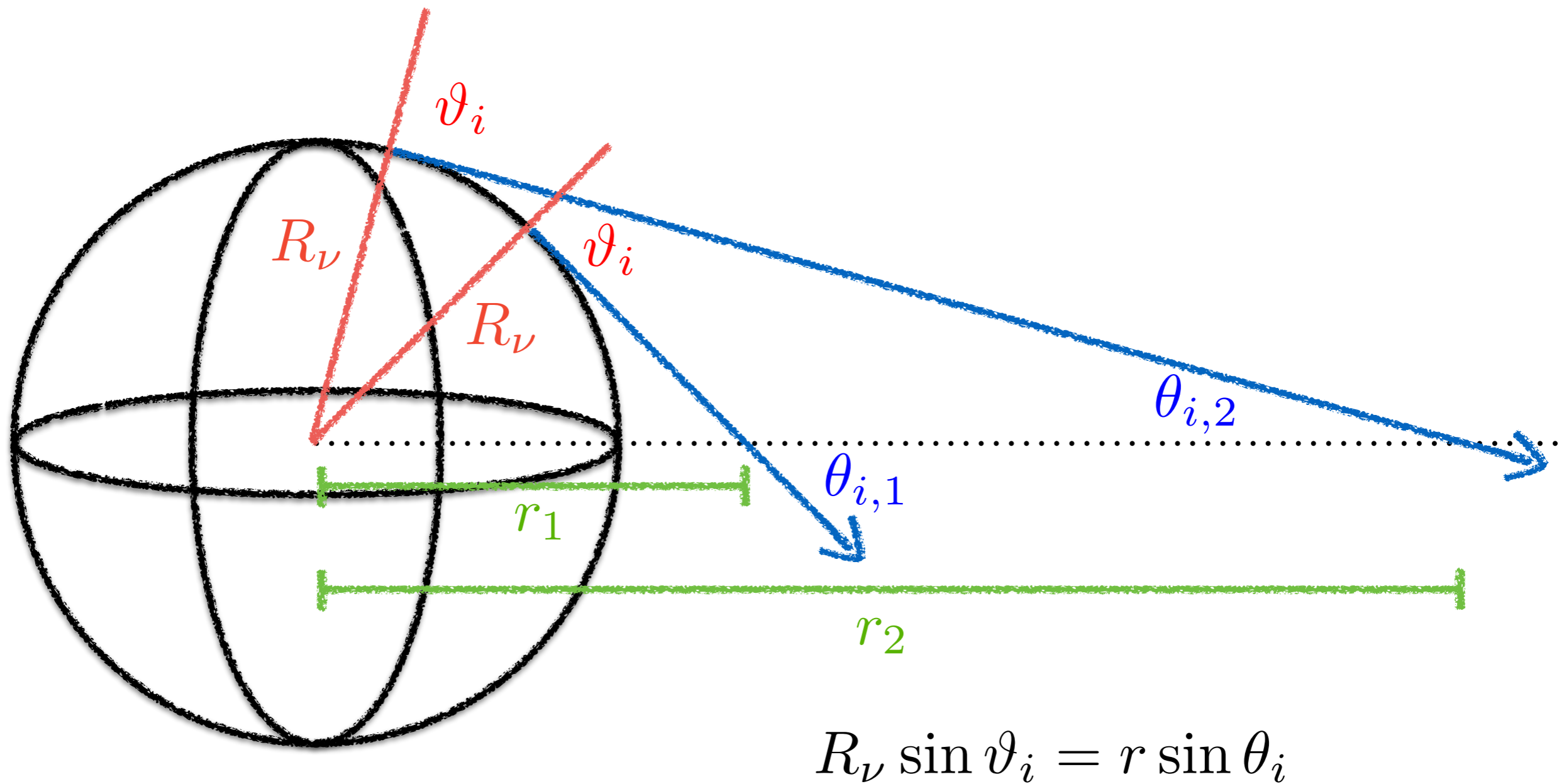


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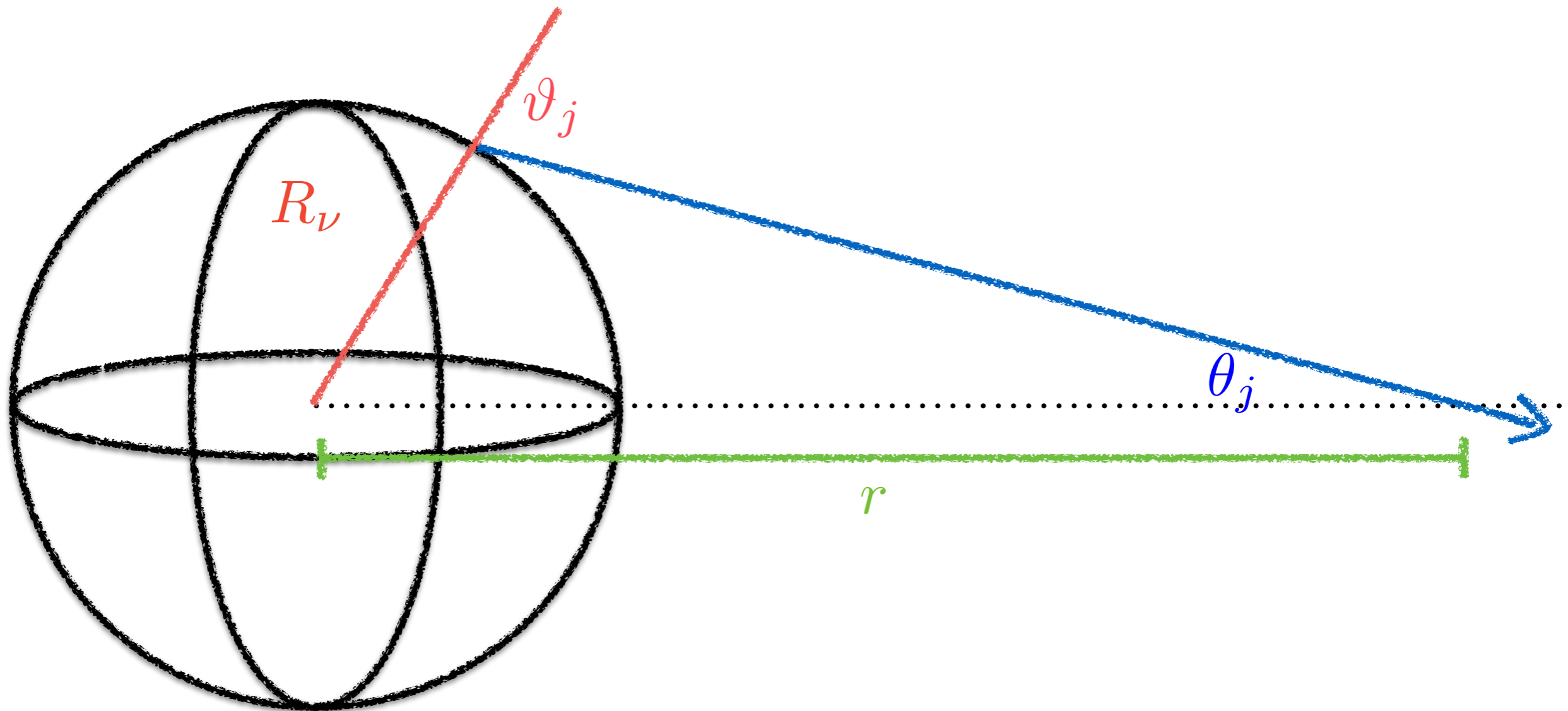
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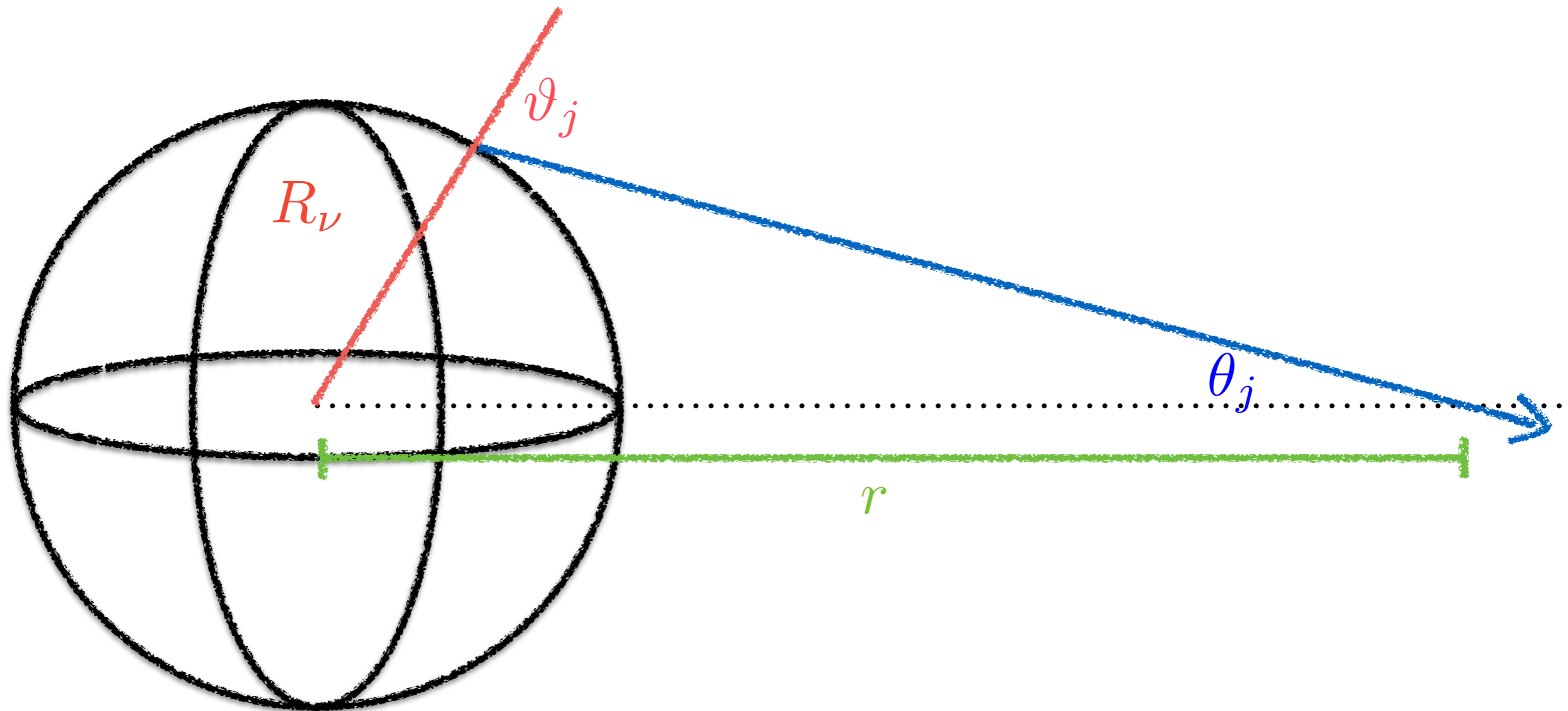


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Basic Trigonometry is our Friend, Part 2

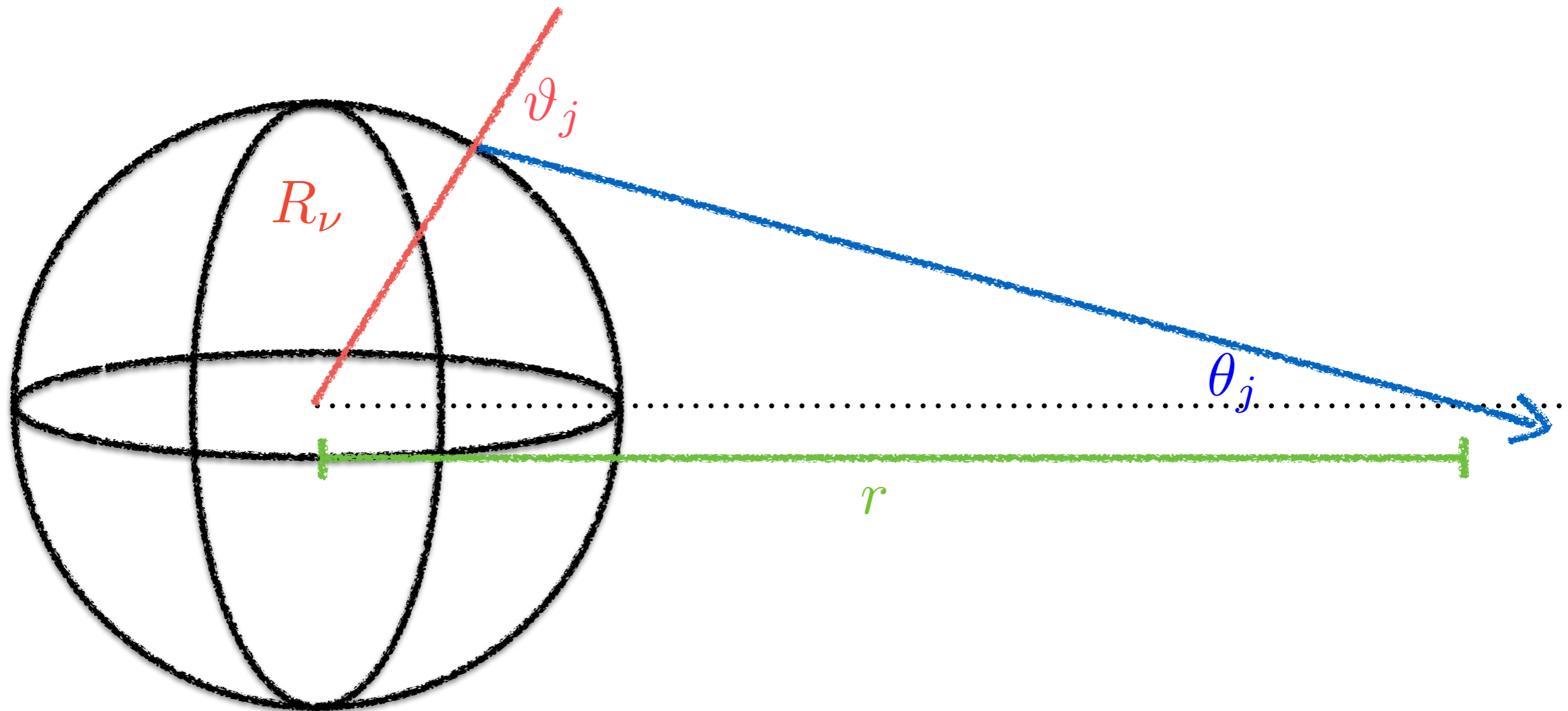


Basic Trigonometry is our Friend, Part 2



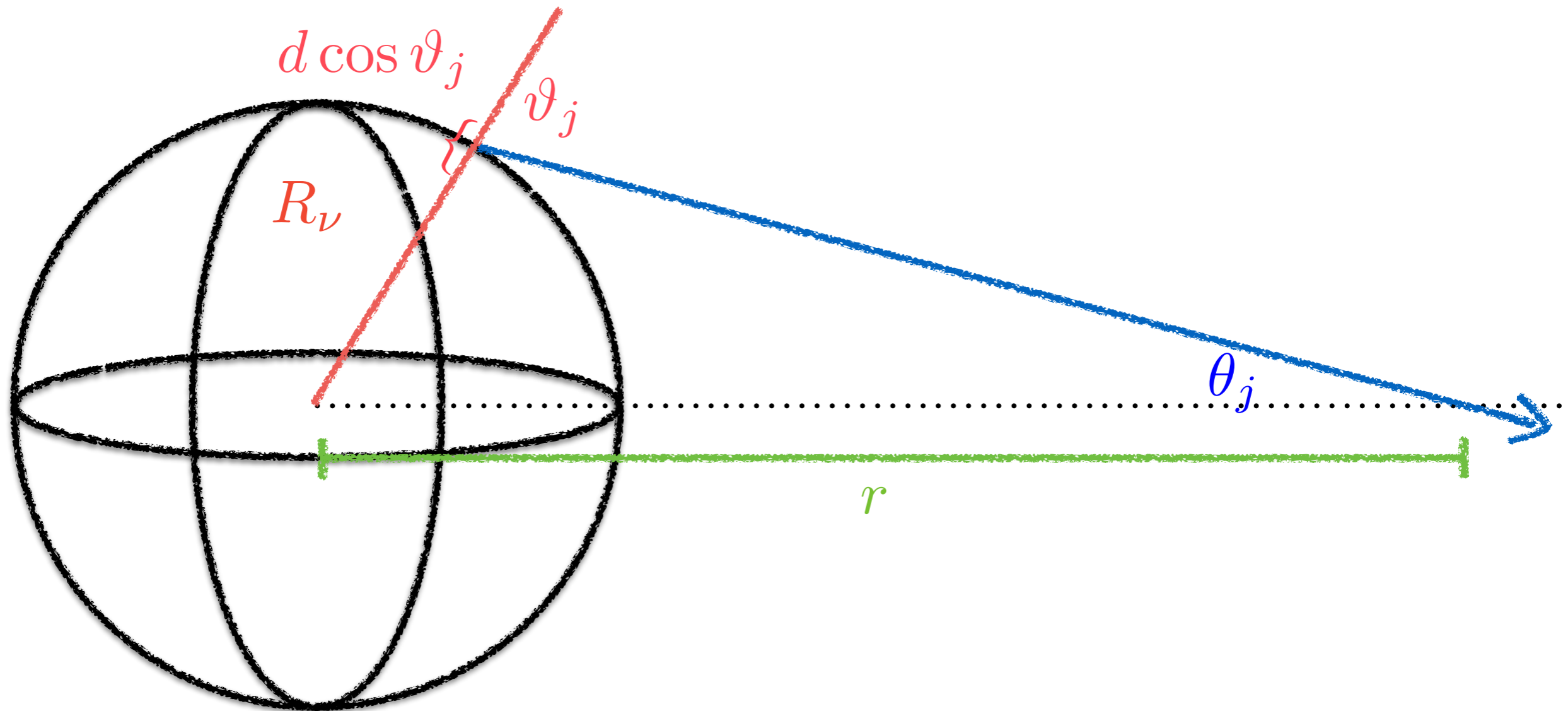
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Basic Trigonometry is our Friend, Part 2



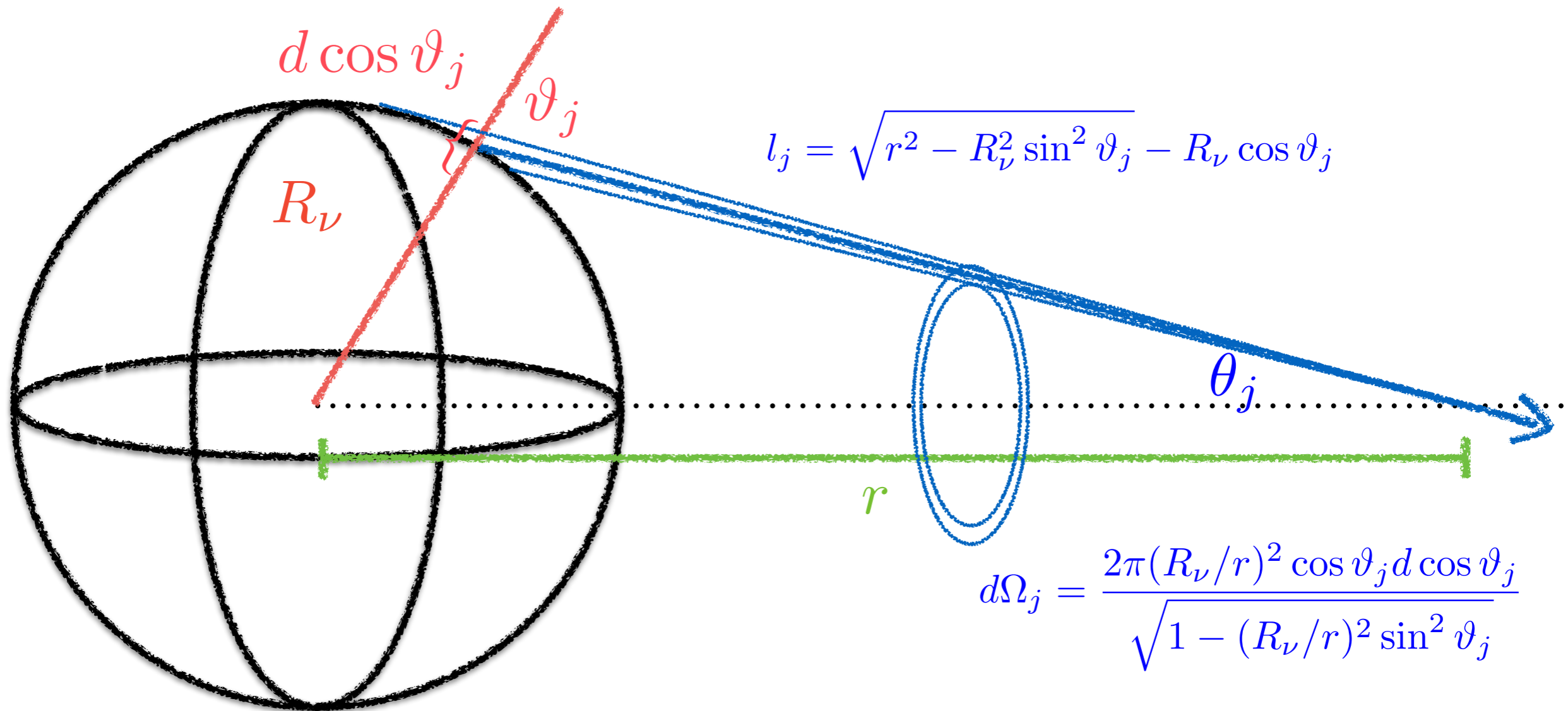
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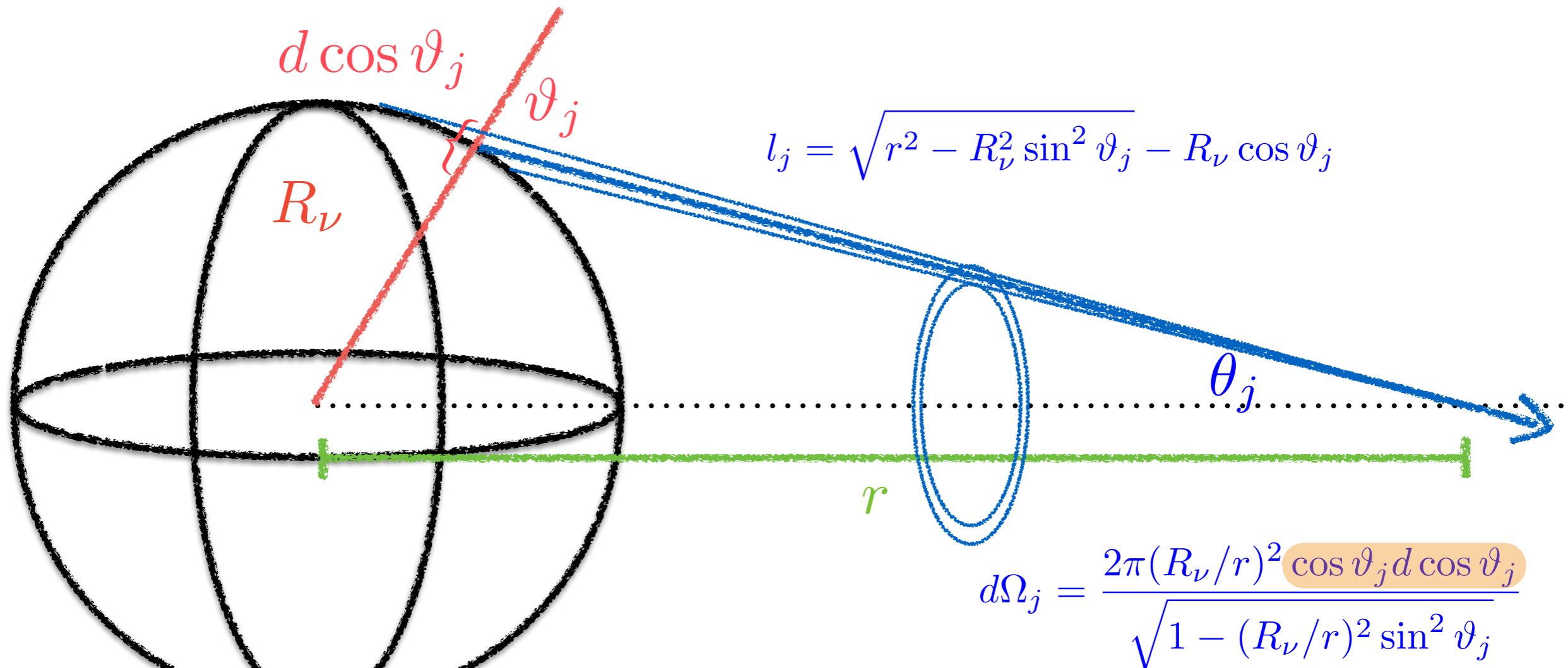
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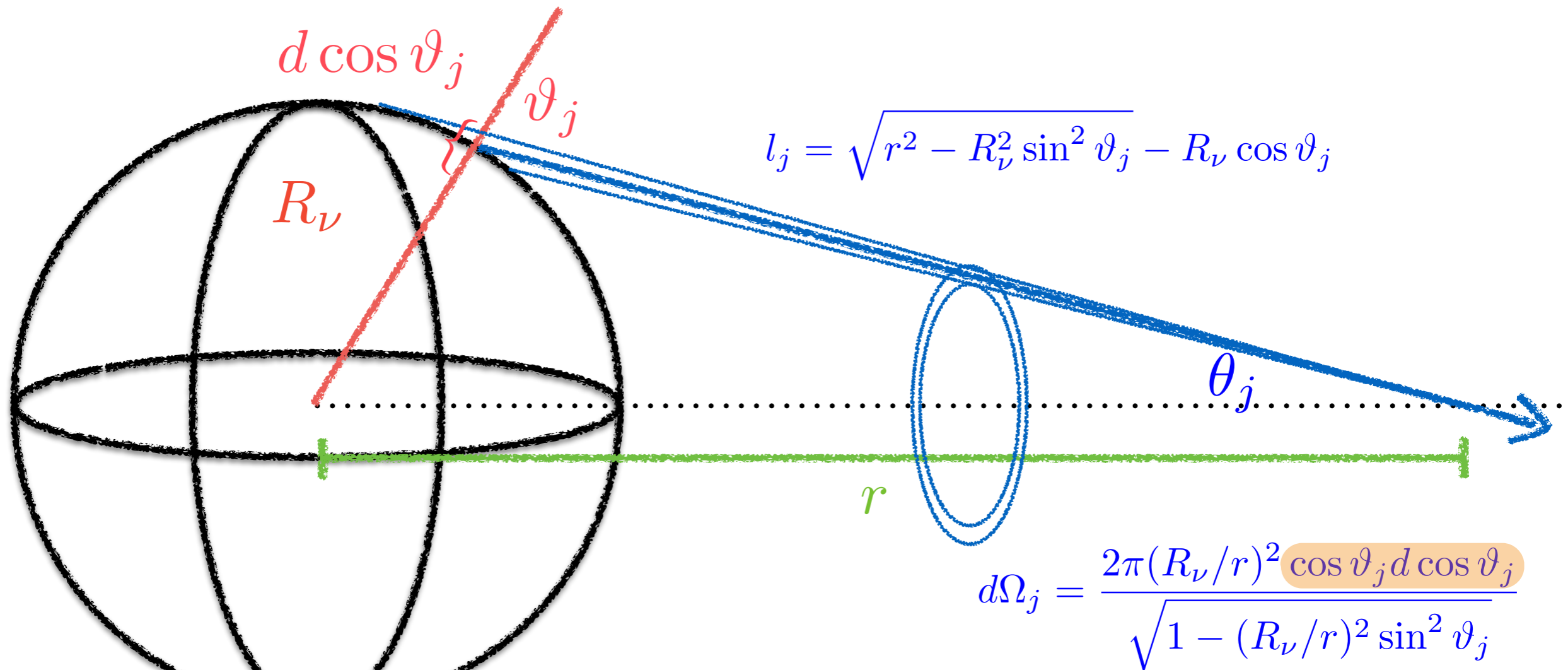
Basic Trigonometry is our Friend, Part 2



Big Hint: bin evenly in $\cos^2 \vartheta$

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explicit functions of r, ϑ_j, E_j

Re-examine our Variables

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Now this is becoming manageable.

Really, We're Down to 3 Dimensions

- The only dimensions left which might need fine resolution are r , E , and ϑ .
- The size of a single $\psi_{\nu,j}$ is set by the SU(3) symmetry of neutrino flavors: 288 bytes.
- The size of the system of coupled states we are solving is now $[\text{ncosth}, \text{negy}, 3, 3] \times 2$.
- ~ 100 kB per process, but ncosth^2 messages need to be passed ~ 100 GB message traffic per time step!

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$$H_{\nu\nu,i} = \sqrt{2}G_F \sum_j \left(1 - \hat{k}_i \cdot \hat{k}_j\right) n_{\nu,j} \psi_{\nu,j} \psi_{\nu,j}^\dagger - \sqrt{2}G_F \sum_j \left(1 - \hat{k}_i \cdot \hat{k}_j\right) n_{\bar{\nu},j} \psi_{\bar{\nu},j} \psi_{\bar{\nu},j}^\dagger$$

\uparrow
(1 - cos θ_{ij})

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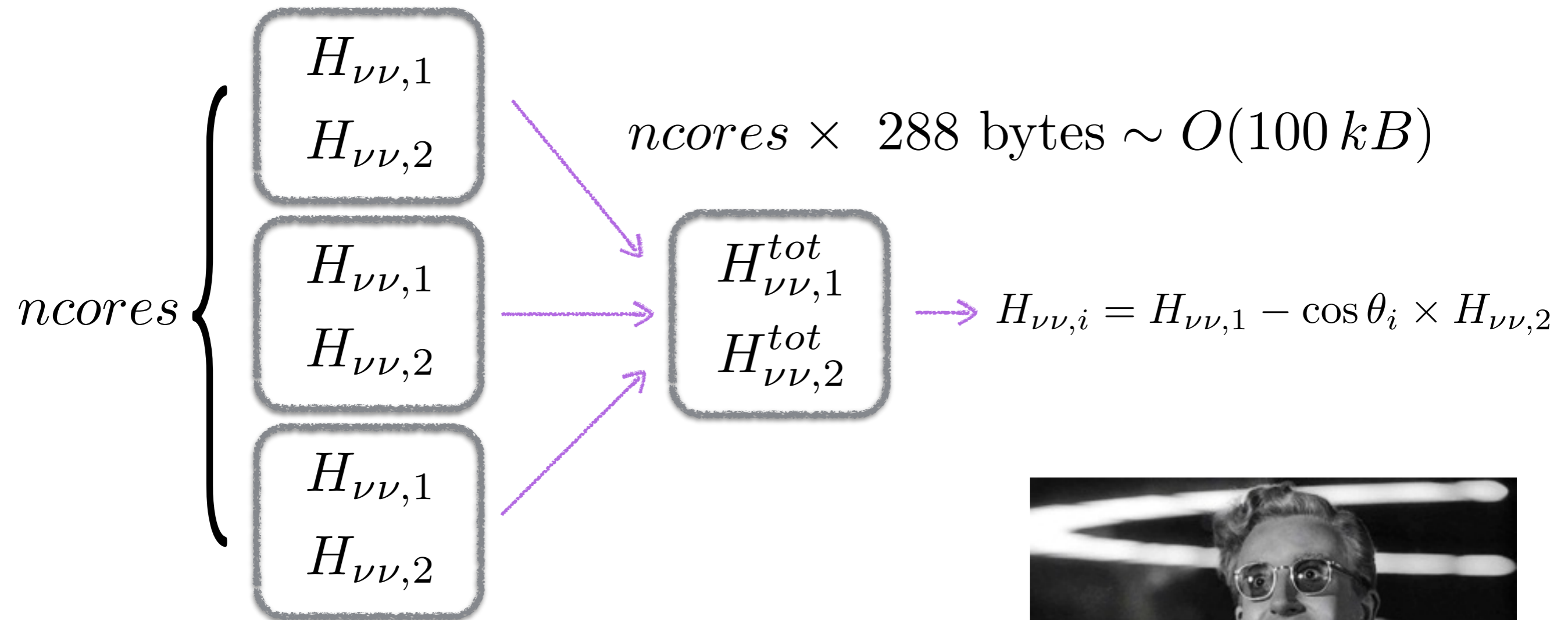
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 &\qquad\qquad\qquad \uparrow \\
 &\qquad\qquad\qquad (1 - \cos \theta_{ij}) \\
 &\qquad\qquad\qquad \uparrow \\
 &\qquad\qquad\qquad (1 - \cos \theta_i \cos \theta_j)
 \end{aligned}$$

Perform a partial sum locally

$$\left. \begin{aligned}
 H_{\nu\nu,1} &= \sqrt{2}G_F \sum_j \left(n_{\nu,j} \psi_{\nu,j} \psi_{\nu,j}^\dagger - n_{\bar{\nu},j} \psi_{\bar{\nu},j} \psi_{\bar{\nu},j}^\dagger \right) \\
 H_{\nu\nu,2} &= \sqrt{2}G_F \sum_j \cos \theta_j \left(n_{\nu,j} \psi_{\nu,j} \psi_{\nu,j}^\dagger - n_{\bar{\nu},j} \psi_{\bar{\nu},j} \psi_{\bar{\nu},j}^\dagger \right)
 \end{aligned} \right\} 288 \text{ Bytes}$$

How I learned to stop worrying and love Allreduce()



Now we have this down to
single process sized problem

$$i \frac{\partial}{\partial t} \psi_{\nu,i} = (H_{\text{vac},i} + H_{e,i} + H_{\nu\nu,i}) \psi_{\nu,i}$$

Each set of equations is now down to 3X3 (X2) with
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$$\psi_n$$

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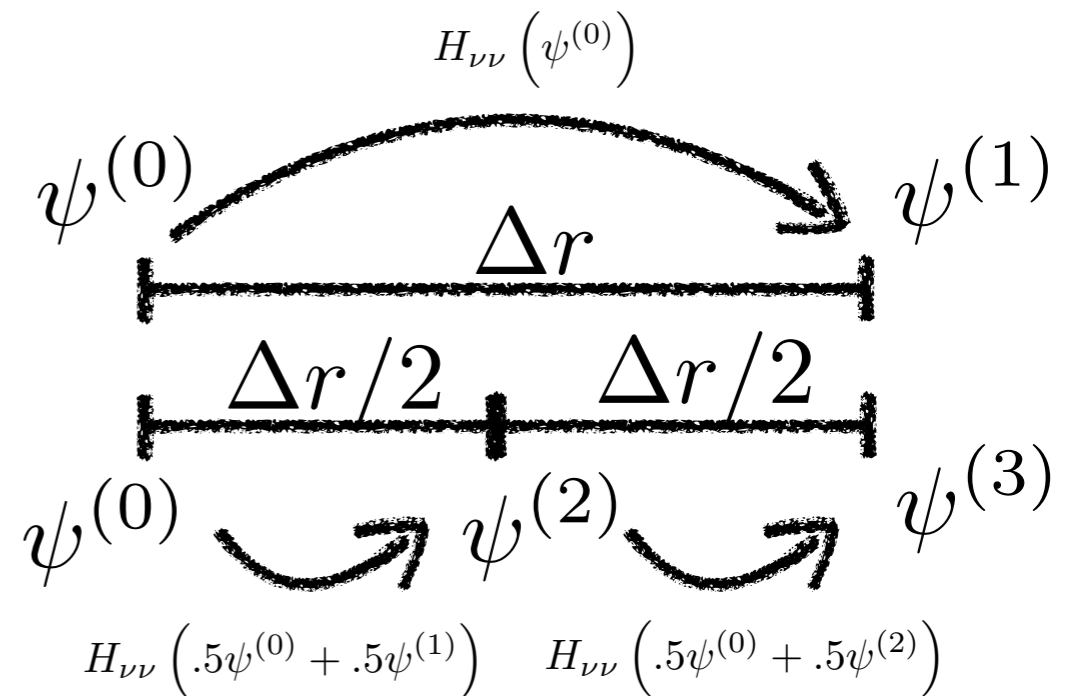


ψ_n

REJECTED

Why does the obvious thing fail?

- Basic Leapfrog algorithm:
- High frequency oscillations.



$$i \frac{d}{dt} \psi_{\nu,i} = H_{tot} \psi_{\nu,i} \implies \text{local solutions where } \omega_{osc} \propto \text{diag}(H_{tot})$$

$$l_{osc} = \frac{2\pi}{\omega_{osc}} \sim 10 \text{ cm} \quad R_{\text{Flavor Transformation}} \sim 10^3 \text{ km}$$

- This is bad news for tracking complex phases in wave functions

$$Err = \text{Re}(\psi^{(1)} - \psi^{(3)})^2 + \text{Im}(\psi^{(1)} - \psi^{(3)})^2 \sim \frac{\Delta r}{l_{osc}} \sim 10^{-6}$$

Find the Local Eigen Basis

$$i \frac{\partial}{\partial t} \psi_{\nu,i} = (H_{\text{vac},i} + H_{e,i} + H_{\nu\nu,i}) \psi_{\nu,i}$$

- Employ the Magnus method to work explicitly in the eigen basis of the local Hamiltonian.

$$\psi_{\nu,i}(r + \Delta r) \simeq \exp(-iH_{\nu,i}\Delta r)\psi_{\nu,i}(r)$$

$$\left. \begin{aligned} \sum_b H_{ab} V_{bc} &= \zeta_c V_{ac}, \quad a, b, c = 1, 2, 3 \\ \exp(-iH_{\nu,i}\Delta r) &= V \begin{pmatrix} e^{-i\zeta_1\Delta r} & 0 & 0 \\ 0 & e^{-i\zeta_2\Delta r} & 0 \\ 0 & 0 & e^{-i\zeta_3\Delta r} \end{pmatrix} V^\dagger \end{aligned} \right\} \begin{array}{l} \text{Computationally} \\ \text{expensive, but} \\ \text{potentially much} \\ \text{longer step size} \end{array}$$

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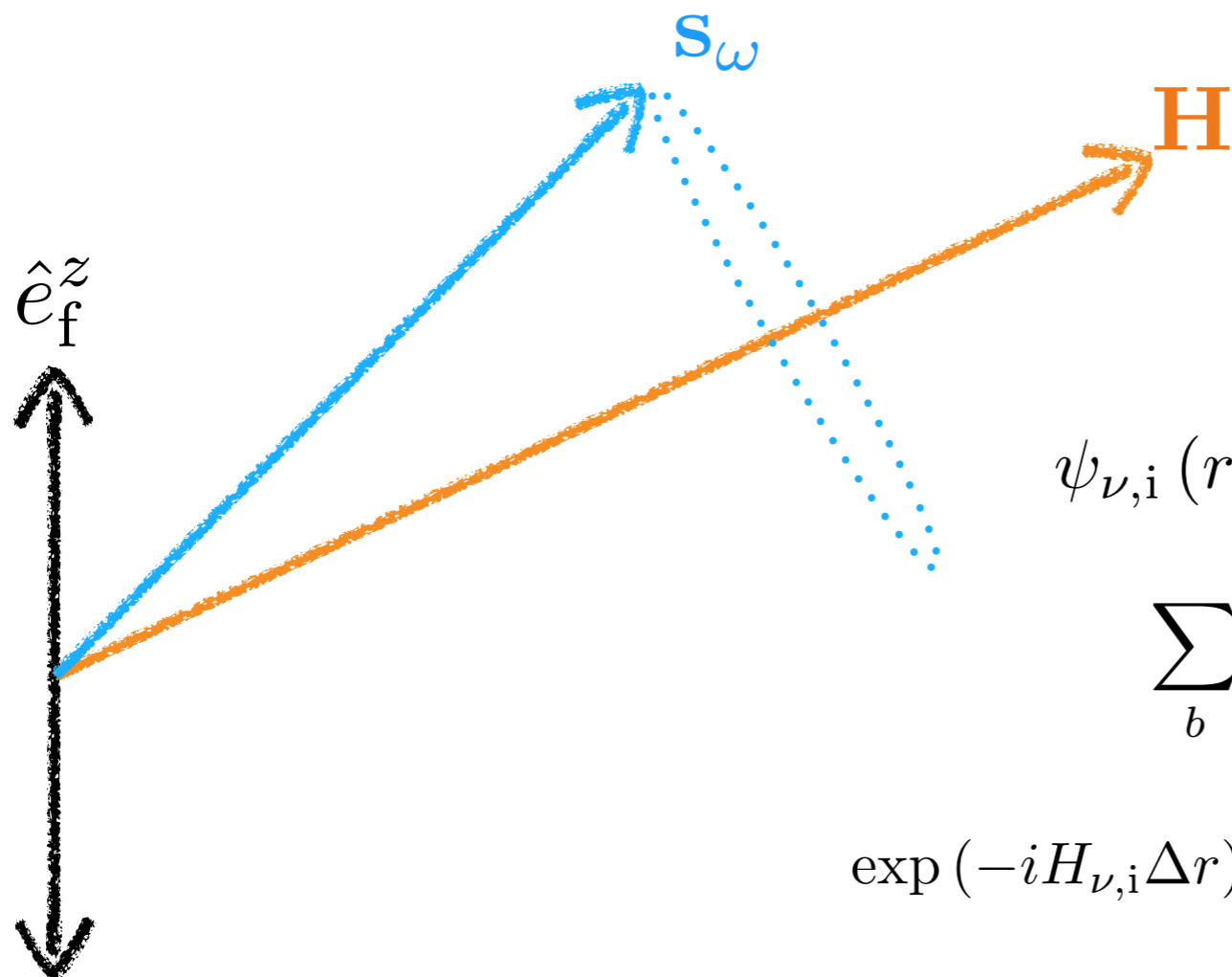
Poster Child for GPU implementable calculation (MAGMA)

Visualizing the Magnus Method

$$\mathbf{s}_\nu \equiv \psi_\nu^\dagger \frac{\boldsymbol{\sigma}}{2} \psi_\nu$$

$$SU(2) \rightarrow SO(3)$$

$$\frac{d}{dt} \mathbf{s} = \mathbf{s} \times \mathbf{H}$$



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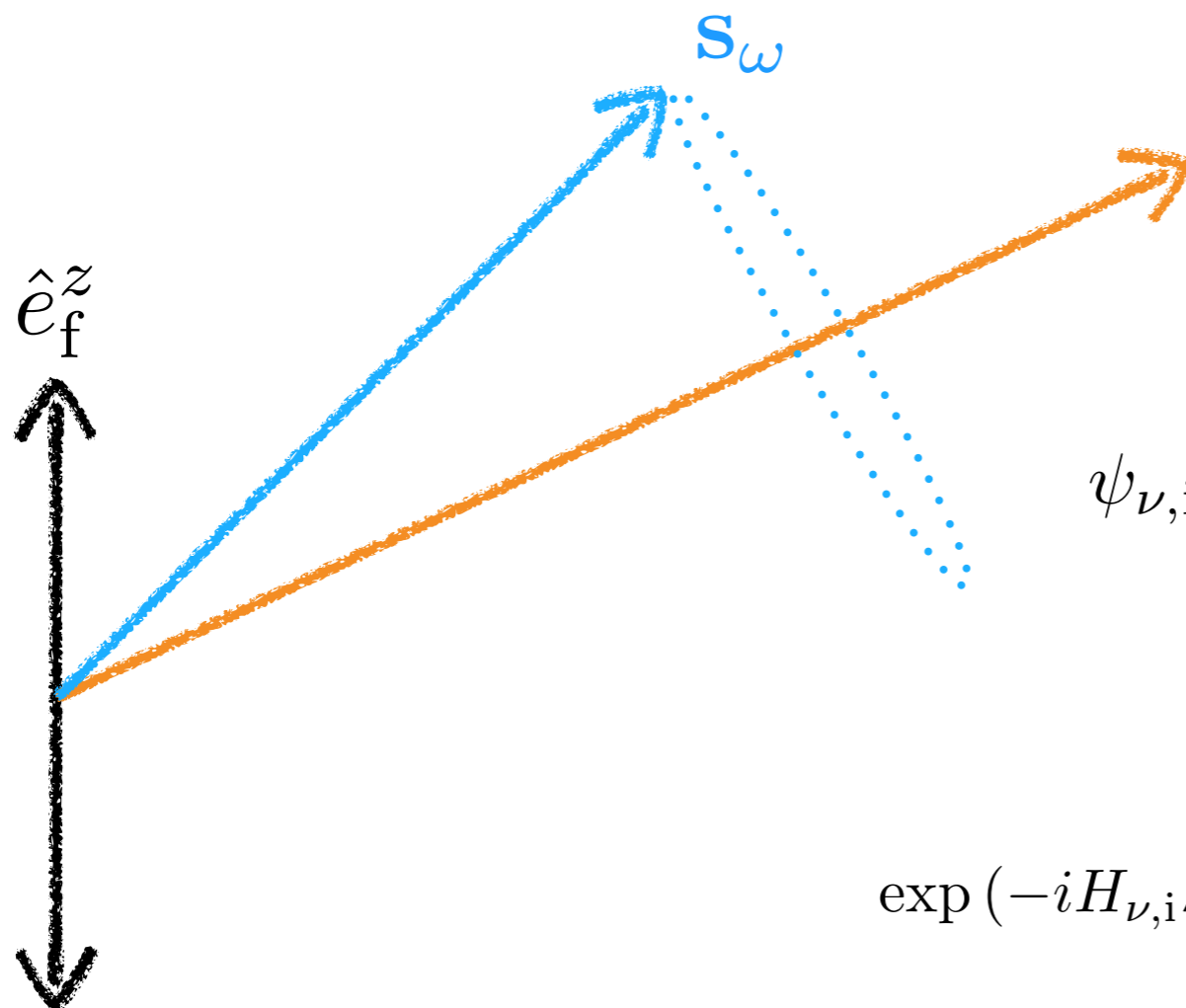
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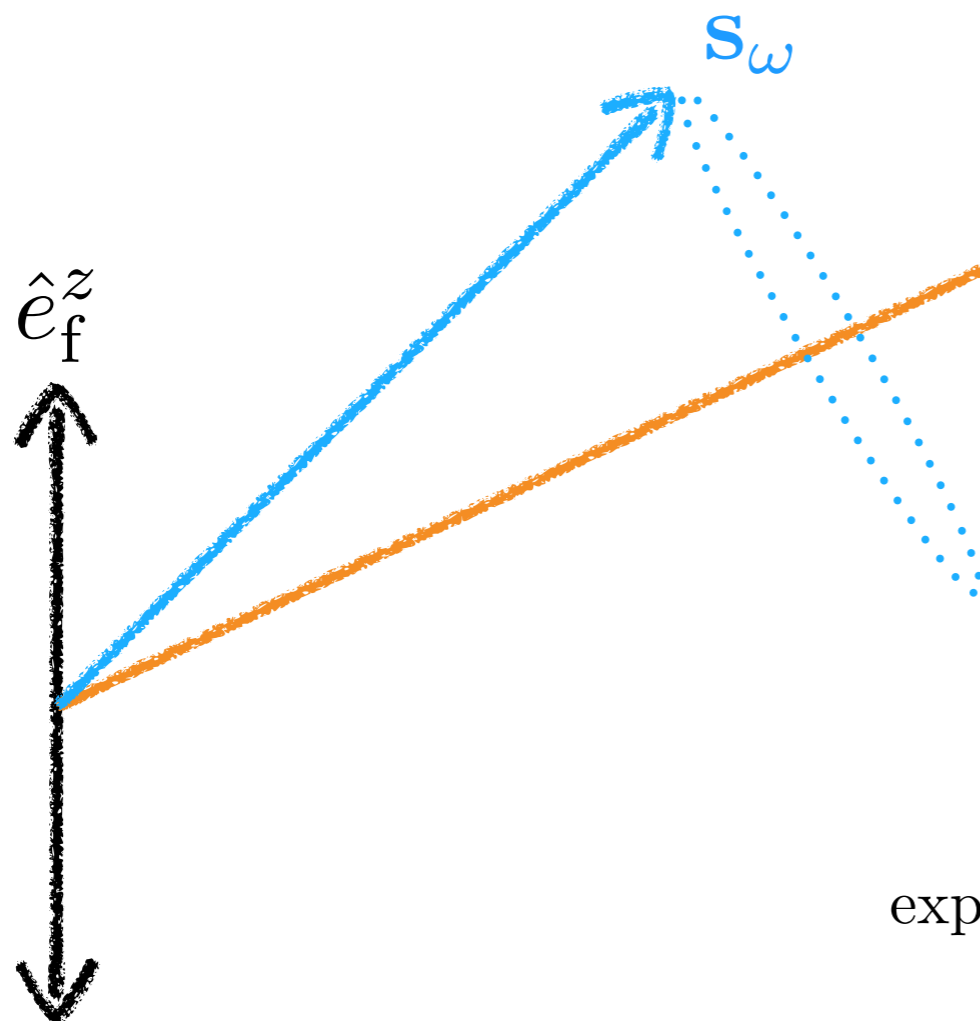
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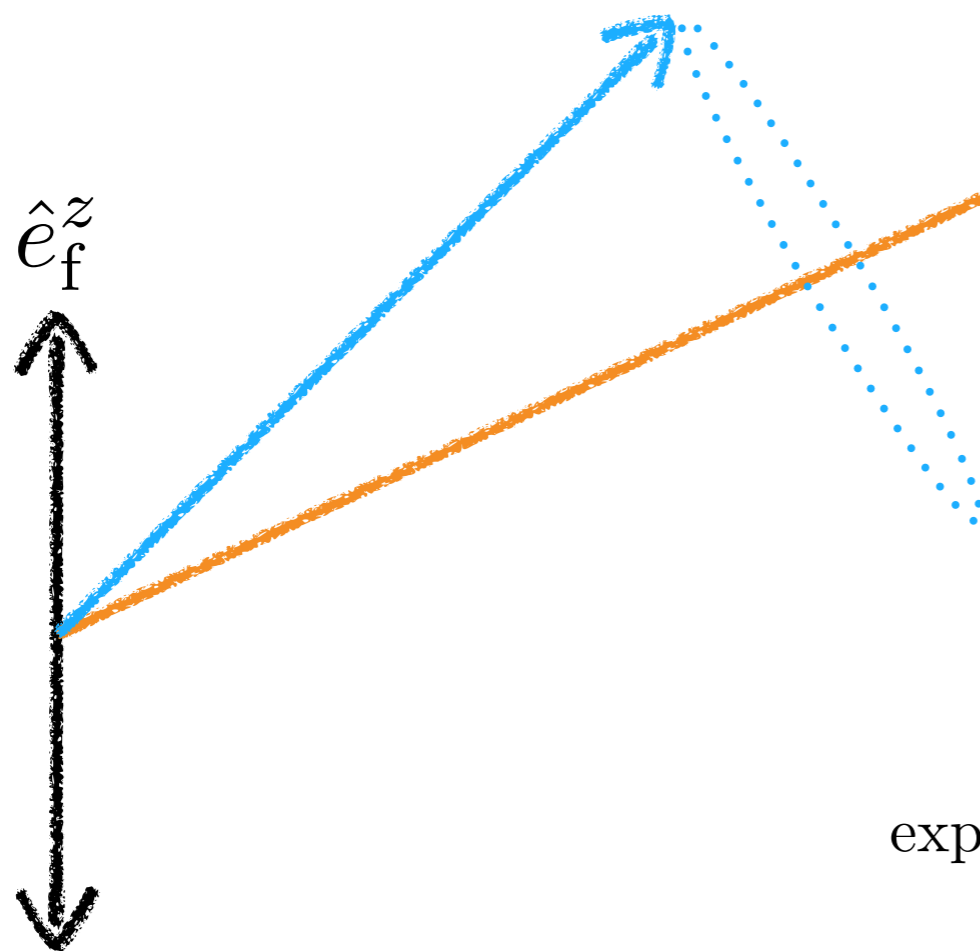
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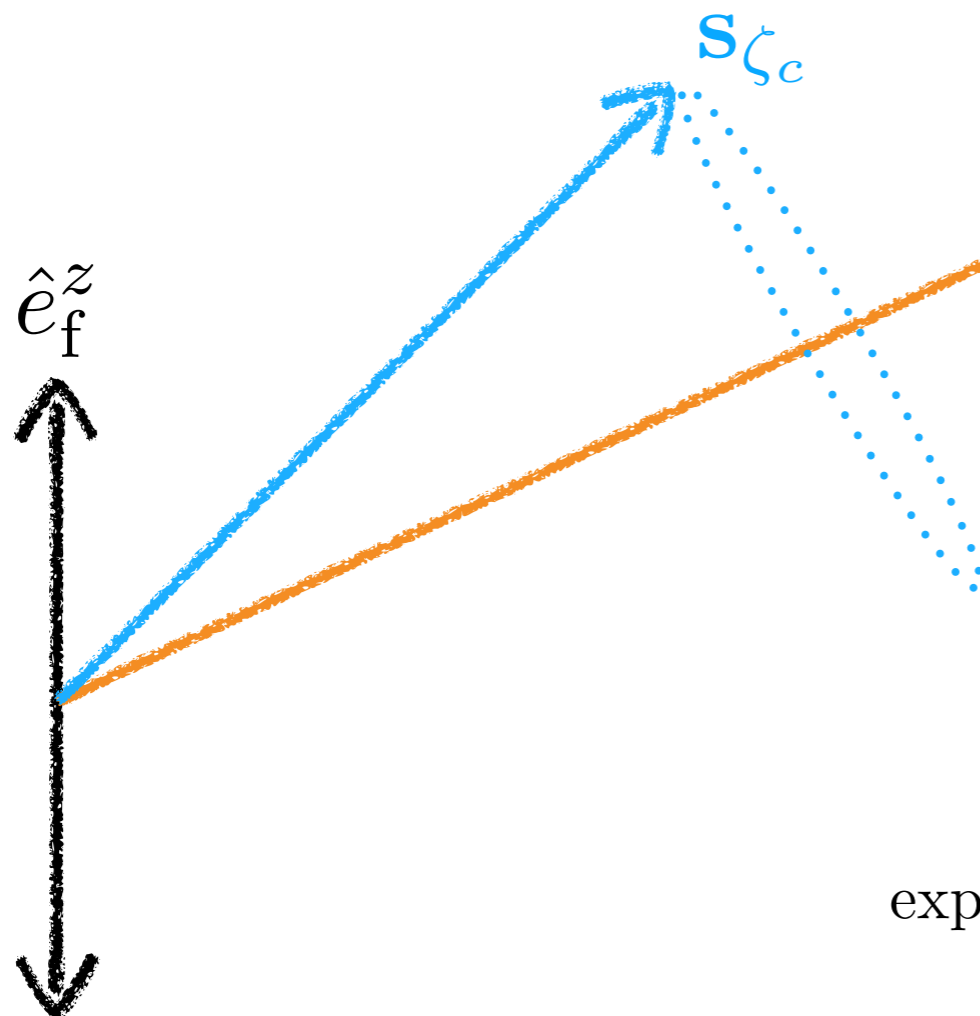
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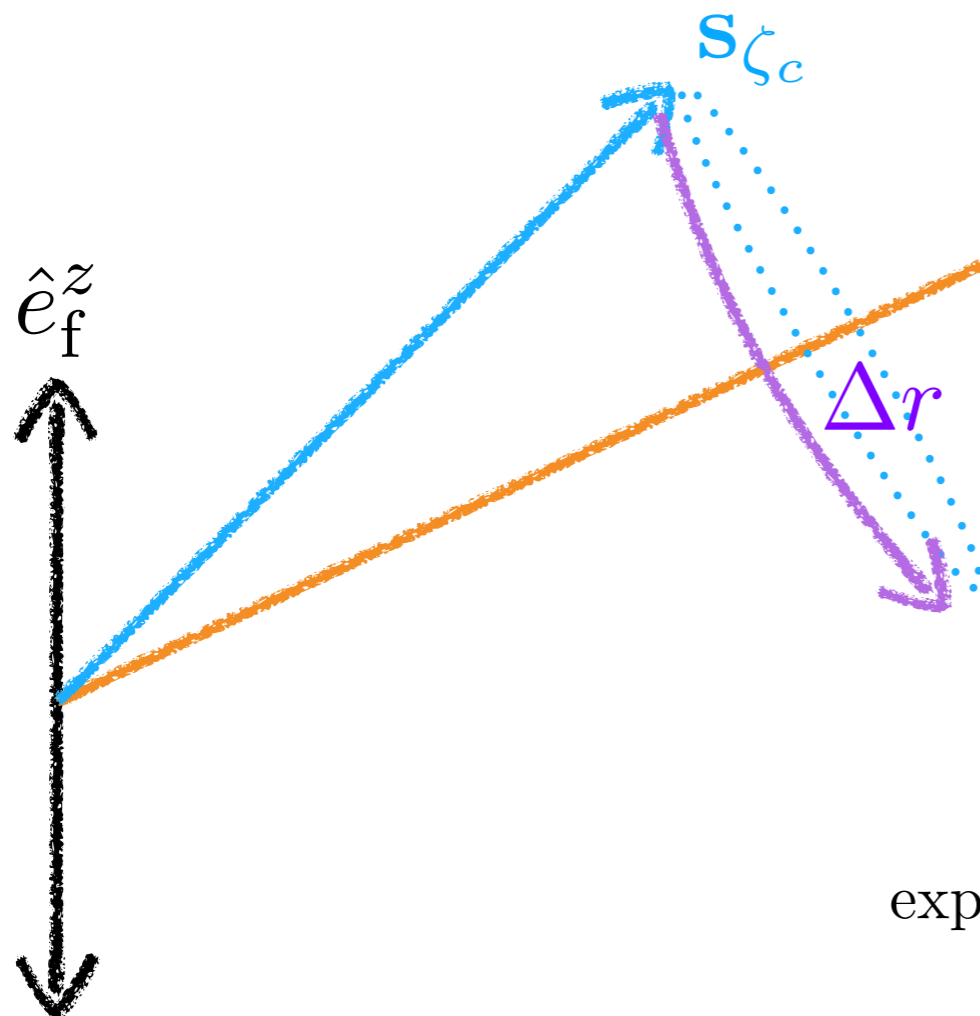
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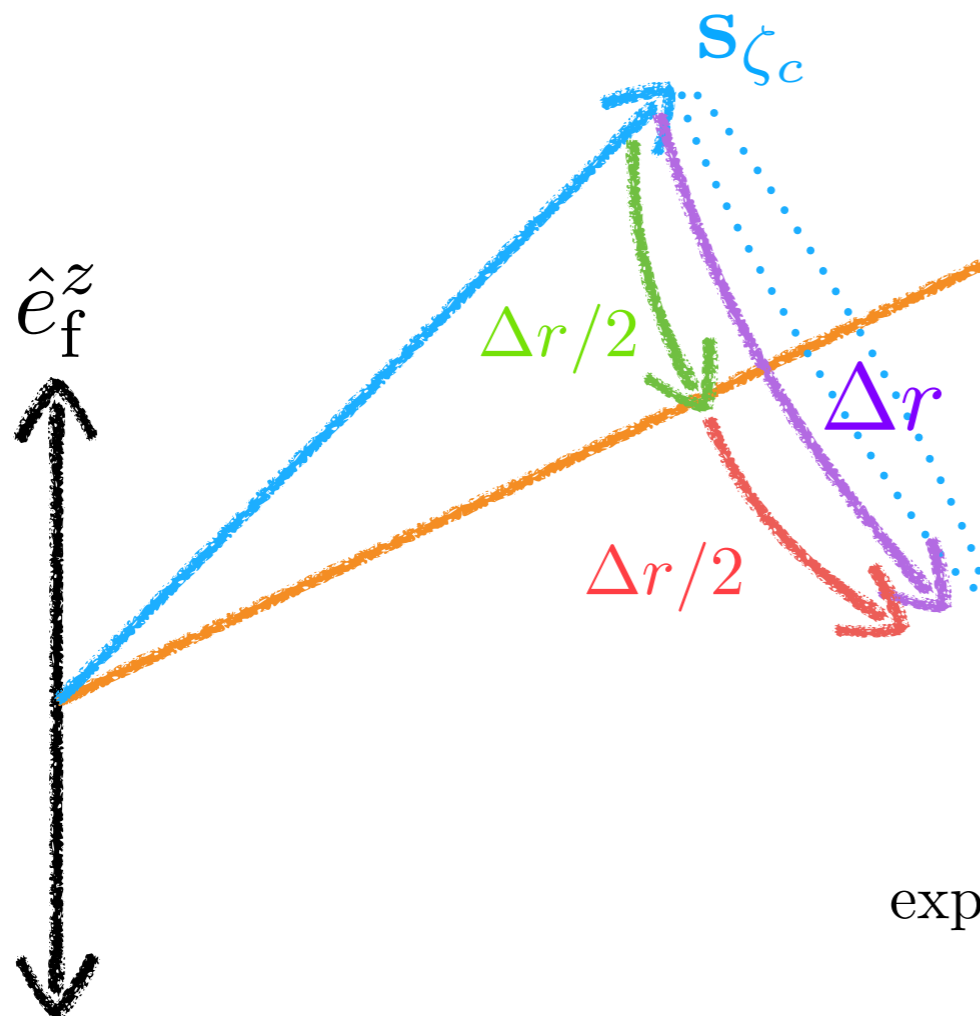
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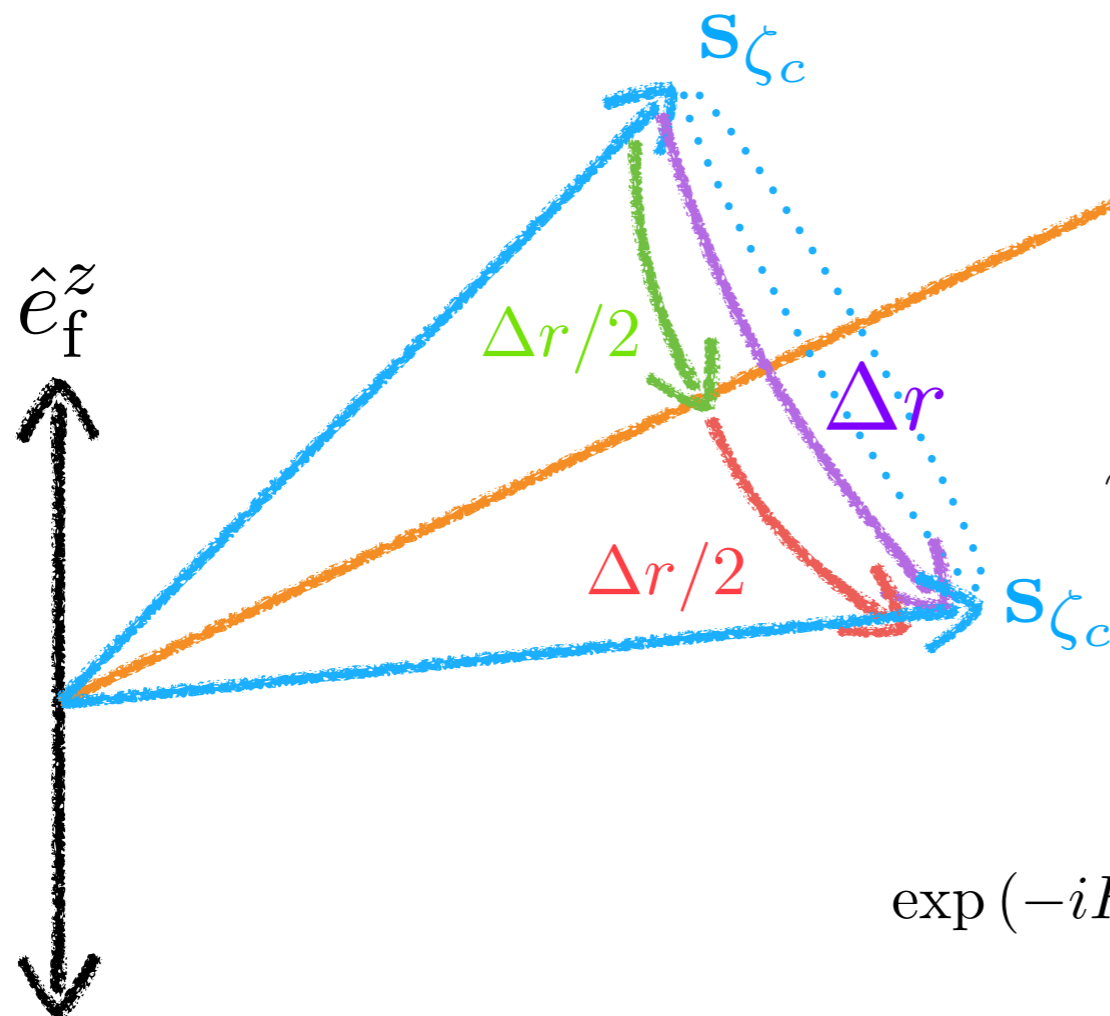
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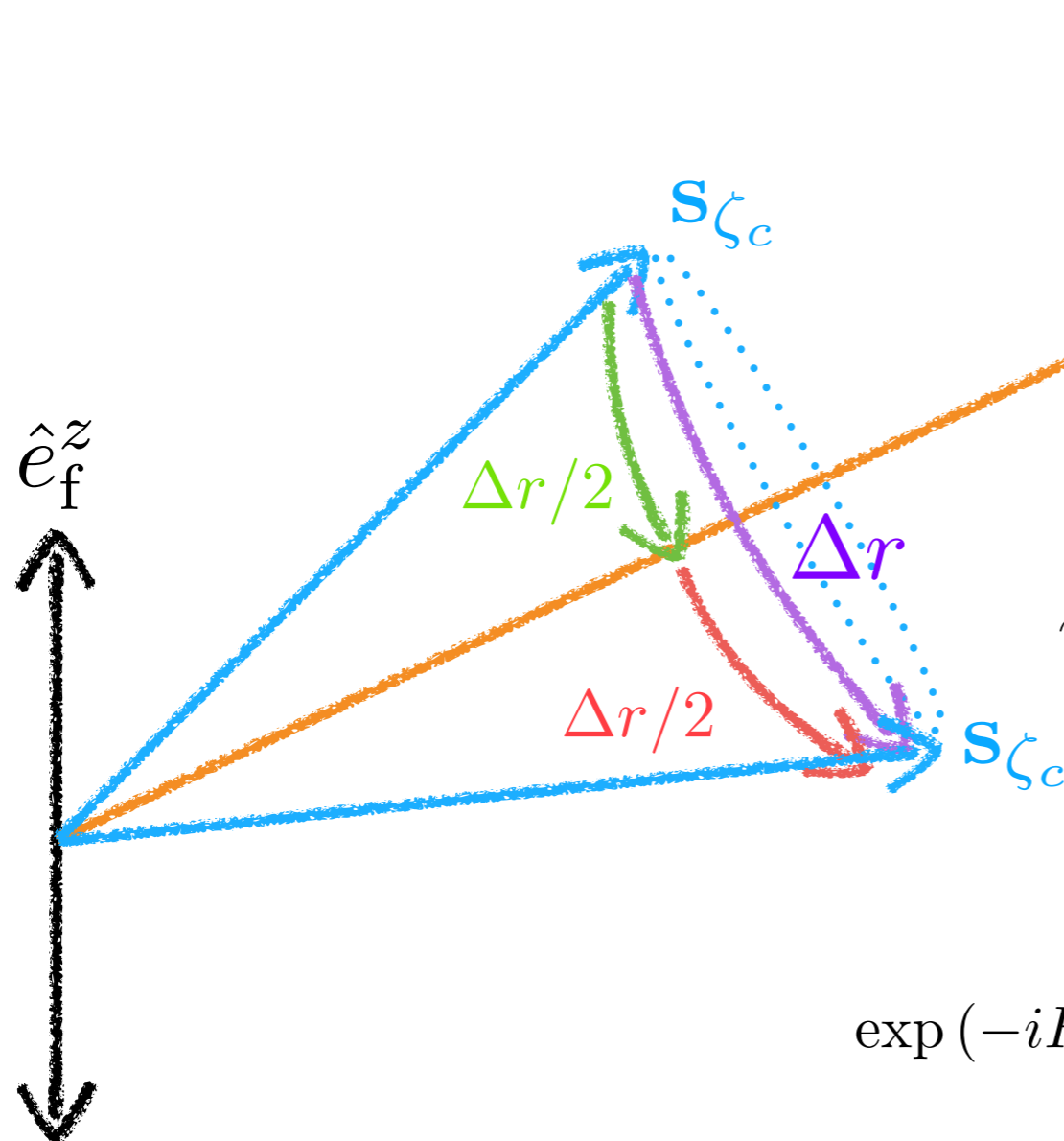
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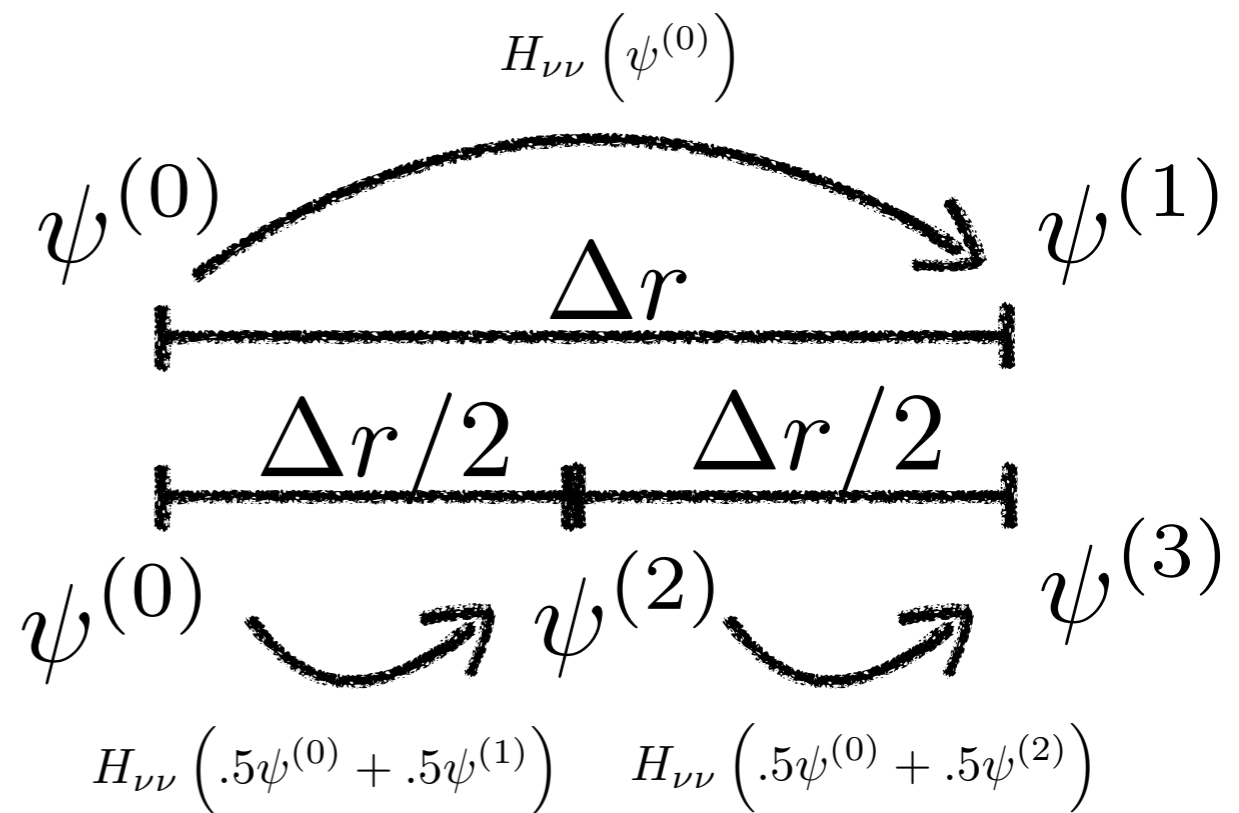
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Back to our Original Idea

- Basic Leapfrog algorithm:
- Rotating about local basis.



$$\sum_b H_{ab} V_{bc} = \zeta_c V_{ac}, \quad a, b, c = 1, 2, 3$$

- An improvement for tracking complex phases

$$Err = Re \left(\psi^{(1)} - \psi^{(3)} \right)^2 + Im \left(\psi^{(1)} - \psi^{(3)} \right)^2 \sim \frac{\Delta r}{2\pi/\zeta_c} \text{ or } \frac{\Delta r}{\Delta V_{ac}} \sim 10^{-6}$$

typically $\Delta r \geq l_{osc} \implies \sim 10^6$ integration steps

Now there is a plan!

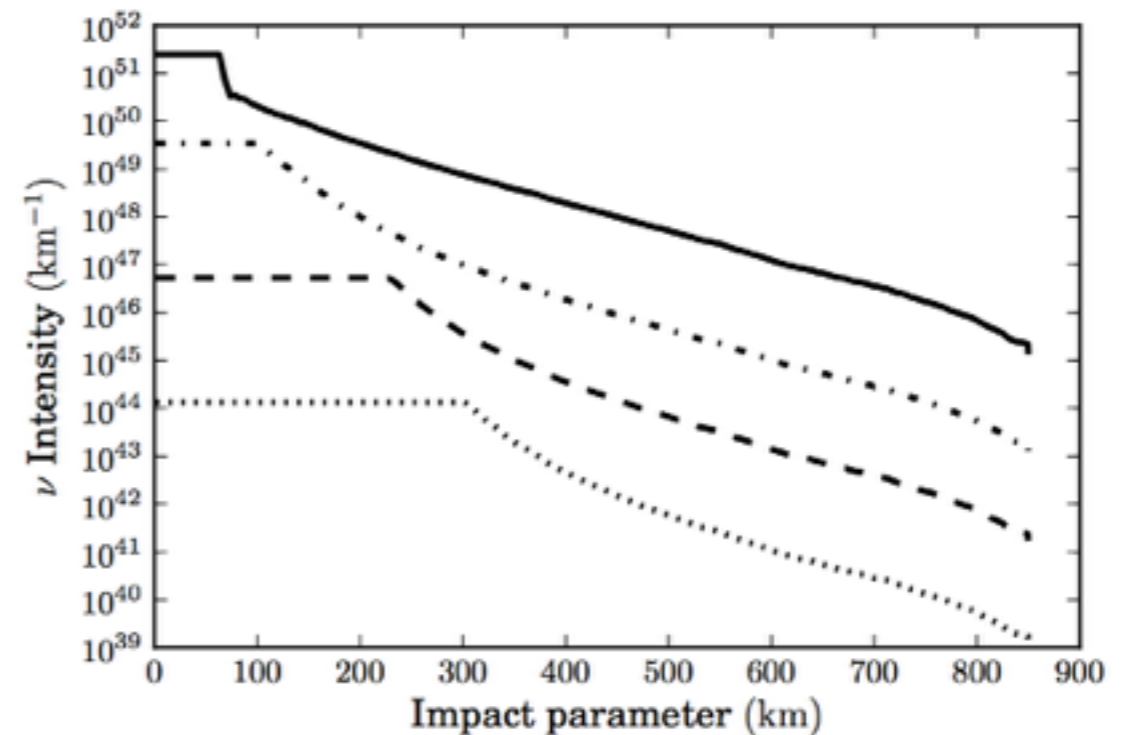
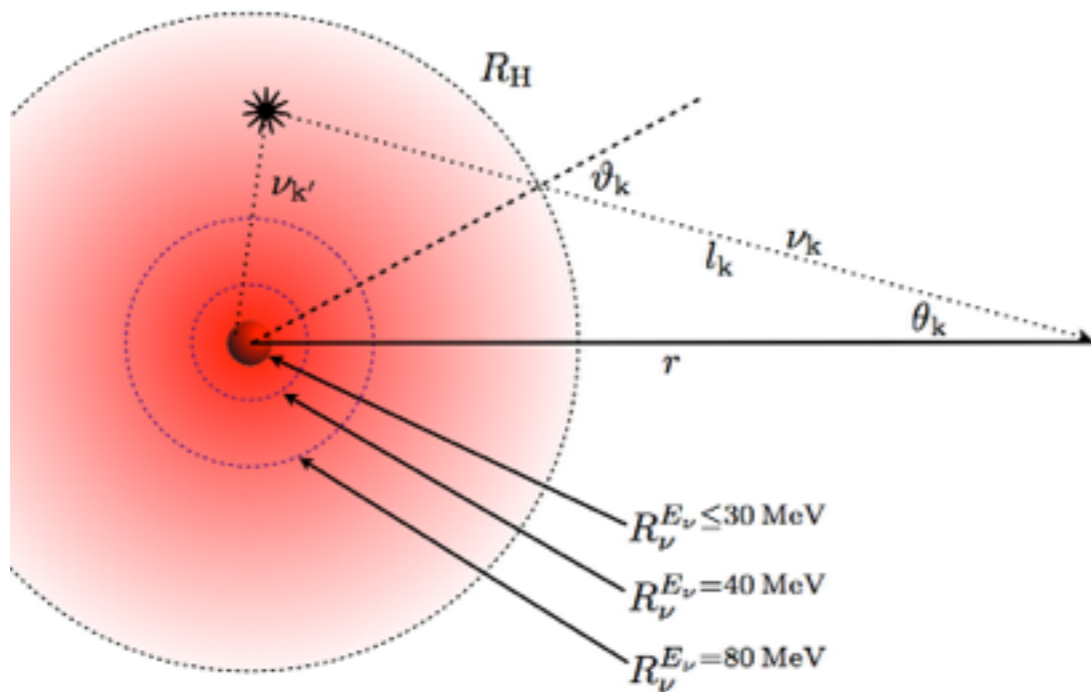
- Step 1: Exploit the symmetry of the problem. 6 Dimensions are reduced to 3.
- Step 2: Be efficient with your message passing and perform as much computation on local distributed processes (like a GPU) as you can get away with.
- Step 3: Think physically. If it looks like a duck, and quacks like a duck, it's probably a duck (to a reasonable approximation).

Not all simplicity is necessary

$$f_\nu(E_\nu, \vartheta_k) \equiv \frac{1}{F_2(\eta_\nu(\vartheta_k)) T_\nu^3(\vartheta_k)} \frac{E_\nu^2}{\exp(E_\nu/T_\nu(\vartheta_k) - \eta_\nu(\vartheta_k)) + 1}$$

$$dn_\nu(E_\nu, \vartheta_k) = \frac{2\pi j_\nu(E_\nu, \vartheta_k) \cos \vartheta_k d(\cos \vartheta_k) R_H^2}{r^2 \left(\sqrt{1 - (\sin \vartheta_k R_H/r)^2} - \cos \vartheta_k R_H/r \right)}$$

$$j_\nu(E_\nu, \vartheta_k) = \frac{L_\nu(\vartheta_k)}{4\pi^2 R_H^2 \langle E_\nu(\vartheta_k) \rangle} f_\nu(E_\nu, \vartheta_k)$$



Local memory usage is increased by 20 MB, or $\sim 5\%$